

C. Nonlinear stability of KdV soliton

1. Last time -

Arnold's method on Arnold's problem

- Everything worked, easily
- Appropriate norm dictated by problem
- $\delta^2 K \geq 0$ at step 4 \Rightarrow Linear stability
(weird?)

2. Today - nonlinear stability of KdV soliton

- See Appendix of [A8] for very detailed analysis (& readable)
- Talk to R. Kollar for geometry of problem

1. Statement of problem

$$\underline{\text{KdV}} \quad \partial_\tau u + 6u \partial_\xi u + \partial_\xi^3 u = 0 \quad \begin{array}{l} -\infty < \xi < \infty \\ \tau > 0 \end{array}$$

u & all derivatives $\rightarrow 0$ as $|\xi| \rightarrow \infty$

Hamiltonian structure

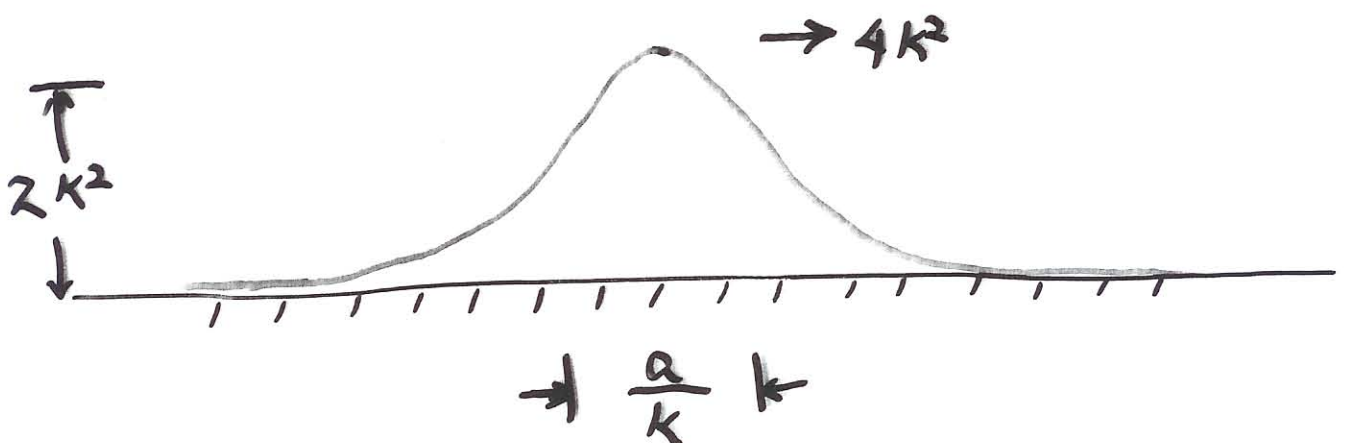
$$H = \int \left[\frac{1}{2} (\partial_\xi u)^2 - u^3 \right] d\xi$$

$$J = \partial_\xi$$

$$\text{KdV} \leftrightarrow \partial_\tau u = J \frac{\delta H}{\delta u}$$

Solitary wave solution (soliton)

$$u(\xi, \tau) = 2k^2 \operatorname{sech}^2(k(\xi - 4k^2\tau + \theta))$$



Q: Is this solution of KdV stable to small perturbations of initial data?

b) Comments & complications (many)

- 2 free constants: k, θ
 - k - "strength" of soliton
 - θ - phase constant

- orbital stability

$$\text{perturbation} = k + \delta k, \quad \delta k \ll k$$

\Rightarrow 2 waves diverge slowly

$$\Rightarrow \|G(\xi - 4k^2\tau) - u(\xi, \tau)\| \rightarrow 2\|G\|$$

$$\text{as } \tau \rightarrow \infty$$

~~unstable?~~

- "orbital stability" means:

$$\inf_y \|G(\xi - 4k^2\tau) - u(\xi + y, \tau)\|$$

(value judgement)

(causes problems later)

• constants of motion

$$I_1 = \int [u] d\xi \quad \text{Casimir}$$

$$I_2 = \int [u^2] d\xi \quad L_2 \text{ norm}$$

$$I_3 = -H = \int [u^3 - \frac{1}{2}(\partial_\xi u)^2] \quad \text{Hamiltonian}$$

⋮
more
⋮

• important constraint

$$\text{For a KdV soliton, } I_2 = \frac{16}{3} k^3$$

⇒ For every positive value of I_2 ,
there is a soliton with that value.

$$\text{Require } I_2(u) = I_2(G)$$

perturbed soliton
solution

Use constants of motion in 2 ways

- build Lyapunov functional

- constrain initial data

• A nonlinear constraint (Benjamin)

Let G represent solitary wave

$u = G + \delta u =$ perturbed solution

$$\int (G + \delta u)^2 d\xi = \int G^2 d\xi$$

$$\Rightarrow \boxed{2 \int [G \cdot \delta u] d\xi = - \int (\delta u)^2 d\xi}$$

- For linear theory

$$\delta u \ll G$$

$$\Rightarrow \int [G \cdot \delta u] d\xi \sim 0$$

perturbation orthogonal to
solitary wave

- For nonlinear theory

δu small, but finite

not orthogonal

$$\int [G \cdot \delta u] d\xi < 0$$

• Last consideration -

revise KdV equation (optional)

Define $x = \xi - 4k^2\tau$, $t = \tau$

$$\Rightarrow \partial_\xi = \partial_x, \quad \partial_\tau = \partial_t - 4k^2 \partial_x$$

$$u(\xi, \tau) = v(x, t)$$

Then

$$\text{KdV: } \partial_t v + 6v \partial_x v - 4k^2 \partial_x v + \partial_x^3 v = 0$$

solitary
wave:

$$G(x) = 2k^2 \operatorname{sech}^2(kx + \theta)$$

$G(x)$ satisfies:

$$\partial_x [\partial_x^2 G + 3G^2 - 4k^2 G] = 0$$

Hamiltonian:

$$\hat{H} = \int \left[\frac{1}{2} (\partial_x v)^2 - v^3 + 2k^2 v^2 \right] dx$$

$$J = \partial_x$$

$$I_1 = \int v dx, \quad I_2 = \int v^2 dx$$

Ready!

3. The Arnold machine, modified

Step 1: Hamiltonian eqn?

$$\text{Yes} \quad \partial_t v = J \frac{\delta \hat{H}}{\delta v} \leftrightarrow \text{KdV}$$

Step 2: Constants of motion

$$K(v) = \hat{H} + c_1 I_1 + c_2 I_2$$

$$= \int_{-\infty}^{\infty} \left[\frac{1}{2} (\partial_x v)^2 - v^3 + 2k^2 v^2 + c_1 v + c_2 v^2 \right] dx$$

Step 3: 1st variation

Require $\delta K|_{v=G} = 0$ (if possible)

$$K(G + \delta v) = K(G) + \delta K + \mathcal{O}(\delta v^2)$$

$$\delta K = \int [\delta v] [-\partial_x^2 G - 3G^2 + 4k^2 G + c_1 + 2c_2 G] dx$$

$$\Rightarrow c_1 = 0, \quad c_2 = 0,$$

$$-\partial_x^2 G - 3G^2 + 4k^2 G = 0$$

$$\text{so } K(v) = \int_{-\infty}^{\infty} \left[\frac{1}{2} (\partial_x v)^2 - v^3 + 2k^2 v^2 \right] dx$$

No free parameters in $K(v)$

Step 4: 2nd variation

$$K(G + \delta v) = K(G) + 0 + \delta^2 K - \int (\delta v)^3 dx,$$

$$\delta^2 K = \int_{-\infty}^{\infty} \left[\underbrace{\frac{1}{2} (\partial_x (\delta v))^2}_{\geq 0} - \underbrace{3G(\delta v)^2}_{\leq 0} + \underbrace{2k^2(\delta v)^2}_{\geq 0} \right] dx$$

????

Concerns: $\delta^2 K \geq 0$?

$$\int (\delta v)^3 dx \quad ?$$

Response: Control $\int (\delta v)^3 dx$ by choosing $\|\cdot\|$

Define 1st Sobolev norm for $v(x, \cdot)$ on \mathbb{R}

$$\|v\|_{(1)} := \left\{ \int_{-\infty}^{\infty} [v^2 + (\partial_x v)^2] dx \right\}^{\frac{1}{2}}$$

Why $\|\cdot\|_{(1)}$?

Consider $v(x)$, cont. diff. on \mathbb{R} ,
with $v(x) \rightarrow 0$ as $x \rightarrow -\infty$
& $v(x) \in H^1$

$$\int_{-\infty}^x 2v \frac{dv}{dy} dy = \int_{-\infty}^x 2v \frac{dv}{dy} dy$$

$$\begin{aligned} v^2(x) &\leq 2 \int_{-\infty}^x |v| \cdot \left| \frac{dv}{dy} \right| dy \\ &\leq 2 \int_{-\infty}^{\infty} |v| \cdot \left| \frac{dv}{dy} \right| dy \end{aligned}$$

$$\sup_x [v^2(x)] \leq \int_{-\infty}^{\infty} |v|^2 + \left| \frac{dv}{dy} \right|^2 dy$$

$$\Rightarrow \boxed{\|v\|_{\infty} \leq \|v\|_{(1)}}$$

$$\begin{aligned} \text{so } \left| -\int_{-\infty}^{\infty} (\delta v)^3 dx \right| &\leq \int_{-\infty}^{\infty} |\delta v|^3 dx \\ &\leq \sup_x |\delta v| \int_{-\infty}^{\infty} |\delta v|^2 dx \\ &\leq \|v\|_{(1)} \cdot \|v\|_{(1)}^2 = \|v\|_{(1)}^3 \end{aligned}$$

H^1 norm can control higher order term.

What about $\delta^2 K$?

$$\delta^2 K = \frac{1}{2} \int_{-\infty}^{\infty} [\partial_x(\delta v)^2 + (4k^2 - 6G)(\delta v)^2] dx$$

$\delta^2 K$ is a quadratic form on (δv)

Define L so $\delta^2 K = \frac{1}{2} \langle \delta v, L \delta v \rangle$

$$L = -\partial_x^2 + 4k^2 - 12k^2 \operatorname{sech}^2(kx + \theta)$$

L is self-adjoint. Find its spectrum

$$L f = \lambda f$$

$$\lambda_1 = -5k^2 \quad f_1(x) = \operatorname{sech}^3(kx + \theta)$$

$$\lambda_2 = 0 \quad f_2(x) = \operatorname{sech}^2(kx + \theta) \cdot \tanh(kx + \theta)$$

$$\lambda_3 = 3k^2 \quad f_3(x) = 4 \operatorname{sech}(kx + \theta) - 5 \operatorname{sech}^3(kx + \theta)$$

$$\lambda_4 = 4k^2 \quad f_4(x) = 2 \tanh(kx + \theta) - 5 \operatorname{sech}^2(kx + \theta) \tanh(kx + \theta)$$

λ_4 begins continuous spectrum



2 problems in spectrum

$$\lambda_1 = -5\kappa^2 < 0 \quad f_1 = \operatorname{sech}^3(\kappa x + \theta)$$

$$\lambda_2 = 0 \quad f_2 = c \partial_x G(x)$$

Result: Let $\delta v(x) \in H^1$, $\alpha, \gamma \in \mathbb{R}$

$$\text{If } \int \partial_x G(x) \cdot \delta v(x) dx = 0$$

$$\& \int G(x) \cdot \delta v(x) dx = -\frac{1}{2} \int (\delta v)^2 dx$$

Then there exist constants (c_1, c_2)

depending only on $G(x)$ so that

$$\delta^2 K = \frac{1}{2} \langle \delta v, L \delta v \rangle \geq c_1 \|\delta v\|_{L^2}^2 - c_2 (\|\delta v\|_{L^2}^3 + \|\delta v\|_{L^2}^4)$$

(see [AB], p 295 for calculation)

Good news:

By making δv small enough in $\|\cdot\|_{(1)}$,
we can make $\delta^2 K \geq c_3 \|\delta v\|_{(1)}$; $c_3 > 0$

This controls the cubic term in

$$K(G + \delta v) - K(G)$$

Bad news The "sliding norm" is not
yet a norm. More work is required
(see Appendix of [A8].)

More general picture ([C5], [C6], [A2])

Several problems of stability of
solitary wave G , with speed c , can

be stated as:

$H(u)$ = Hamiltonian of flow

$$I_2(u) = \frac{1}{2} \int u^2 dx$$

$$\text{set } d(c) = H|_G + c I_2|_G$$

$$d''(c) > 0 \Leftrightarrow \text{nonlinear stability}$$