

AUTO-07P projects

The following three sample projects could be pursued by participants:

- Demo pp2: if you would like to use prepared AUTO files, try this demo to continue equilibria of the planar ODE, locate and continue saddle-node and Hopf bifurcations, and continue periodic orbits.
- Compute a circle using continuation: this problem allows you to implement an algebraic problem in AUTO.
- Compute and continue a pulse solution: this project is about the computation of travelling waves in AUTO via a boundary-value-problem formulation. Starting data come from an explicit solution.

Other sample project are listed on the following page.

Predator-prey model: Consider the predator-prey model

$$\dot{u} = bu(1 - u) - uv - a(1 - e^{-cu}), \quad \dot{v} = -v + duv$$

where $u, v \geq 0$ and $a, b, c, d > 0$. This system is used for the AUTO demo **pp2** for which details are given in the AUTO manual. The code is set up in the directory **auto-pp2-demo**: go to this directory and follow the commands outlined in the **README** file.

Compute a circle with AUTO: Trace out the circle $x^2 + y^2 = 1$ numerically with AUTO using continuation. The solution can be found in the directory **auto-circle**.

Pulses in a bistable partial differential equation: Consider the bistable PDE

$$u_t = u_{xx} - u + au^3, \quad x \in \mathbb{R},$$

which admits the standing pulse solution $u(x, t) = \sqrt{2}\operatorname{sech}(x)$ when $a = 1$. Compute and continue these pulses numerically in AUTO starting from the exact solution. Experiment with using different truncation intervals and different values of **NTST**. The solution can be found in the directory **auto-bistable**.

Other AUTO-07P projects

Computation of real eigenvalues: Take your favorite $n \times n$ matrix A and determine its real eigenvalues numerically with AUTO via continuation:

- AUTO: solve the algebraic system $(A - \lambda)v = 0$ for v by continuation in $\lambda \in \mathbb{R}$ with starting data $(v, \lambda) = 0$. Enable detection of branch points. What do you find?
 - Theory: investigate why this algorithm works.
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Hopf bifurcations and branch switching: Consider the Brusselator

$$\dot{u} = a - (b + 1)u + u^2v, \quad \dot{v} = bu - u^2v$$

where $u, v \geq 0$ and $a, b > 0$. This system has the unique equilibrium $(u, v) = (a, b/a)$.

- AUTO: continue the equilibrium numerically and investigate its Hopf bifurcations. Trace out the curve of Hopf bifurcations in (a, b) -space, and compute the periodic orbits that bifurcate from the equilibrium. Check `fort.9` to see whether the periodic orbits are stable or unstable.
 - Theory: compare the location of the Hopf bifurcation curve in (a, b) -space with the theoretical prediction.
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Pitchfork bifurcations and branch switching: Consider the second-order equation

$$\ddot{u} = \sin(u) \left[\cos(u) - \frac{1}{\gamma} \right]$$

that describes a bead that slides on a wire hoop. This system has the equilibrium $u = 0$ for all values of γ . Investigate its bifurcations numerically using AUTO: branch switch onto any bifurcating solutions by (i) using the branch switching algorithm built into AUTO and (ii) adding a symmetry-breaking term.

Fronts in the Nagumo equation: Consider the Nagumo PDE

$$u_t = u_{xx} + u(u - a)(1 - u), \quad x \in \mathbb{R},$$

which admits the travelling fronts $u(x, t) = 1 + \tanh((x + ct)/2)$ with $c = (1 - 2a)/\sqrt{2}$ for $0 < a < 1$. Compute and continue these fronts numerically in AUTO starting from the exact solution. Experiment with using different truncation intervals and different values of NTST.

Finite-difference approximations of PDEs: Consider the Nagumo PDE

$$u_t = u_{xx} - cu_x + u(u - a)(1 - u)$$

in a moving coordinate frame on a large interval $(-L, L)$ with Dirichlet boundary conditions at $x = \pm L$. Discretize this PDE in space using centered finite differences and implement the resulting large algebraic system in AUTO. Using appropriate values of L and the step size (you need to experiment), find the travelling waves $u(x) = 1 + \tanh(x/2)$ with $c = (1 - 2a)/\sqrt{2}$ in AUTO and determine the stability of the front by checking `fort.9`. Plot the solution profiles in MATLAB and compare them with the exact solution.
