

The following is the analytical solution for the diffusion in composite spherical geometry: (For more details refer to "Lithium Intercalation in Core-Shell Materials–Theoretical Analysis")

```
> restart:with(plots):Digits:=15:with(RootFinding):with(IntegrationTools):
```

```
>
```

User defined parameters:

Description of parameters: beta^2=D2/D1, alpha=R1/R2, kappa=c1*/c2*,delta=current density

```
> constants:=[beta=5,alpha=0.4,gamma=1000,kappa=1.5,delta=-.25];
constants := [ β = 5, α = 0.4, γ = 1000, κ = 1.5, δ = -0.25 ]
```

Number of eigenvalues to be used (Higher the better!!!)

```
> NN:=20:
```

```
>
```

```
>
```

Solution

```
> param1:=[theta[n]=alpha*lambda[n]*beta,phi[n]=lambda[n]*(alpha-1)]
```

```
;
```

$$param1 := [\theta_n = \alpha \lambda_n \beta, \phi_n = \lambda_n (\alpha - 1)]$$

```
> param2:=[theta[n]=alpha*lambda*beta,phi[n]=lambda*(alpha-1)];
```

$$param2 := [\theta_n = \alpha \lambda \beta, \phi_n = \lambda (\alpha - 1)]$$

Eigenvalue Equation

```
> eigeneqn:=subs(param2,(1/gamma+beta^2*alpha^2*lambda^2+1/gamma*alpha*lambda^2-alpha*kappa+beta^2*alpha)*sin(theta[n])*sin(phi[n])+(-beta^2*alpha^2*lambda+beta^2*alpha*lambda-alpha*kappa+1/gamma*lambda-1/gamma*lambda*alpha)*cos(phi[n])*sin(theta[n])+(beta*alpha^2*lambda*kappa-1/gamma*beta*lambda*alpha-1/gamma*beta*lambda^3*alpha^2)*sin(phi[n])*cos(theta[n])+(beta*alpha^2*lambda^2*kappa+1/gamma*beta*lambda^2*alpha-1/gamma*beta*lambda^2*alpha)*cos(theta[n])*cos(phi[n]));
```

$$\begin{aligned} eigeneqn := & \left(\frac{1}{\gamma} + \beta^2 \alpha^2 \lambda^2 + \frac{\alpha \lambda^2}{\gamma} - \alpha \kappa + \beta^2 \alpha \right) \sin(\alpha \lambda \beta) \sin(\lambda (\alpha - 1)) \\ & + \left(-\beta^2 \alpha^2 \lambda + \beta^2 \alpha \lambda - \alpha \lambda \kappa + \frac{\lambda}{\gamma} - \frac{\lambda \alpha}{\gamma} \right) \cos(\lambda (\alpha - 1)) \sin(\alpha \lambda \beta) \\ & + \left(\beta \alpha^2 \lambda \kappa - \frac{\beta \lambda \alpha}{\gamma} - \frac{\beta \lambda^3 \alpha^2}{\gamma} \right) \sin(\lambda (\alpha - 1)) \cos(\alpha \lambda \beta) \\ & + \left(\beta \alpha^2 \lambda^2 \kappa + \frac{\beta \lambda^2 \alpha^2}{\gamma} - \frac{\beta \lambda^2 \alpha}{\gamma} \right) \cos(\alpha \lambda \beta) \cos(\lambda (\alpha - 1)) \end{aligned}$$

Function to return Eigenequation (necessary for using Nextzero function of Maple) The following

equation is hardcoded (copy pasted from above), this is the only way I can make the nextzero work.

```
> KKK:=lambda->(1/gamma+beta^2*alpha^2*lambda^2+1/gamma*alpha*lambda
^2-alpha*kappa+beta^2*alpha)*sin(alpha*lambda*beta)*sin(lambda*(al
pha-1))+(-beta^2*alpha^2*lambda+beta^2*alpha*lambda-alpha*lambda*k
appa+1/gamma*lambda-1/gamma*lambda*alpha)*cos(lambda*(alpha-1))*si
n(alpha*lambda*beta)+(beta*alpha^2*lambda*kappa-1/gamma*beta*lam
da*alpha-1/gamma*beta*lambda^3*alpha^2)*sin(lambda*(alpha-1))*cos(a
lpha*lambda*beta)+(beta*alpha^2*lambda^2*kappa+1/gamma*beta*lam
da^2*alpha^2-1/gamma*beta*lambda^2*alpha)*cos(alpha*lambda*beta)*cos
(lambda*(alpha-1));
```

$$KKK := \lambda \rightarrow \left(\frac{1}{\gamma} + \beta^2 \alpha^2 \lambda^2 + \frac{\alpha \lambda^2}{\gamma} - \alpha \kappa + \beta^2 \alpha \right) \sin(\alpha \lambda \beta) \sin(\lambda (\alpha - 1)) \\ + \left(-\beta^2 \alpha^2 \lambda + \beta^2 \alpha \lambda \kappa - \alpha \lambda \kappa + \frac{\lambda}{\gamma} - \frac{\lambda \alpha}{\gamma} \right) \cos(\lambda (\alpha - 1)) \sin(\alpha \lambda \beta) \\ + \left(\beta \alpha^2 \lambda \kappa - \frac{\beta \lambda \alpha}{\gamma} - \frac{\beta \lambda^3 \alpha^2}{\gamma} \right) \sin(\lambda (\alpha - 1)) \cos(\alpha \lambda \beta) \\ + \left(\beta \alpha^2 \lambda^2 \kappa + \frac{\beta \lambda^2 \alpha^2}{\gamma} - \frac{\beta \lambda^2 \alpha}{\gamma} \right) \cos(\alpha \lambda \beta) \cos(\lambda (\alpha - 1))$$

```
> ChiParam:=
```

```
[
```

```
chi[1] = cos(theta[n])*theta[n]-sin(theta[n]),
chi[2] = phi[n]*cos(phi[n])+(-alpha*lambda[n]^2-1)*sin(phi[n]),
chi[3] = -theta[n]+cos(theta[n])*sin(theta[n]),
chi[4] =
cos(phi[n])*sin(phi[n])*(-lambda[n]^2+1)+2*lambda[n]*cos(phi[n])^2
-phi[n]*lambda[n]^2+(-alpha-1)*lambda[n]
```

```
];
```

```
ChiParam := [  $\chi_1 = \cos(\theta_n) \theta_n - \sin(\theta_n)$ ,  $\chi_2 = \phi_n \cos(\phi_n) + (-\alpha \lambda_n^2 - 1) \sin(\phi_n)$ ,
 $\chi_3 = -\theta_n + \cos(\theta_n) \sin(\theta_n)$ ,  $\chi_4 = \cos(\phi_n) \sin(\phi_n) (-\lambda_n^2 + 1) + 2 \lambda_n \cos(\phi_n)^2 - \phi_n \lambda_n^2 + (-\alpha - 1) \lambda_n$  ]
```

```
>
```

```
> Aneqn:=A[n] =
2*chi[1]*delta*kappa*lambda[n]/(beta^3*chi[2]^2*chi[3]-kappa*chi[1]^2*chi[4]);
```

$$Aneqn := A_n = \frac{2 \chi_1 \delta \kappa \lambda_n}{\beta^3 \chi_2^2 \chi_3 - \kappa \chi_1^2 \chi_4}$$

```

> OtherParam:=[

k[1] = -3*kappa*delta/(alpha^3*kappa-alpha^3+1) ,
k[2] = -3*delta/(alpha^3*kappa-alpha^3+1) ,

a[1] =
1/10*(-5*alpha^5*beta^2-3*alpha^5+(3*alpha^5*beta^2+5*alpha^5-15*a
lpha^3+10*alpha^2)*kappa+15*alpha^3-15*alpha^2+5*alpha^2*beta^2+3)
*delta*kappa/(alpha^3*kappa-alpha^3+1)^2+1/10*(10*alpha^4-10*alpha
)*delta*kappa/(alpha^3*kappa-alpha^3+1)^2/gamma,

a[2] =
-1/10/(alpha^6*kappa^2+(-2*alpha^6+2*alpha^3)*kappa+alpha^6-2*alph
a^3+1)*(10*kappa^2*alpha^5+((2*beta^2-30)*alpha^5+15*alpha^3)*kapp
a+18*alpha^5-15*alpha^3-3)*delta+1/(alpha^6*kappa^2+(-2*alpha^6+2*
alpha^3)*kappa+alpha^6-2*alpha^3+1)*kappa*alpha^4*delta/gamma
];

```

$$\begin{aligned}
OtherParam := & \left[k_1 = -\frac{3 \kappa \delta}{\alpha^3 \kappa - \alpha^3 + 1}, k_2 = -\frac{3 \delta}{\alpha^3 \kappa - \alpha^3 + 1}, a_1 = \right. \\
& \frac{(-5 \alpha^5 \beta^2 - 3 \alpha^5 + (3 \alpha^5 \beta^2 + 5 \alpha^5 - 15 \alpha^3 + 10 \alpha^2) \kappa + 15 \alpha^3 - 15 \alpha^2 + 5 \alpha^2 \beta^2 + 3) \delta \kappa}{10 (\alpha^3 \kappa - \alpha^3 + 1)^2} \\
& + \frac{(10 \alpha^4 - 10 \alpha) \delta \kappa}{10 (\alpha^3 \kappa - \alpha^3 + 1)^2 \gamma}, a_2 = -\frac{(10 \kappa^2 \alpha^5 + ((2 \beta^2 - 30) \alpha^5 + 15 \alpha^3) \kappa + 18 \alpha^5 - 15 \alpha^3 - 3) \delta}{10 (\alpha^6 \kappa^2 + (-2 \alpha^6 + 2 \alpha^3) \kappa + \alpha^6 - 2 \alpha^3 + 1)} \\
& \left. + \frac{\kappa \alpha^4 \delta}{(\alpha^6 \kappa^2 + (-2 \alpha^6 + 2 \alpha^3) \kappa + \alpha^6 - 2 \alpha^3 + 1) \gamma} \right]
\end{aligned}$$

```
> #####
```

Final Solution

```
x2 #part1=without infinite sum, part2 term in the infinite sum
```

```
>
```

```
> x1part1:=1/6*k[1]*beta^2*x^2+a[1]+k[1]*t;
```

$$x1part1 := \frac{1}{6} k_1 \beta^2 x^2 + a_1 + k_1 t$$

```
> x1part2:=-sin(lambda[n]*beta*x)*chi[2]*A[n]*beta^2/lambda[n]/x*exp
(-lambda[n]^2*t);
```

$$x1part2 := -\frac{\sin(\lambda_n \beta x) \chi_2 A_n \beta^2 e^{\left(-\lambda_n^2 t\right)}}{\lambda_n x}$$

```

[ >
[ x2 #part1=without infinite sum, part2 term in the infinite sum
[ > x2part1:=1/6*k[2]*x^2-(-delta-1/3*k[2])/x+a[2]+k[2]*t;

$$x2part1 := \frac{1}{6} k_2 x^2 - \frac{-\delta - \frac{1}{3} k_2}{x} + a_2 + k_2 t$$

[ > x2part2:=- (lambda[n]*cos(x*lambda[n]-lambda[n])+sin(x*lambda[n]-la
mbda[n]))/lambda[n]/x*chi[1]*A[n]*exp(-lambda[n]^2*t) ;

$$x2part2 := - \frac{(\lambda_n \cos(x \lambda_n - \lambda_n) + \sin(x \lambda_n - \lambda_n)) \chi_1 A_n e^{(-\lambda_n^2 t)}}{\lambda_n x}$$

[ >

```

Calculation of X1 and X2 expressions using numerical eigenvalues

```

First Eigenvalue
[ > Lam[1]:=NextZero(subs(param1,constants,lambda[n]=lambda,eval(KKK))
,0);

$$Lam_1 := 1.58054819116320$$

All eigenvalues till NN
[ > for i from 2 to NN do
    Lam[i]:=NextZero(subs(constants,eval(KKK)),Lam[i-1]);od:
List of all the eigenvalues
[ > ListLambda:=[seq(lambda[i]=Lam[i],i=1..NN)]:
Check if the k1 k2 and a1 and a2 are calculated numerically
[ > evalf(subs(constants,OtherParam));
Computation of Expressions for x1 and x2
[ > expr11:=0:expr22:=0:
    for i from 1 to NN do

NumChiparam:=evalf(subs(param1,n=i,ListLambda,constants,ChiParam))
;
NumAn:=evalf(subs(param1,n=i,ListLambda,constants,NumChiparam,Aneq
n));
expr11:=expr11
+subs(param1,n=i,NumChiparam,ListLambda,NumAn,OtherParam,constants
, x1part2);

expr22:=expr22

```

```

+subs(param1,n=i,NumChiparam,ListLambda,NumAn,OtherParam,constants
, x2part2):
od:
[> expr1:=expr11+subs(OtherParam,constants,x1part1):
[> expr2:=expr22+subs(OtherParam,constants,x2part1):
[> param1;
[>
[>
[>

```

Plot of concentration curves

```

[> p3:=plot(evalf(subs(t=0,expr1)),x=0..eval(alpha,constants)):p4:=pl
ot(evalf(subs(t=0,expr2)),x=eval(alpha,constants)..1):display(p3,p
4);

[>
[> q1:=plot3d(expr1,x=0..subs(constants,alpha),t=1/4000..0.1,axes=box
ed):
[> q2:=plot3d(expr2,x=subs(constants,alpha)..1,t=1/4000..0.1,axes=box
ed):
[> with(plots):
[> display(q1,q2);
display(q1, q2)
[>
[>
[>

```

Stress parameter definition and equations:

```

[> nondimparam := [Theta = E[1]/E[2], PI = Omega[1]/Omega[2],
Sigma[r[1]] = -(-1+nu[1])*sigma[r1](x)/Omega[1]/E[1]/c[0],
Sigma[t[1]] = -(-1+nu[1])*sigma[t1](x)/Omega[1]/E[1]/c[0],
Sigma[r[2]] = -(-1+nu[2])*sigma[r2](x)/Omega[2]/E[2]/c[0],
Sigma[t[2]] = -(-1+nu[2])*sigma[t2](x)/Omega[2]/E[2]/c[0]];

nondimparam := 
$$\Theta = \frac{E_1}{E_2}, \Pi = \frac{\Omega_1}{\Omega_2}, \Sigma_{r_1} = -\frac{(-1 + \nu_1) \sigma_{r1}(x)}{\Omega_1 E_1 c_0}, \Sigma_{t_1} = -\frac{(-1 + \nu_1) \sigma_{t1}(x)}{\Omega_1 E_1 c_0},$$


$$\Sigma_{r_2} = -\frac{(-1 + \nu_2) \sigma_{r2}(x)}{\Omega_2 E_2 c_0}, \Sigma_{t_2} = -\frac{(-1 + \nu_2) \sigma_{t2}(x)}{\Omega_2 E_2 c_0}$$


[> add_param :=
[4*Theta*alpha^3*nu[2]-2*Theta*alpha^3-4*alpha^3*nu[1]+2*alpha^3-T
heta*nu[2]-Theta+4*nu[1]-2 = Delta[1],
4*Theta*alpha^3*nu[2]-2*Theta*alpha^3-alpha^3*nu[1]-alpha^3-Theta*
```

```

nu[2]-Theta+nu[1]+1 = Delta[2], 2*Theta*nu[2]-Theta-2*nu[1]+1 =
Delta[3], Theta*nu[2]+Theta-4*nu[1]+2 = Delta[4]];

add_param := [4 Θ α³ ν₂ - 2 Θ α³ - 4 α³ ν₁ + 2 α³ - Θ ν₂ - Θ + 4 ν₁ - 2 = Δ₁,
4 Θ α³ ν₂ - 2 Θ α³ - α³ ν₁ - α³ - Θ ν₂ - Θ + ν₁ + 1 = Δ₂, 2 Θ ν₂ - Θ - 2 ν₁ + 1 = Δ₃,
Θ ν₂ + Θ - 4 ν₁ + 2 = Δ₄]

> sigmar1eqn1 := Sigma[r[1]] =
2/3*Delta[2]/alpha^3/Delta[1]*int(z^2*x[1](z), z = 0 ..
alpha)-2/3*1/x^3*int(z^2*x[1](z), z = 0 ..
x)+2*(-1+nu[1])/Delta[1]/PI*int(z^2*x[2](z), z = alpha .. 1);

sigmar1eqn1 := Σr1 =  $\frac{2}{3} \left( \frac{\Delta_2}{\alpha^3 \Delta_1} \int_0^\alpha z^2 x_1(z) dz \right) - \frac{2}{3} \left( \frac{1}{x^3} \int_0^x z^2 x_1(z) dz \right) + \frac{2(-1+\nu_1)}{\Delta_1 \Pi} \int_\alpha^1 z^2 x_2(z) dz$ 

> sigmat1eqn1 := Sigma[t[1]] =
2/3*Delta[2]/alpha^3/Delta[1]*int(z^2*x[1](z), z = 0 ..
alpha)+1/3*1/x^3*int(z^2*x[1](z), z = 0 ..
x)+2*(-1+nu[1])/Delta[1]/PI*int(z^2*x[2](z), z = alpha ..
1)-1/3*x[1](z);

sigmat1eqn1 :=
Σt1 =  $\frac{2}{3} \left( \frac{\Delta_2}{\alpha^3 \Delta_1} \int_0^\alpha z^2 x_1(z) dz \right) + \frac{1}{3} \left( \frac{1}{x^3} \int_0^x z^2 x_1(z) dz \right) + \frac{2(-1+\nu_1)}{\Delta_1 \Pi} \int_\alpha^1 z^2 x_2(z) dz - \frac{1}{3} x_1(z)$ 

> sigmar2eqn1 := Sigma[r[2]] =
2*Theta*PI*(x-1)*(x^2+x+1)*(-1+nu[2])/Delta[1]/x^3*int(z^2*x[1](z),
,z = 0 ..
alpha)+2/3*(2*alpha^3*Delta[3]-x^3*Delta[4])/Delta[1]/x^3*int(z^2*x[2](z),
,z = alpha .. 1)-2/3*1/x^3*int(z^2*x[2](z),z = alpha .. x);

sigmar2eqn1 := Σr2 =  $\frac{2 \Theta \Pi (x-1) (x^2+x+1) (-1+\nu_2)}{\Delta_1 x^3} \int_0^\alpha z^2 x_1(z) dz$ 
+  $\frac{2}{3} \left( \frac{2 \alpha^3 \Delta_3 - x^3 \Delta_4}{\Delta_1 x^3} \int_\alpha^1 z^2 x_2(z) dz \right) - \frac{2}{3} \left( \frac{1}{x^3} \int_\alpha^x z^2 x_2(z) dz \right)$ 

> sigmat2eqn1 := Sigma[t[2]] =
Theta*(2*x^3+1)*(-1+nu[2])*PI/Delta[1]/x^3*int(z^2*x[1](z),z = 0 ..
..
alpha)-2/3*(alpha^3*Delta[3]+x^3*Delta[4])/Delta[1]/x^3*int(z^2*x[2](z),
,z = alpha .. 1)+1/3*1/x^3*int(z^2*x[2](z),z = alpha ..
x)-1/3*x[2](z);

```

$$\begin{aligned} \text{sigmat2eqn1} := \Sigma_{t_2} = & \frac{\Theta(2x^3 + 1)(-1 + v_2)\Pi}{\Delta_1 x^3} \int_0^a z^2 x_1(z) dz - \frac{2}{3} \left(\frac{\alpha^3 \Delta_3 + x^3 \Delta_4}{\Delta_1 x^3} \int_a^1 z^2 x_2(z) dz \right) \\ & + \frac{1}{3} \left(\frac{1}{x^3} \int_a^x z^2 x_2(z) dz \right) - \frac{1}{3} x_2(z) \end{aligned}$$

[>

[>

Stress calculation and plots

```
> num_nondimparam:=[Theta=1,PI=1,nu[1]=0.3,nu[2]=0.3];#param22
      num_nondimparam := [Theta = 1, PI = 1, nu1 = 0.3, nu2 = 0.3]
> add_param2:=[seq(rhs(add_param[i])=lhs(subs(num_nondimparam,constants,add_param[i])),i=1..nops(add_param))];#param11
      add_param2 := [Delta1 = -2.1, Delta2 = -0.1344, Delta3 = 0., Delta4 = 2.1]

Plot at different point in time
> NPlots:=5:
Specific time when profiles will be plotted
> ttime:=[0.01,0.025,0.05,0.1,0.2]:
Style of lines in the plot (may not work)
> styleop:=[dash,dashdot,dot,solid,circle];
      styleop := [dash, dashdot, dot, solid, circle]
>
> for i from 1 to NPlots do

dumexpr11:=evalf(subs(t=ttime[i],expr1));
dumexpr22:=evalf(subs(t=ttime[i],expr2));

px1||i:=plot(evalf(subs(t=ttime[i],expr1)),x=0..eval(alpha,constants),color=black,thickness=3,linestyle = i+1):
px2||i:=plot(evalf(subs(t=ttime[i],expr2)),x=eval(alpha,constants)..1,color=blue,thickness=3,linestyle = i+1);

#print(i);

psr1_||i:=plot(Expand(subs(add_param2,constants,num_nondimparam,subs(x[1](x)=dumexpr11,x[2](x)=dumexpr22,(PI*Theta)*rhs(subs(z=x,sigmar1eqn1)))),x=0..eval(alpha,constants),color=black,thickness=3,linestyle = i+1):
#print(i);
psr2_||i:=plot(Expand(subs(add_param2,constants,num_nondimparam,subs(x[1](x)=dumexpr11,x[2](x)=dumexpr22,(PI*Theta)*rhs(subs(z=x,sigmar1eqn1)))),x=0..eval(alpha,constants),color=black,thickness=3,linestyle = i+1):
```

```

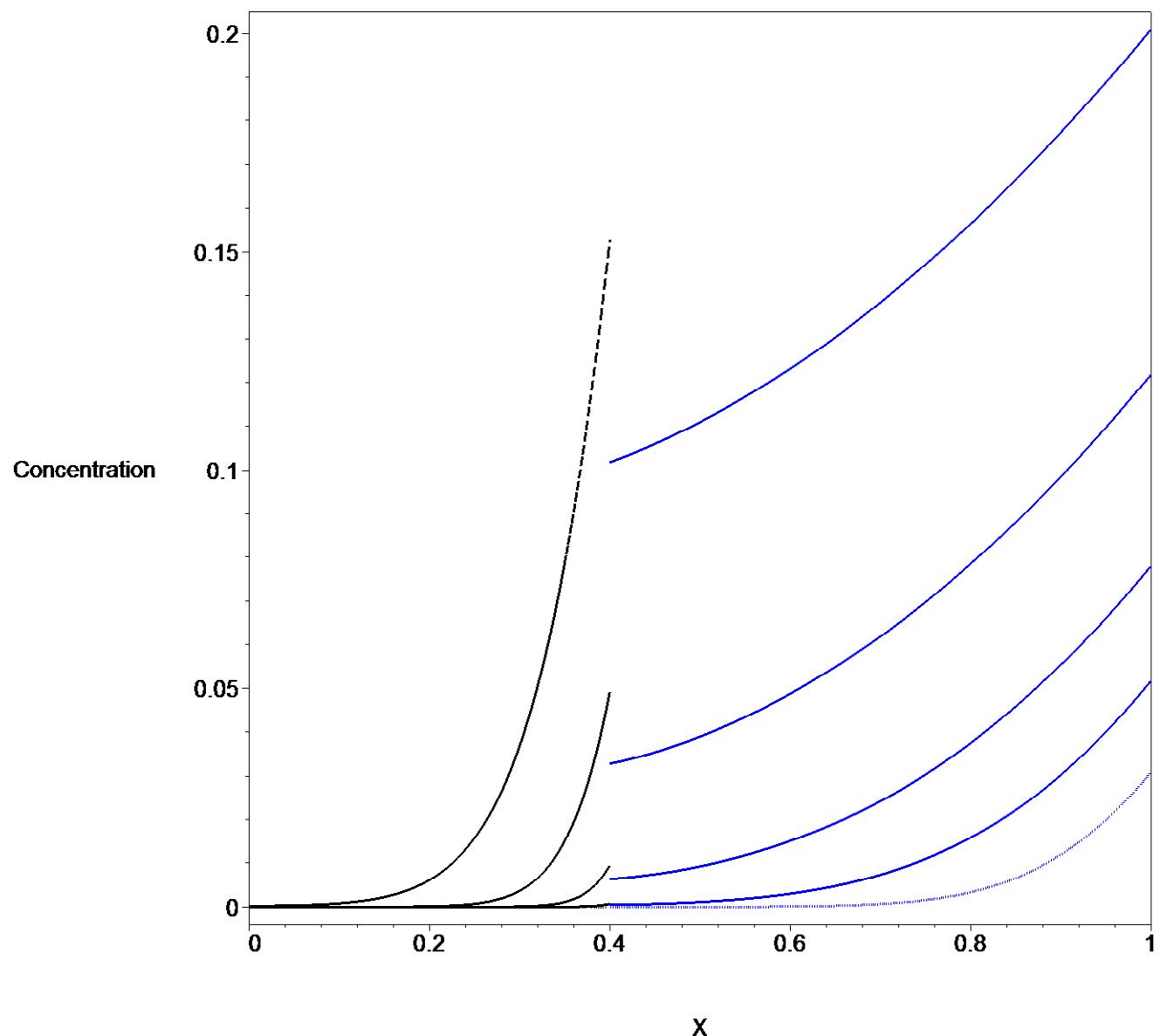
bs(x[1](x)=dumexpr11,x[2](x)=dumexpr22,rhs(subs(z=x,sigmar2eqn1)))
)),x=eval(alpha,constants)..1,color=blue,thickness=3,linestyle =
i+1):

#print(i);

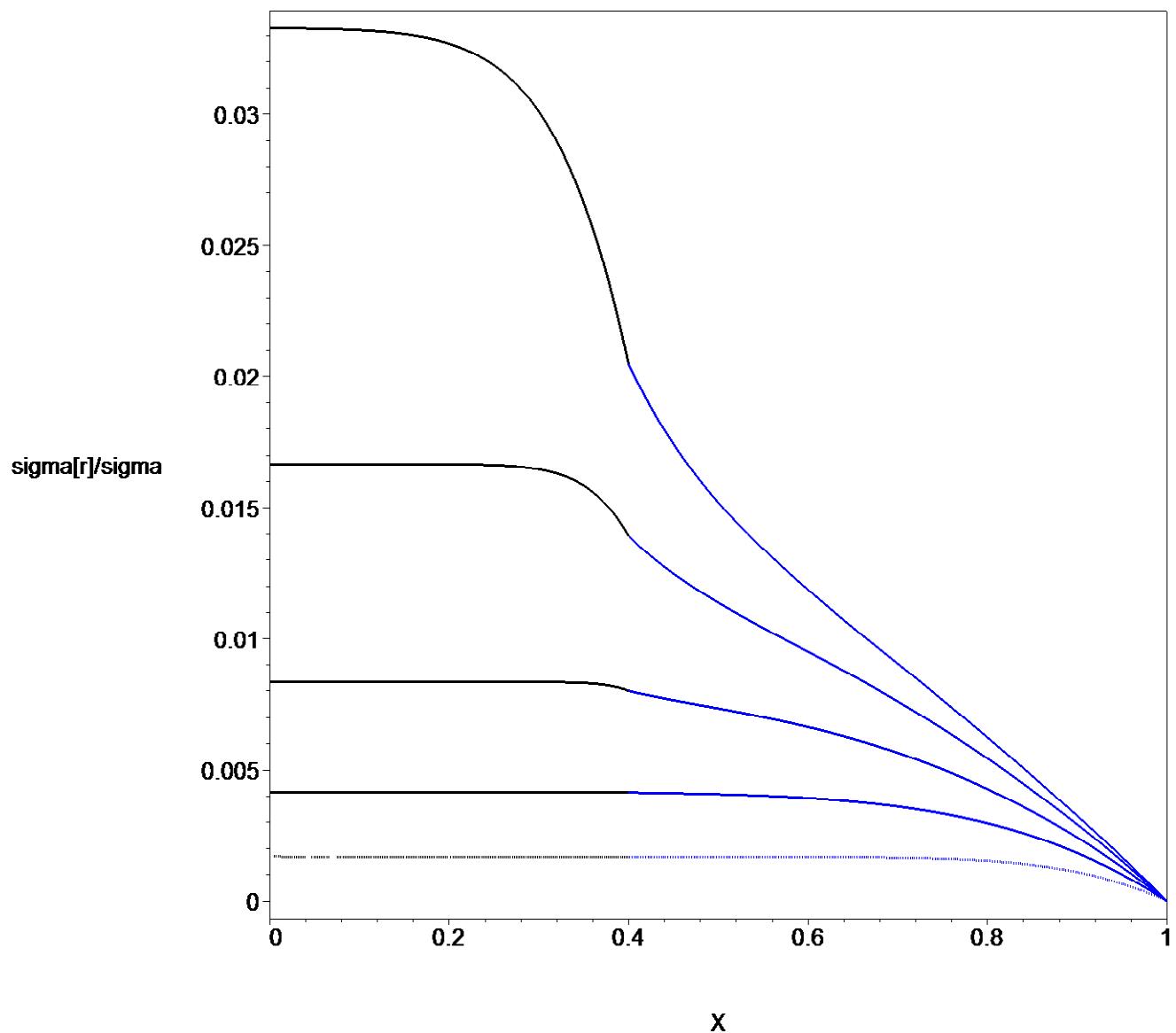
pst1_||i:=plot(Expand(subs(add_param2,constants,num_nondimparam,su
bs(x[1](x)=dumexpr11,x[2](x)=dumexpr22,(PI*Theta)*rhs(subs(z=x,sig
mat1eqn1)))),x=0..eval(alpha,constants),color=black,thickness=3,l
inestyle = i+1):

pst2_||i:=plot(Expand(subs(add_param2,constants,num_nondimparam,su
bs(x[1](x)=dumexpr11,x[2](x)=dumexpr22,rhs(subs(z=x,sigmat2eqn1)))
)),x=eval(alpha,constants)..1,color=blue,thickness=3,linestyle =
i+1):
print(i);
od:
      1
      2
      3
      4
      5
> i:='i':
display(seq(px1||i,i=1..NPlots),seq(px2||i,i=1..NPlots),axes=boxed
,labels=[ "X",Concentration],labeldirections=[horizontal,horizontal
]);

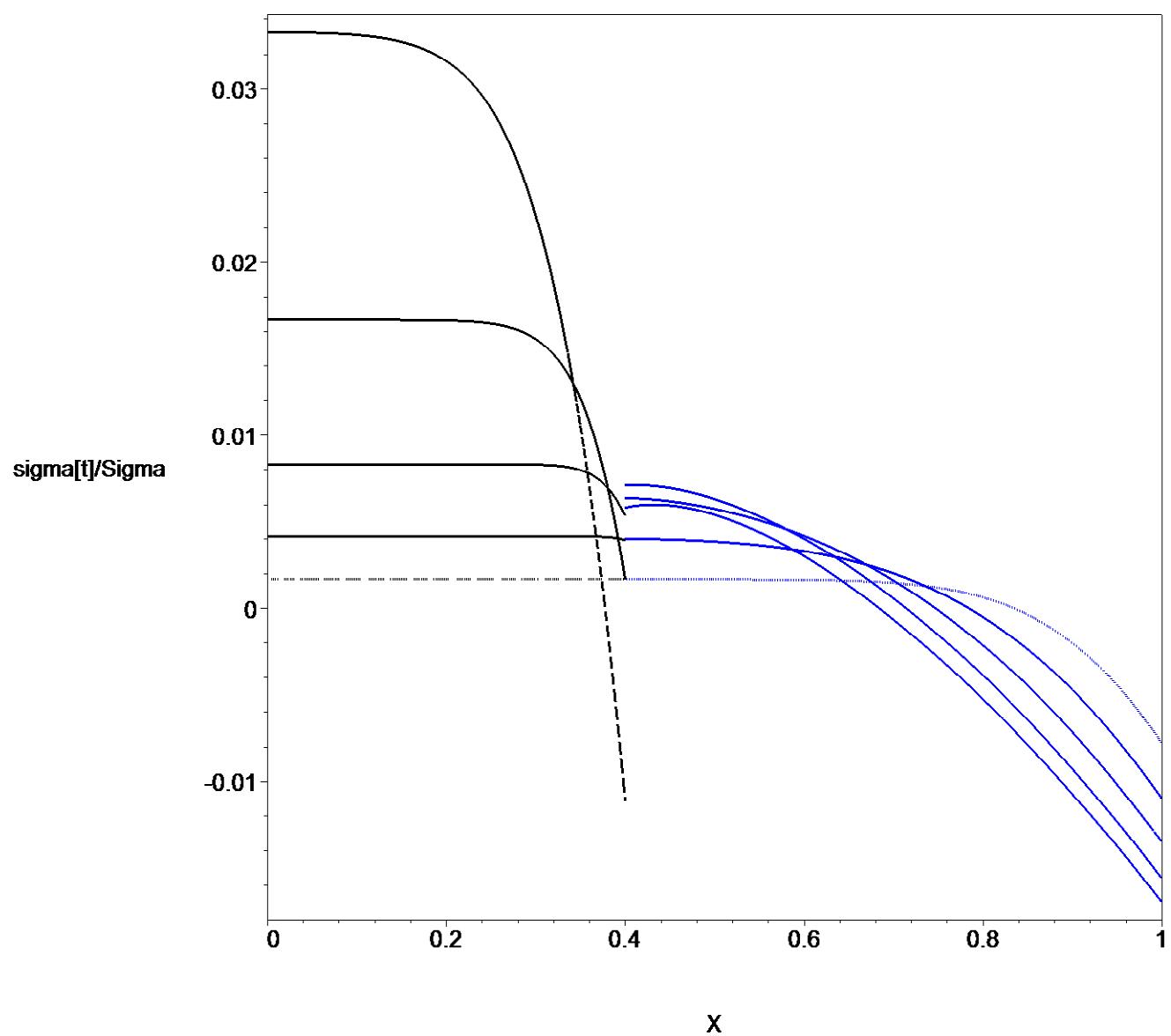
```



```
>
> #?font
> display(seq(psr1_||i,i=1..NPlots),seq(psr2_||i,i=1..NPlots),axes=b
oxed,labels=["X",sigma[r]/sigma],labeldirections=[horizontal,horiz
ontal]);
```



```
>
> display(seq(pst1_||i,i=1..NPlots),seq(pst2_||i,i=1..NPlots),axes=boxed,labels=["X",sigma[t]/Sigma],labeldirections=[horizontal,horizontal]);
```



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