#### Gene Golub SIAM Summer School 2012

Numerical Methods for Wave Propagation Finite Volume Methods Lecture 2

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#### This lecture

- Finite difference / finite volume methods
- Godunov's method
- High resolution methods (limiters)
- Two-dimensional methods
- Seismic example

#### Upwind method for advection

Scalar advection:

$$
q_t + uq_x = 0, \qquad u > 0
$$

As finite difference method:

$$
\left(\frac{Q_i^{n+1} - Q_i^n}{\Delta t}\right) + u\left(\frac{Q_i^n - Q_{i-1}^n}{\Delta x}\right) = 0
$$

Gives the explicit method:

$$
Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x} (Q_i^n - Q_{i-1}^n).
$$

Stable provided CFL condition satisfied:

$$
0 \le \frac{u\Delta t}{\Delta x} \le 1
$$

and first order accurate on smooth data.

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Domain of dependence: The solution  $q(X,T)$  depends on the data  $q(x, 0)$  over some set of x values,  $x \in \mathcal{D}(X, T)$ .

Advection:  $q(X,T) = q(X - uT, 0)$  and so  $\mathcal{D}(X,T) = \{X - uT\}.$ 

The CFL Condition: A numerical method can be convergent only if its numerical domain of dependence contains the true domain of dependence of the PDE, at least in the limit as  $\Delta t$ and  $\Delta x$  go to zero.

Note: Necessary but not sufficient for stability!

## Numerical domain of dependence

With a 3-point explicit method:



On a finer grid with  $\Delta t/\Delta x$  fixed:



For the method to be stable, the numerical domain of dependence must include the true domain of dependence.

For advection, the solution is constant along characteristics,

$$
q(x,t) = q(x - ut, 0)
$$

For a 3-point method, CFL condition requires  $\left|\frac{u\Delta t}{\Delta x}\right|\leq1.$ 

#### If this is violated:



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For a 3-point method, CFL condition requires  $\left|\frac{u\Delta t}{\Delta x}\right|\leq1.$ 

#### If this is violated:



# Stencil CFL Condition







 $0 \leq \frac{u\Delta t}{\Delta x}$  $\frac{x-2}{\Delta x} \leq 1$ 

$$
-1 \leq \frac{u\Delta t}{\Delta x} \leq 0
$$

$$
-1 \le \frac{u\Delta t}{\Delta x} \le 1
$$





#### Upwind method for advection

Scalar advection:

$$
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$$

As finite difference method:

$$
\left(\frac{Q_i^{n+1} - Q_i^n}{\Delta t}\right) + u\left(\frac{Q_i^n - Q_{i-1}^n}{\Delta x}\right) = 0
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Gives the explicit method:

$$
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$$

Stable provided CFL condition satisfied:

$$
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and first order accurate on smooth data.

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## Finite differences vs. finite volumes

#### Finite difference Methods

- Pointwise values  $Q_i^n \approx q(x_i, t_n)$
- Approximate derivatives by finite differences
- Assumes smoothness

#### Finite volume Methods

- Approximate cell averages:  $Q_i^n \approx$ 1  $\Delta x$  $\int^{x_{i+1/2}}$  $x_{i-1/2}$  $q(x, t_n) dx$
- Integral form of conservation law,

$$
\frac{\partial}{\partial t} \int_{x_{i-1/2}}^{x_{i+1/2}} q(x, t) dx = f(q(x_{i-1/2}, t)) - f(q(x_{i+1/2}, t))
$$

leads to conservation law  $q_t + f_x = 0$  but also directly to numerical method.

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#### Finite volume method

$$
Q_i^n \approx \frac{1}{h} \int_{x_{i-1/2}}^{x_{i+1/2}} q(x, t_n) \, dx
$$

Integral form:

$$
\frac{\partial}{\partial t} \int_{x_{i-1/2}}^{x_{i+1/2}} q(x, t) dx = f(q(x_{i-1/2}, t)) - f(q(x_{i+1/2}, t))
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#### Finite volume method

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$$

Integrate from  $t_n$  to  $t_{n+1} \implies$ 

$$
\int q(x, t_{n+1}) dx = \int q(x, t_n) dx + \int_{t_n}^{t_{n+1}} f(q(x_{i-1/2}, t)) - f(q(x_{i+1/2}, t)) dt
$$

#### Finite volume method

$$
Q_i^n \approx \frac{1}{h} \int_{x_{i-1/2}}^{x_{i+1/2}} q(x, t_n) \, dx
$$

Integral form:

$$
\frac{\partial}{\partial t} \int_{x_{i-1/2}}^{x_{i+1/2}} q(x, t) dx = f(q(x_{i-1/2}, t)) - f(q(x_{i+1/2}, t))
$$

Integrate from  $t_n$  to  $t_{n+1} \implies$ 

$$
\int q(x, t_{n+1}) dx = \int q(x, t_n) dx + \int_{t_n}^{t_{n+1}} f(q(x_{i-1/2}, t)) - f(q(x_{i+1/2}, t)) dt
$$

Numerical method:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (F_{i+1/2}^n - F_{i-1/2}^n)
$$

$$
\text{Numerical flux: } F_{i-1/2}^n \approx \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} f(q(x_{i-1/2}, t)) \, dt.
$$

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#### Upwind method for advection

Flux:  $f(q) = uq$ 

Numerical flux:  $F_{i-1/2}^n \approx$ 1  $\Delta t$  $\int^{t_{n+1}}$  $\int_{t_n} f(q(x_{i-1/2}, t)) dt.$ 

If  $q(x, t_n)$  is piecewise constant in each cell, then

$$
F_{i-1/2}^n = \begin{cases} uQ_{i-1}^n & \text{if } u > 0, \\ uQ_i^n & \text{if } u < 0. \end{cases}
$$

#### Upwind method for advection

Flux:  $f(q) = uq$ 

Numerical flux: 
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F_{i-1/2}^n \approx \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} f(q(x_{i-1/2}, t)) dt
$$
.

If  $q(x, t_n)$  is piecewise constant in each cell, then

$$
F_{i-1/2}^n = \begin{cases} uQ_{i-1}^n & \text{if } u > 0, \\ uQ_i^n & \text{if } u < 0. \end{cases}
$$

This gives the upwind method:

$$
\begin{aligned} Q_i^{n+1} &= Q_i^n - \frac{u\Delta t}{\Delta x}(Q_i^n - Q_{i-1}^n) & \text{if } u > 0\\ Q_i^{n+1} &= Q_i^n - \frac{u\Delta t}{\Delta x}(Q_{i+1}^n - Q_i^n) & \text{if } u < 0 \end{aligned}
$$

## Upwind for advection as a finite volume method

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (F_{i+1/2}^n - F_{i-1/2}^n)
$$

Advection equation:  $f(q) = uq$ 

$$
F_{i-1/2} \approx \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} uq(x_{i-1/2}, t) dt.
$$

First order upwind:

$$
F_{i-1/2} = u^+ Q_{i-1}^n + u^- Q_i^n
$$
  

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (u^+(Q_i^n - Q_{i-1}^n) + u^-(Q_{i+1}^n - Q_i^n)).
$$

where  $u^+ = \max(u, 0), u^- = \min(u, 0).$ 

Consider  $q_t + A q_x = 0$ . Eigenvalues are wave speeds.

Upwind method if all  $\lambda^p > 0$ :

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (AQ_i^n - AQ_{i-1}^n)
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Upwind method if all  $\lambda^p < 0$ :

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Upwind method if all  $\lambda^p < 0$ :

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What if some eigenvalues of each sign?

Consider  $q_t + A q_x = 0$ . Eigenvalues are wave speeds.

Upwind method if all  $\lambda^p > 0$ :

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Upwind method if all  $\lambda^p < 0$ :

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Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (AQ_{i+1}^n - AQ_i^n)
$$

What if some eigenvalues of each sign?

Diagonalize and apply scalar upwind to each wave family. Easier ways to accomplish this!

#### Lax-Wendroff method

Second-order accuracy?

Taylor series:

$$
q(x, t + \Delta t) = q(x, t) + \Delta t q_t(x, t) + \frac{1}{2} \Delta t^2 q_{tt}(x, t) + \cdots
$$

From  $q_t = -Aq_x$  we find  $q_{tt} = A^2 q_{xx}$ .

$$
q(x,t+\Delta t) = q(x,t) - \Delta t A q_x(x,t) + \frac{1}{2} \Delta t^2 A^2 q_{xx}(x,t) + \cdots
$$

Replace  $q_x$  and  $q_{xx}$  by centered differences:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{2\Delta x} A(Q_{i+1}^n - Q_{i-1}^n) + \frac{1}{2} \frac{\Delta t^2}{\Delta x^2} A^2 (Q_{i-1}^n - 2Q_i^n + Q_{i+1}^n)
$$

Second order of smooth solutions but very dispersive!

Discontinuities or steep gradients  $\implies$  nonphysical oscillations.

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#### Some examples solving the advection equation with periodic boundary conditions

Using Clawpack and various numerical methods...

**[www.clawpack.org/g2s3/claw-apps/advection-1d-](http://www.clawpack.org/g2s3/claw-apps/advection-1d-3/README.html)[3/README.html](http://www.clawpack.org/g2s3/claw-apps/advection-1d-3/README.html)**



1. Solve Riemann problems at all interfaces, yielding waves  $\mathcal{W}_{i-1/2}^p$  and speeds  $s_i^p$  $_{i-1/2}^p$ , for  $p=1, 2, ..., m$ .

Riemann problem: Original equation with piecewise constant data.



#### Then either:

1. Compute new cell averages by integrating over cell at  $t_{n+1}$ ,



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- 1. Compute new cell averages by integrating over cell at  $t_{n+1}$ ,
- 2. Compute fluxes at interfaces and flux-difference:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} [F_{i+1/2}^n - F_{i-1/2}^n]
$$



#### Then either:

- 1. Compute new cell averages by integrating over cell at  $t_{n+1}$ ,
- 2. Compute fluxes at interfaces and flux-difference:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} [F_{i+1/2}^n - F_{i-1/2}^n]
$$

3. Update cell averages by contributions from all waves entering cell:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} [\mathcal{A}^+ \Delta Q_{i-1/2} + \mathcal{A}^- \Delta Q_{i+1/2}]
$$
  
where  $\mathcal{A}^{\pm} \Delta Q_{i-1/2} = \sum_{i=1}^m (s_{i-1/2}^p)^{\pm} \mathcal{W}_{i-1/2}^p$ .

#### Godunov's method with flux differencing

 $Q_{i}^{n}$  defines a piecewise constant function

$$
\tilde{q}^n(x,t_n) = Q_i^n \ \ \text{for} \ x_{i-1/2} < x < x_{i+1/2}
$$

Discontinuities at cell interfaces  $\implies$  Riemann problems.



$$
\tilde{q}^n(x_{i-1/2}, t) \equiv q^{\psi}(Q_{i-1}, Q_i) \quad \text{for } t > t_n.
$$
  

$$
F_{i-1/2}^n = \frac{1}{\Delta t} \int_{t_n}^{t_{n+1}} f(q^{\psi}(Q_{i-1}^n, Q_i^n)) dt = f(q^{\psi}(Q_{i-1}^n, Q_i^n)).
$$

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#### Wave-propagation viewpoint

For linear system  $q_t + Aq_x = 0$ , the Riemann solution consists of

waves  $\mathcal{W}^p$  propagating at constant speed  $\lambda^p$ .  $\lambda^2 \Delta t$  ${\cal W}_{i-1/2}^1$  |  ${\cal W}_{i+1/2}^1$  $\mathcal{W}_{i-1/2}^2$  $\mathcal{W}_{i-1/2}^3$  $Q_i - Q_{i-1} = \sum^{m}$  $_{p=1}$  $\alpha_i^p$  $\sum_{i=1/2}^p r^p \equiv \sum_{i=1}^m$  $p=1$  $\mathcal{W}_{i-1/2}^p$ .  $Q_i^{n+1} = Q_i^n \Delta t$  $\Delta x$  $\left[\lambda^2 \mathcal{W}_{i-1/2}^2 + \lambda^3 \mathcal{W}_{i-1/2}^3 + \lambda^1 \mathcal{W}_{i+1/2}^1\right].$  **D** Reconstruct a piecewise constant function  $\tilde{q}^n(x,t_n)$ defined for all  $x$ , from the cell averages  $Q_i^n.$ 

$$
\tilde{q}^n(x,t_n) = Q_i^n \quad \text{for all } x \in \mathcal{C}_i.
$$

- 2 Evolve the hyperbolic equation exactly (or approximately) with this initial data to obtain  $\tilde{q}^n(x,t_{n+1})$  a time  $\Delta t$  later.
- **3** Average this function over each grid cell to obtain new cell averages

$$
Q_i^{n+1} = \frac{1}{\Delta x} \int_{\mathcal{C}_i} \tilde{q}^n(x, t_{n+1}) dx.
$$

#### Godunov's method for advection

 $Q_{i}^{n}$  defines a piecewise constant function

$$
\tilde{q}^n(x,t_n) = Q_i^n \ \ \text{for} \ x_{i-1/2} < x < x_{i+1/2}
$$

Discontinuities at cell interfaces  $\implies$  Riemann problems.<br> $u > 0$ 



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Cell averages and piecewise constant reconstruction:









The cell average is modified by

$$
\frac{u\Delta t \cdot (Q_{i-1}^n - Q_i^n)}{\Delta x}
$$

So we obtain the upwind method

$$
Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x} (Q_i^n - Q_{i-1}^n).
$$

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For linear system  $q_t + Aq_x = 0$ , the Riemann solution consists of

waves  $\mathcal{W}^p$  propagating at constant speed  $\lambda^p$ .  $\lambda^2 \Delta t$  ${\cal W}_{i-1/2}^1$  |  ${\cal W}_{i+1/2}^1$  $\mathcal{W}_{i-1/2}^2$  $\mathcal{W}_{i-1/2}^3$  $Q_i - Q_{i-1} = \sum^{m}$  $_{p=1}$  $\alpha_i^p$  $\sum_{i=1/2}^p r^p \equiv \sum_{i=1}^m$  $p=1$  $\mathcal{W}_{i-1/2}^p$ .  $Q_i^{n+1} = Q_i^n \Delta t$  $\Delta x$  $\left[\lambda^2 \mathcal{W}_{i-1/2}^2 + \lambda^3 \mathcal{W}_{i-1/2}^3 + \lambda^1 \mathcal{W}_{i+1/2}^1\right].$ 

## Upwind wave-propagation algorithm

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} \left[ \sum_{p=1}^m (\lambda^p)^+ \mathcal{W}_{i-1/2}^p + \sum_{p=1}^m (\lambda^p)^- \mathcal{W}_{i+1/2}^p \right]
$$

or

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} \left[ \mathcal{A}^+ \Delta Q_{i-1/2} + \mathcal{A}^- \Delta Q_{i+1/2} \right].
$$

where the fluctuations are defined by

$$
\begin{aligned} \mathcal{A}^- \Delta Q_{i-1/2} &= \sum_{p=1}^m (\lambda^p)^- \mathcal{W}_{i-1/2}^p, \quad \text{left-going} \\ \mathcal{A}^+ \Delta Q_{i-1/2} &= \sum_{p=1}^m (\lambda^p)^+ \mathcal{W}_{i-1/2}^p, \quad \text{right-going} \end{aligned}
$$
# Upwind wave-propagation algorithm

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} \left[ \sum_{p=1}^m (s_{i-1/2}^p)^+ \mathcal{W}_{i-1/2}^p + \sum_{p=1}^m (s_{i+1/2}^p)^- \mathcal{W}_{i+1/2}^p \right]
$$

where

$$
s^+ = \max(s, 0),
$$
  $s^- = \min(s, 0).$ 

Note: Requires only waves and speeds.

Applicable also to hyperbolic problems not in conservation form.

For  $q_t + f(q)_x = 0$ , conservative if waves chosen properly, e.g. using Roe-average of Jacobians.

Great for general software, but only first-order accurate (upwind method for linear systems).

**D** Reconstruct a piecewise linear function  $\tilde{q}^n(x,t_n)$  defined for all  $x$ , from the cell averages  $Q_i^n$ .

$$
\tilde{q}^n(x,t_n) = Q_i^n + \sigma_i^n(x-x_i) \quad \text{for all } x \in \mathcal{C}_i.
$$

- 2 Evolve the hyperbolic equation exactly (or approximately) with this initial data to obtain  $\tilde{q}^n(x,t_{n+1})$  a time  $\Delta t$  later.
- **3** Average this function over each grid cell to obtain new cell averages

$$
Q_i^{n+1} = \frac{1}{\Delta x} \int_{\mathcal{C}_i} \tilde{q}^n(x, t_{n+1}) dx.
$$

Cell averages and piecewise linear reconstruction:



$$
\tilde{Q}^n(x, t_n) = Q_i^n + \sigma_i^n(x - x_i) \qquad \text{for } x_{i-1/2} \le x < x_{i+1/2}.
$$

Applying REA algorithm gives:

$$
Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x}(Q_i^n - Q_{i-1}^n) - \frac{1}{2}\frac{u\Delta t}{\Delta x}(\Delta x - \bar{u}\Delta t)(\sigma_i^n - \sigma_{i-1}^n)
$$

Choice of slopes:

Centered slope: 
$$
\sigma_i^n = \frac{Q_{i+1}^n - Q_{i-1}^n}{2\Delta x}
$$
 (From m)

\nUpwind slope: 
$$
\sigma_i^n = \frac{Q_i^n - Q_{i-1}^n}{\Delta x}
$$
 (Beam-Warming)

\nDownwind slope: 
$$
\sigma_i^n = \frac{Q_{i+1}^n - Q_i^n}{\Delta x}
$$
 (Lax-Wendroff)

Any of these slope choices will give oscillations near discontinuities.





Want to use slope where solution is smooth for "second-order" accuracy.

Where solution is not smooth, adding slope corrections gives oscillations.

Limit the slope based on the behavior of the solution.

$$
\sigma_i^n = \left( \frac{Q_{i+1}^n - Q_i^n}{\Delta x} \right) \Phi_i^n.
$$

 $\Phi = 1 \implies$  Lax-Wendroff,

 $\Phi = 0 \implies$  upwind.

$$
\text{minmod}(a, b) = \begin{cases} a & \text{if } |a| < |b| \text{ and } ab > 0 \\ b & \text{if } |b| < |a| \text{ and } ab > 0 \\ 0 & \text{if } ab \le 0 \end{cases}
$$

Slope:

$$
\begin{array}{lcl} \sigma_i^n & = & \displaystyle \operatorname{minmod}((Q_i^n-Q_{i-1}^n)/\Delta x, \ \ (Q_{i+1}^n-Q_i^n)/\Delta x) \\ \\ & = & \displaystyle \left(\frac{Q_{i+1}^n-Q_i^n}{\Delta x}\right)\Phi(\theta_i^n) \end{array}
$$

where

$$
\begin{array}{rcl} \theta_i^n & = & \displaystyle \frac{Q_i^n - Q_{i-1}^n}{Q_{i+1}^n - Q_i^n} \\ \Phi(\theta) & = & \displaystyle \text{minmod}(\theta, 1) \end{array}
$$

Lax-Wendroff reconstruction:



Minmod reconstruction:



# Some popular limiters

Linear methods:

upwind :  $\phi(\theta) = 0$ Lax-Wendroff :  $\phi(\theta) = 1$ Beam-Warming :  $\phi(\theta) = \theta$ Fromm :  $\phi(\theta) = \frac{1}{2}(1+\theta)$ 

High-resolution limiters:

minmod: 
$$
\phi(\theta) = \text{minmod}(1, \theta)
$$
  
superbee:  $\phi(\theta) = \max(0, \min(1, 2\theta), \min(2, \theta))$   
MC:  $\phi(\theta) = \max(0, \min((1 + \theta)/2, 2, 2\theta))$   
van Lee:  $\phi(\theta) = \frac{\theta + |\theta|}{1 + |\theta|}$ 

# Slope limiters and flux limiters

#### Slope limiter formulation for advection:

$$
\tilde{Q}^n(x, t_n) = Q_i^n + \sigma_i^n(x - x_i) \qquad \text{for } x_{i-1/2} \le x < x_{i+1/2}.
$$

Applying REA algorithm gives:

$$
Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x}(Q_i^n - Q_{i-1}^n) - \frac{1}{2}\frac{u\Delta t}{\Delta x}(\Delta x - \bar{u}\Delta t)(\sigma_i^n - \sigma_{i-1}^n)
$$

Flux limiter formulation:

$$
Q_i^{n+1} = Q_i^n - \frac{\Delta t}{\Delta x} (F_{i+1/2}^n - F_{i-1/2}^n)
$$

with flux

$$
F_{i-1/2}^n = uQ_{i-1}^n + \frac{1}{2}u(\Delta x - u\Delta t)\sigma_{i-1}^n.
$$

# Wave limiters

Let 
$$
W_{i-1/2} = Q_i^n - Q_{i-1}^n
$$
.  
Upwind:  $Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x} W_{i-1/2}$ .

Lax-Wendroff:

$$
Q_i^{n+1} = Q_i^n - \frac{u\Delta t}{\Delta x} \mathcal{W}_{i-1/2} - \frac{\Delta t}{\Delta x} (\tilde{F}_{i+1/2} - \tilde{F}_{i-1/2})
$$

$$
\tilde{F}_{i-1/2} = \frac{1}{2} \left( 1 - \left| \frac{u\Delta t}{\Delta x} \right| \right) |u| \mathcal{W}_{i-1/2}
$$

High-resolution method:

$$
\tilde{F}_{i-1/2} = \frac{1}{2} \left( 1 - \left| \frac{u\Delta t}{\Delta x} \right| \right) |u|\widetilde{\mathcal{W}}_{i-1/2}
$$

where  $\mathcal{W}_{i-1/2} = \Phi_{i-1/2} \mathcal{W}_{i-1/2}$ .

Evolution of total mass due to fluxes through cell edges:

$$
\frac{d}{dt} \iint_{\mathcal{C}_{ij}} q(x, y, t) dx dy = \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i+1/2}, y, t) dy \n- \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i-1/2}, y, t) dy \n+ \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j+1/2}, t) dx \n- \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j-1/2}, t) dx.
$$

Evolution of total mass due to fluxes through cell edges:

$$
\frac{d}{dt} \iint_{\mathcal{C}_{ij}} q(x, y, t) dx dy = \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i+1/2}, y, t) dy \n- \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i-1/2}, y, t) dy \n+ \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j+1/2}, t) dx \n- \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j-1/2}, t) dx.
$$

#### Suggests:

$$
\frac{\Delta x \Delta y Q_{ij}^{n+1} - \Delta x \Delta y Q_{ij}^n}{\Delta t} = -\Delta y [F_{i+1/2,j}^n - F_{i-1/2,j}^n]
$$

$$
-\Delta x [G_{i,j+1/2}^n - G_{i,j-1/2}^n],
$$

$$
\Delta x \Delta y Q_{ij}^{n+1} = \Delta x \Delta y Q_{ij}^{n} - \Delta t \Delta y [F_{i+1/2,j}^{n} - F_{i-1/2,j}^{n}] - \Delta t \Delta x [G_{i,j+1/2}^{n} - G_{i,j-1/2}^{n}],
$$

Where we define numerical fluxes:

$$
F_{i-1/2,j}^n \approx \frac{1}{\Delta t \Delta y} \int_{t_n}^{t_{n+1}} \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i-1/2}, y, t)) dy dt,
$$
  

$$
G_{i,j-1/2}^n \approx \frac{1}{\Delta t \Delta x} \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j-1/2}, t)) dx dt.
$$

$$
\Delta x \Delta y Q_{ij}^{n+1} = \Delta x \Delta y Q_{ij}^{n} - \Delta t \Delta y [F_{i+1/2,j}^{n} - F_{i-1/2,j}^{n}] - \Delta t \Delta x [G_{i,j+1/2}^{n} - G_{i,j-1/2}^{n}],
$$

Where we define numerical fluxes:

$$
F_{i-1/2,j}^n \approx \frac{1}{\Delta t \Delta y} \int_{t_n}^{t_{n+1}} \int_{y_{j-1/2}}^{y_{j+1/2}} f(q(x_{i-1/2}, y, t)) dy dt,
$$
  

$$
G_{i,j-1/2}^n \approx \frac{1}{\Delta t \Delta x} \int_{t_n}^{t_{n+1}} \int_{x_{i-1/2}}^{x_{i+1/2}} g(q(x, y_{j-1/2}, t)) dx dt.
$$

Rewrite by dividing by  $\Delta x \Delta y$ :

$$
Q_{ij}^{n+1} = Q_{ij}^n - \frac{\Delta t}{\Delta x} [F_{i+1/2,j}^n - F_{i-1/2,j}^n]
$$

$$
- \frac{\Delta t}{\Delta y} [G_{i,j+1/2}^n - G_{i,j-1/2}^n].
$$

# 2d finite volume method

$$
Q_{ij}^{n+1} = Q_{ij}^n - \frac{\Delta t}{\Delta x} [F_{i+1/2,j}^n - F_{i-1/2,j}^n]
$$

$$
- \frac{\Delta t}{\Delta y} [G_{i,j+1/2}^n - G_{i,j-1/2}^n].
$$

#### Fluctuation form:

$$
Q_{ij}^{n+1} = Q_{ij} - \frac{\Delta t}{\Delta x} (\mathcal{A}^+ \Delta Q_{i-1/2,j} + \mathcal{A}^- \Delta Q_{i+1/2,j})
$$
  
- 
$$
\frac{\Delta t}{\Delta y} (\mathcal{B}^+ \Delta Q_{i,j-1/2} + \mathcal{B}^- \Delta Q_{i,j+1/2})
$$
  
- 
$$
\frac{\Delta t}{\Delta x} (\tilde{F}_{i+1/2,j} - \tilde{F}_{i-1/2,j}) - \frac{\Delta t}{\Delta y} (\tilde{G}_{i,j+1/2} - \tilde{G}_{i,j-1/2}).
$$

The  $\tilde{F}$  and  $\tilde{G}$  are correction fluxes to go beyond Godunov's upwind method.

Incorporate approximations to second derivative terms in each direction ( $q_{xx}$  and  $q_{yy}$ ) and mixed term  $q_{xy}$ .

## Advection: Donor Cell Upwind

With no correction fluxes, Godunov's method for advection is Donor Cell Upwind:

$$
Q_{ij}^{n+1} = Q_{ij} - \frac{\Delta t}{\Delta x} [u^+(Q_{ij} - Q_{i-1,j}) + u^-(Q_{i+1,j} - Q_{ij})]
$$

$$
- \frac{\Delta t}{\Delta y} [v^+(Q_{ij} - Q_{i,j-1}) + v^-(Q_{i,j+1} - Q_{ij})].
$$



Stable only if  $\left|\frac{u\Delta t}{\Delta x}\right| + \left|$  $\underline{v\Delta t}$  $\Delta y$  $\Big|\leq 1.$  Correction fluxes can be added to advect waves correctly.

#### Corner Transport Upwind:



# Advection: Corner Transport Upwind (CTU)

Need to transport triangular region from cell  $(i, j)$  to  $(i, j + 1)$ :

Area 
$$
=\frac{1}{2}(u\Delta t)(v\Delta t) \Longrightarrow \left(\frac{\frac{1}{2}uv(\Delta t)^2}{\Delta x \Delta y}\right)(Q_{ij} - Q_{i-1,j}).
$$

Accomplished by correction flux:



# Wave propagation algorithm for  $q_t + Aq_x + Bq_y = 0$

Decompose 
$$
A = A^{+} + A^{-}
$$
 and  $B = B^{+} + B^{-}$ .



# Wave propagation algorithm for  $q_t + Aq_x + Bq_y = 0$

Decompose 
$$
A = A^{+} + A^{-}
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 and  $B = B^{+} + B^{-}$ .



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## Wave propagation algorithm for  $q_t + A q_x + B q_y = 0$

Decompose  $A = A^{+} + A^{-}$  and  $B = B^{+} + B^{-}$ .



# Equations of linear elasticity

$$
\sigma_t^{11} - (\lambda + 2\mu)u_x - \lambda v_y = 0
$$
  
\n
$$
\sigma_t^{22} - \lambda u_x - (\lambda + 2\mu)v_y = 0
$$
  
\n
$$
\sigma_t^{12} - \mu(v_x + u_y) = 0
$$
  
\n
$$
\rho u_t - \sigma_x^{11} - \sigma_y^{12} = 0
$$
  
\n
$$
\rho v_t - \sigma_x^{12} - \sigma_y^{22} = 0
$$
  
\n
$$
\sigma_t^{12} - \sigma_y^{22} = 0
$$
  
\n
$$
\sigma_t^{12} - \sigma_y^{22} = 0
$$
  
\n
$$
\sigma_t^{12} - \sigma_y^{22} = 0
$$

where  $\lambda(x, y)$  and  $\mu(x, y)$  are Lamé parameters.

This has the form  $q_t + Aq_x + Bq_y = 0$ .

The matrix  $(A \cos \theta + B \sin \theta)$  has eigenvalues  $-c_p$ ,  $-c_s$ , 0,  $c_s$ ,  $c_p$ where the P-wave speed and S-wave speed are  $c_p = \sqrt{\frac{\lambda+2\mu}{\rho}}$ ,  $c_s = \sqrt{\frac{\mu}{\rho}}$ 







# Seismic waves in layered earth



Layers 1 and 3:  $\rho = 2$ ,  $\lambda = 1$ ,  $\mu = 1$ ,  $c_n \approx 1.2$ ,  $c_s \approx 0.7$ Layer 2:  $\rho = 5, \lambda = 10, \mu = 5, c_n = 2.0, c_s = 1$ Impulse at top surface at  $t = 0$ .

Solved on uniform Cartesian grid (600  $\times$  300).

Cell average of material parameters used in each finite volume cell.

Extrapolation at computational boundaries.

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



R.J. LeVeque, University of Washington [Gene Golub SIAM Summer School 2012](#page-0-0)

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.20

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.30

#### R.J. LeVeque, University of Washington [Gene Golub SIAM Summer School 2012](#page-0-0)

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.40

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.50

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.60

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.70

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 0.80

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]




### Seismic wave in layered medium

 $Red = div(u)$  [P-waves], Blue = curl(u) [S-waves]



Div (red) and Curl (blue) at t = 1.00







Div (red) and Curl (blue) at  $t = 0.40$ 



# You might want to work through the following slides on your own!

Total variation:

$$
TV(Q) = \sum_{i} |Q_i - Q_{i-1}|
$$

For a function,  $TV(q) = \int |q_x(x)| dx$ .

A method is Total Variation Diminishing (TVD) if

$$
TV(Q^{n+1}) \leq TV(Q^n).
$$

If  $Q^n$  is monotone, then so is  $Q^{n+1}.$ 

No spurious oscillations generated.

Gives a form of stability useful for proving convergence, also for nonlinear scalar conservation laws.

# TVD REA Algorithm

**D** Reconstruct a piecewise linear function  $\tilde{q}^n(x,t_n)$  defined for all  $x$ , from the cell averages  $Q_i^n$ .

$$
\tilde{q}^n(x, t_n) = Q_i^n + \sigma_i^n(x - x_i) \quad \text{for all } x \in \mathcal{C}_i
$$

with the property that  $TV(\tilde{q}^n) \leq TV(Q^n)$ .

- **2** Evolve the hyperbolic equation exactly (or approximately) with this initial data to obtain  $\tilde{q}^n(x,t_{n+1})$  a time  $k$  later.
- **3** Average this function over each grid cell to obtain new cell averages

$$
Q_i^{n+1} = \frac{1}{\Delta x} \int_{\mathcal{C}_i} \tilde{q}^n(x, t_{n+1}) dx.
$$

Note: Steps 2 and 3 are always TVD.



Data at time  $t_n: \ \tilde{q}^n(x,t_n) = Q_i^n$  for  $x_{i-1/2} < x < x_{i+1/2}$ Solving Riemann problems for small  $\Delta t$  gives solution:

$$
\tilde{q}^n(x, t_{n+1}) = \begin{cases}\nQ_{i-1/2}^* & \text{if } x_{i-1/2} - c\Delta t < x < x_{i-1/2} + c\Delta t, \\
Q_i^n & \text{if } x_{i-1/2} + c\Delta t < x < x_{i+1/2} - c\Delta t, \\
Q_{i+1/2}^* & \text{if } x_{i+1/2} - c\Delta t < x < x_{i+1/2} + c\Delta t,\n\end{cases}
$$



Data at time  $t_n: \ \tilde{q}^n(x,t_n) = Q_i^n$  for  $x_{i-1/2} < x < x_{i+1/2}$ Solving Riemann problems for small  $\Delta t$  gives solution:

$$
\tilde{q}^n(x, t_{n+1}) = \begin{cases}\nQ_{i-1/2}^* & \text{if } x_{i-1/2} - c\Delta t < x < x_{i-1/2} + c\Delta t, \\
Q_i^n & \text{if } x_{i-1/2} + c\Delta t < x < x_{i+1/2} - c\Delta t, \\
Q_{i+1/2}^* & \text{if } x_{i+1/2} - c\Delta t < x < x_{i+1/2} + c\Delta t,\n\end{cases}
$$

So computing cell average gives:

$$
Q_i^{n+1} = \frac{1}{\Delta x} \left[ c \Delta t Q_{i-1/2}^* + (\Delta x - 2c \Delta t) Q_i^n + c \Delta t Q_{i+1/2}^* \right].
$$

$$
Q_i^{n+1} = \frac{1}{\Delta x} \left[ c \Delta t Q_{i-1/2}^* + (\Delta x - 2c \Delta t) Q_i^n + c \Delta t Q_{i+1/2}^* \right].
$$

Solve Riemann problems:

$$
Q_i^n - Q_{i-1}^n = \Delta Q_{i-1/2} = \mathcal{W}_{i-1/2}^1 + \mathcal{W}_{i-1/2}^2 = \alpha_{i-1/2}^1 r^1 + \alpha_{i-1/2}^2 r^2,
$$
  
\n
$$
Q_{i+1}^n - Q_i^n = \Delta Q_{i+1/2} = \mathcal{W}_{i+1/2}^1 + \mathcal{W}_{i+1/2}^2 = \alpha_{i+1/2}^1 r^1 + \alpha_{i+1/2}^2 r^2,
$$

$$
Q_i^{n+1} = \frac{1}{\Delta x} \left[ c \Delta t Q_{i-1/2}^* + (\Delta x - 2c \Delta t) Q_i^n + c \Delta t Q_{i+1/2}^* \right].
$$

Solve Riemann problems:

 $Q_i^n - Q_{i-1}^n = \Delta Q_{i-1/2} = \mathcal{W}_{i-1/2}^1 + \mathcal{W}_{i-1/2}^2 = \alpha_{i-1/2}^1 r^1 + \alpha_{i-1/2}^2 r^2$  $Q_{i+1}^n - Q_i^n = \Delta Q_{i+1/2} = \mathcal{W}_{i+1/2}^1 + \mathcal{W}_{i+1/2}^2 = \alpha_{i+1/2}^1 r^1 + \alpha_{i+1/2}^2 r^2,$ 

The intermediate states are:

$$
Q_{i-1/2}^* = Q_i^n - \mathcal{W}_{i-1/2}^2, \qquad Q_{i+1/2}^* = Q_i^n + \mathcal{W}_{i+1/2}^1,
$$

$$
Q_i^{n+1} = \frac{1}{\Delta x} \left[ c \Delta t Q_{i-1/2}^* + (\Delta x - 2c \Delta t) Q_i^n + c \Delta t Q_{i+1/2}^* \right].
$$

Solve Riemann problems:

$$
Q_i^n - Q_{i-1}^n = \Delta Q_{i-1/2} = \mathcal{W}_{i-1/2}^1 + \mathcal{W}_{i-1/2}^2 = \alpha_{i-1/2}^1 r^1 + \alpha_{i-1/2}^2 r^2,
$$
  
\n
$$
Q_{i+1}^n - Q_i^n = \Delta Q_{i+1/2} = \mathcal{W}_{i+1/2}^1 + \mathcal{W}_{i+1/2}^2 = \alpha_{i+1/2}^1 r^1 + \alpha_{i+1/2}^2 r^2,
$$

The intermediate states are:

$$
Q_{i-1/2}^* = Q_i^n - \mathcal{W}_{i-1/2}^2, \qquad Q_{i+1/2}^* = Q_i^n + \mathcal{W}_{i+1/2}^1,
$$

So,

$$
Q_i^{n+1} = \frac{1}{\Delta x} \left[ c \Delta t (Q_i^n - \mathcal{W}_{i-1/2}^2) + (\Delta x - 2c\Delta t) Q_i^n + c \Delta t (Q_i^n + \mathcal{W}_{i+1/2}^1) \right]
$$
  
=  $Q_i^n - \frac{c \Delta t}{\Delta x} \mathcal{W}_{i-1/2}^2 + \frac{c \Delta t}{\Delta x} \mathcal{W}_{i+1/2}^1$ .

#### Solve Riemann problems:

$$
Q_i^n - Q_{i-1}^n = \Delta Q_{i-1/2} = \mathcal{W}_{i-1/2}^1 + \mathcal{W}_{i-1/2}^2 = \alpha_{i-1/2}^1 r^1 + \alpha_{i-1/2}^2 r^2,
$$
  
\n
$$
Q_{i+1}^n - Q_i^n = \Delta Q_{i+1/2} = \mathcal{W}_{i+1/2}^1 + \mathcal{W}_{i+1/2}^2 = \alpha_{i+1/2}^1 r^1 + \alpha_{i+1/2}^2 r^2,
$$

The waves are determined by solving for  $\alpha$  from  $R\alpha = \Delta Q$ :

$$
A = \begin{bmatrix} 0 & K \\ 1/\rho & 0 \end{bmatrix}, \qquad R = \begin{bmatrix} -Z & Z \\ 1 & 1 \end{bmatrix}, \qquad R^{-1} = \frac{1}{2Z} \begin{bmatrix} -1 & Z \\ 1 & Z \end{bmatrix}.
$$

So

$$
\Delta Q = \left[ \begin{array}{c} \Delta p \\ \Delta u \end{array} \right] = \alpha^1 \left[ \begin{array}{c} -Z \\ 1 \end{array} \right] + \alpha^2 \left[ \begin{array}{c} Z \\ 1 \end{array} \right]
$$

with

$$
\alpha^1 = \frac{1}{2Z}(-\Delta p + Z\Delta u), \qquad \alpha^2 = \frac{1}{2Z}(\Delta p + Z\Delta u).
$$

## CLAWPACK Riemann solver

The hyperbolic problem is specified by the Riemann solver

- Input: Values of  $q$  in each grid cell
- Output: Solution to Riemann problem at each interface.
	- Waves  $W^p \in \mathbb{R}^m$ ,  $p = 1, 2, \ldots, M_w$
	- Speeds  $s^p \in \mathbb{R}$ ,  $p = 1, 2, ..., M_w$ ,
	- Fluctuations  $\mathcal{A}^- \Delta Q$ ,  $\mathcal{A}^+ \Delta Q \in \mathbb{R}^m$

Note: Number of waves  $M_w$  often equal to m (length of q), but could be different (e.g. HLL solver has 2 waves).

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Note: Number of waves  $M_w$  often equal to m (length of q), but could be different (e.g. HLL solver has 2 waves).

#### Fluctuations:

 $\mathcal{A}^- \Delta Q =$  Contribution to cell average to left,  $\mathcal{A}^+\Delta Q =$  Contribution to cell average to right

For conservation law,  $A^{-}\Delta Q + A^{+}\Delta Q = f(Q_r) - f(Q_l)$ 

# CLAWPACK Riemann solver

Inputs to rp1 subroutine:

q1(i,1:m) = Value of q at left edge of ith cell,

 $qr(i,1:m)$  = Value of q at right edge of ith cell,

Warning: The Riemann problem at the interface between cells  $i-1$  and i has left state  $\sigma$  (i-1,:) and right state  $\sigma$ 1(i,:).

rp1 is normally called with  $q1 = qr = q$ , but designed to allow other methods:



# Wave propagation algorithms in 2D

Clawpack requires:

Normal Riemann solver rpn2.f Solves 1d Riemann problem  $q_t + A q_x = 0$ Decomposes  $\Delta Q = Q_{ij} - Q_{i-1,j}$  into  $\mathcal{A}^+ \Delta Q$  and  $\mathcal{A}^- \Delta Q$ . For  $q_t + Aq_x + Bq_y = 0$ , split using eigenvalues, vectors:

$$
A = R\Lambda R^{-1} \implies A^- = R\Lambda^- R^{-1}, A^+ = R\Lambda^+ R^{-1}
$$

Input parameter  $ixy$  determines if it's in x or y direction. In latter case splitting is done using  $B$  instead of  $A$ . This is all that's required for dimensional splitting.

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$$
A = R\Lambda R^{-1} \implies A^- = R\Lambda^- R^{-1}, A^+ = R\Lambda^+ R^{-1}
$$

Input parameter  $ixy$  determines if it's in x or y direction. In latter case splitting is done using  $B$  instead of  $A$ . This is all that's required for dimensional splitting.

Transverse Riemann solver rpt2.f Decomposes  $\mathcal{A}^+ \Delta Q$  into  $\mathcal{B}^- \mathcal{A}^+ \Delta Q$  and  $\mathcal{B}^+ \mathcal{A}^+ \Delta Q$  by splitting this vector into eigenvectors of  $B$ .

(Or splits vector into eigenvectors of A if  $ixy=2$ .)