

Self-assembly  
from Nano to Milli Scales  
Prof. Karl F Böhringer, Electrical Engineering

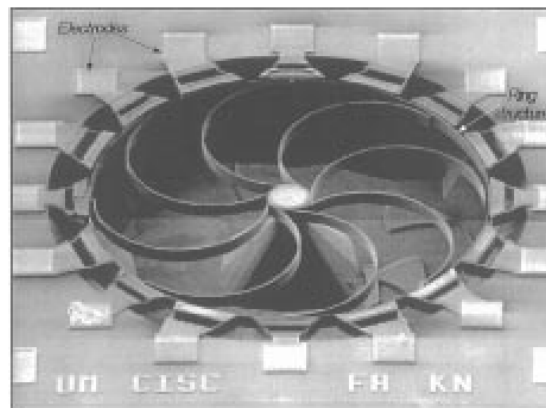
Freshman Seminar – GEN ST 197 D  
Nanoscience & Molecular Engineering  
Monday, March 1, 2010

# Introduction

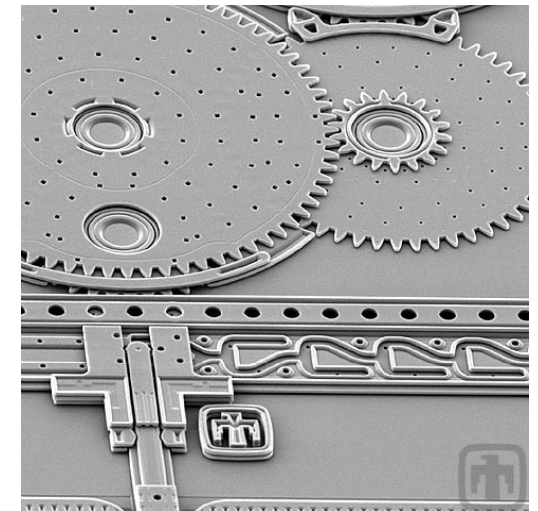
- Micro Electro Mechanical Systems (MEMS):
  - Sub-millimeter sized machines typically built in batch fabrication processes derived from integrated circuit (IC) technology
  - Can have broad functionality, including sensing, actuation, computation, and communication



MEMS Scanning  
Tunneling Microscope  
[Xu et al. APS'95]



Vibrating ring gyro  
[Ayazi et al.  
IEEE MEMS'98]



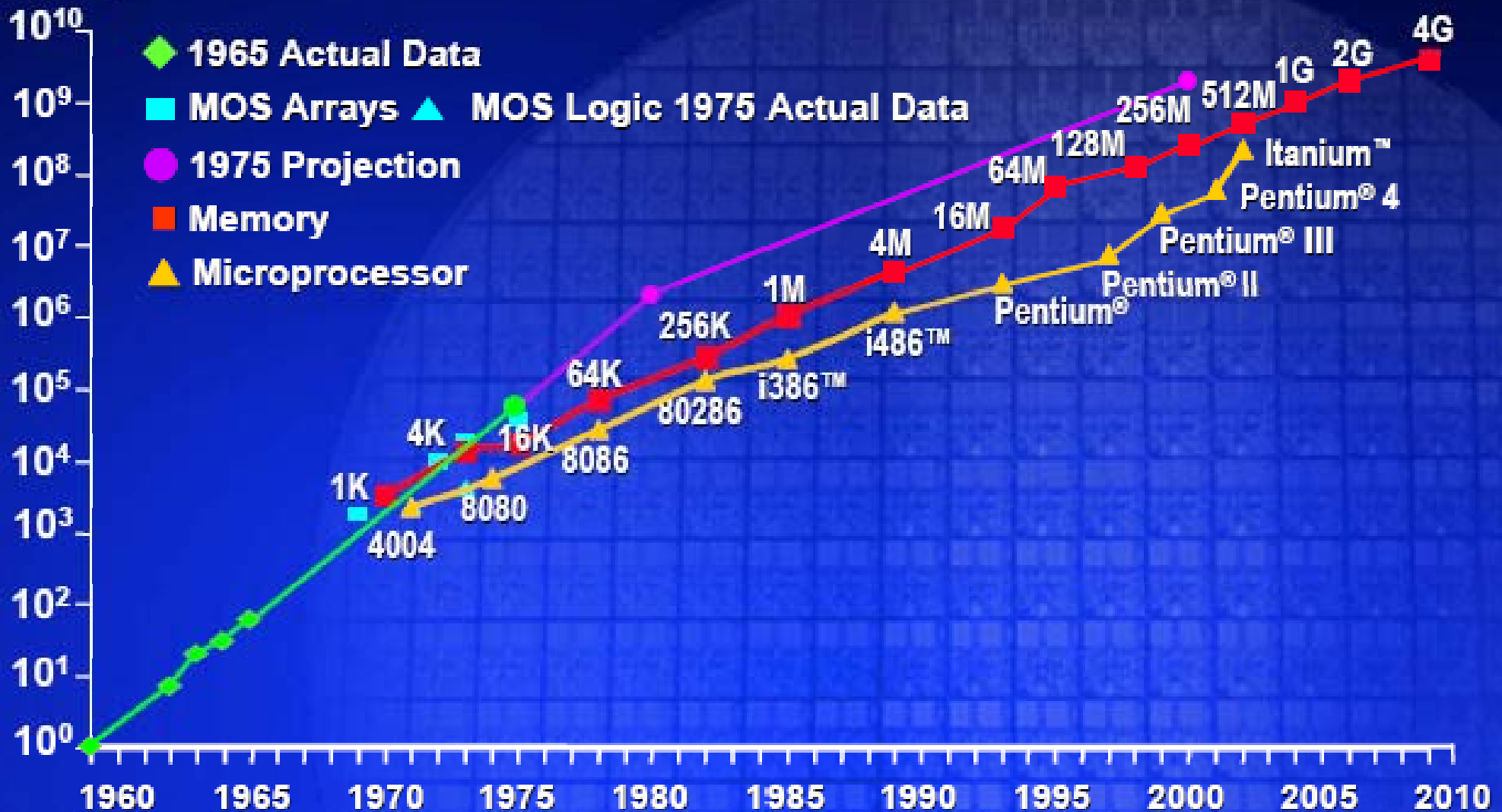
Micro combination lock  
[Sandia National Labs]

# Introduction

- Micro Electro Mechanical Systems (MEMS):
  - Sub-millimeter sized machines typically built in batch fabrication processes derived from integrated circuit (IC) technology
  - Can have broad functionality, including sensing, actuation, computation, and communication
- Claim:
  - Just like IC's have revolutionized computation, MEMS are revolutionizing sensors and actuators (transducers)
- Challenge:
  - Unlike IC's, MEMS rely on a much broader range of materials, processes, and effects to achieve their optimal functionality

# Integrated Circuit Complexity

Transistors  
Per Die



# Motivation

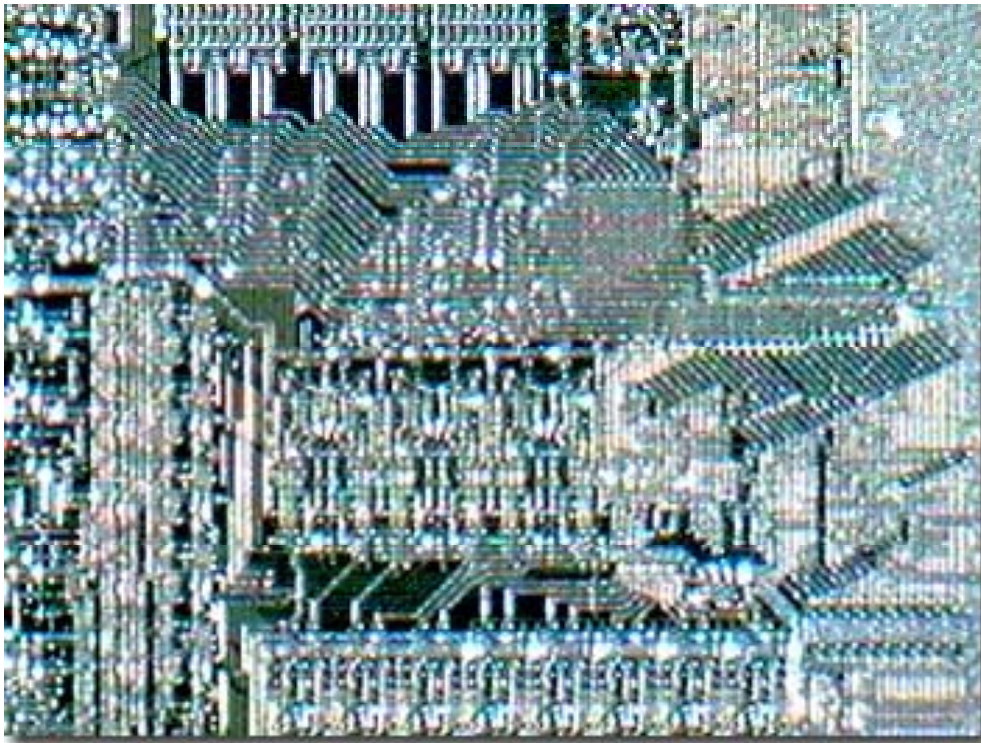
## Background:

- Since the 1960's, integrated circuits (ICs) have been growing in complexity by about a factor of two every two years ("Moore's Law").
- Since the 1980's, IC technology has increasingly been adapted to build micro sensors and actuators.

## Question:

- How does design methodology and manufacturing technology adapt to this increasing complexity and diversity?

# Circuit City



Integrated circuit,  
microscopic view



City landscape,  
macroscopic view

# Top-down and Bottom-up

## Integrated circuits:

- “Top-down” centralized design
- Monolithic batch fabrication

## Heterogeneous microsystems:

- Separate design & fabrication of functional units
- Precision assembly and customized packaging

## City:

- Decentralized planning and construction
- “Bottom-up” guided growth

# Growth and Self-assembly

- Growth processes (crystals, organisms, cities, etc.) tend to be
  - distributed
  - massively parallel
  - stochastic
  - guided by a utility function
- Can we apply this approach to microsystems?
  - Self-assembly (from nano to milli scales)



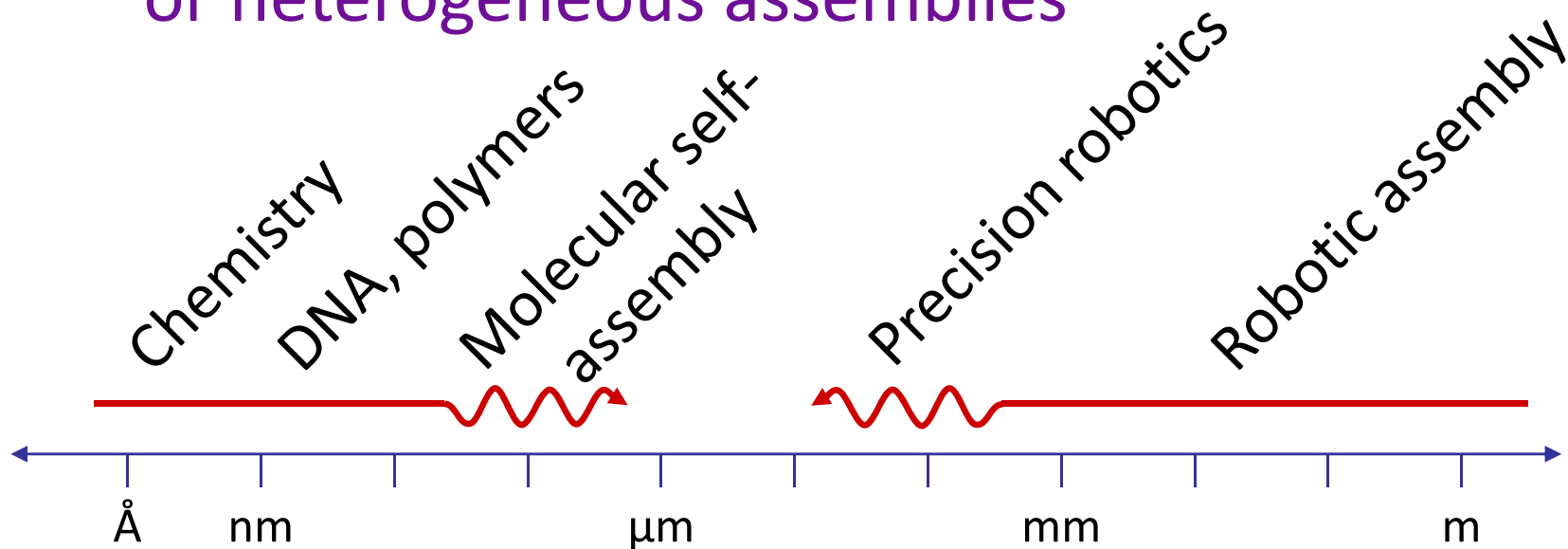
# Definition

## Self-assembly:

The autonomous and spontaneous organization of components into patterns or structures.

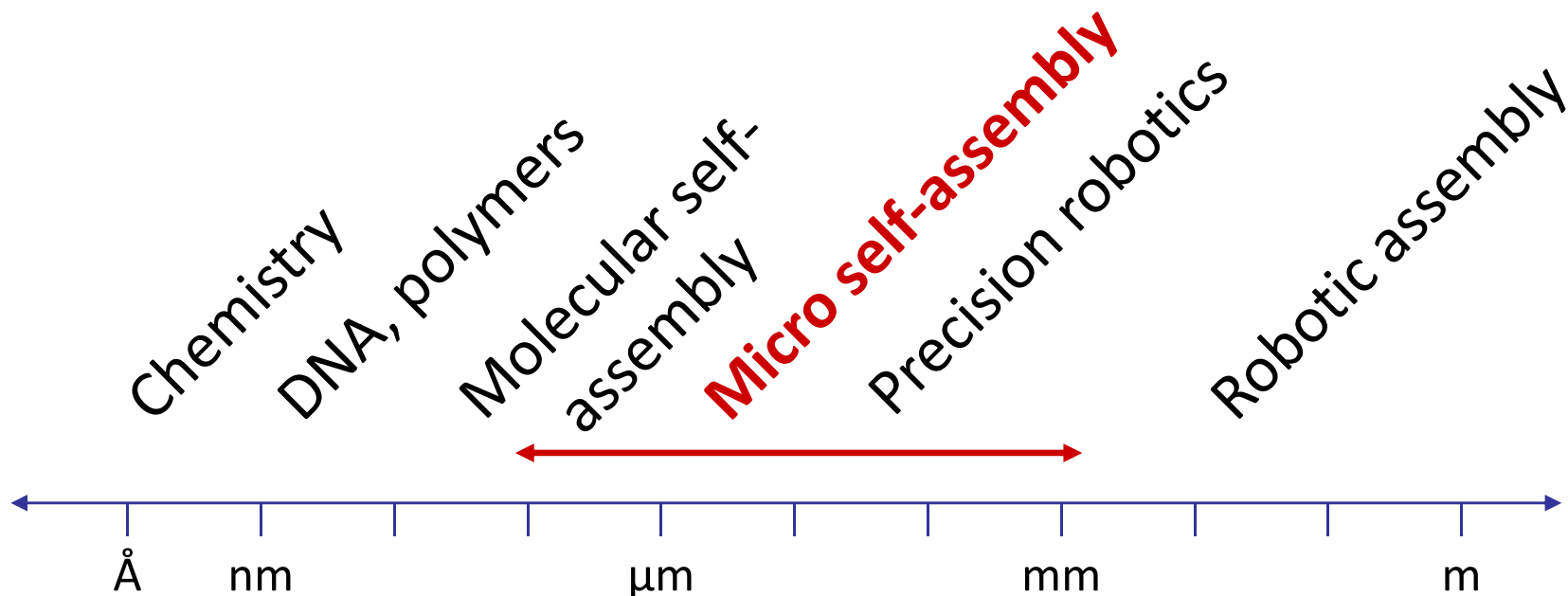
# Self-assembly Across Scales

- Currently, “no-man’s-land” for engineered assembly in the micrometer range
  - Conventional robots get very expensive
  - Chemical synthesis cannot produce non-periodic or heterogeneous assemblies



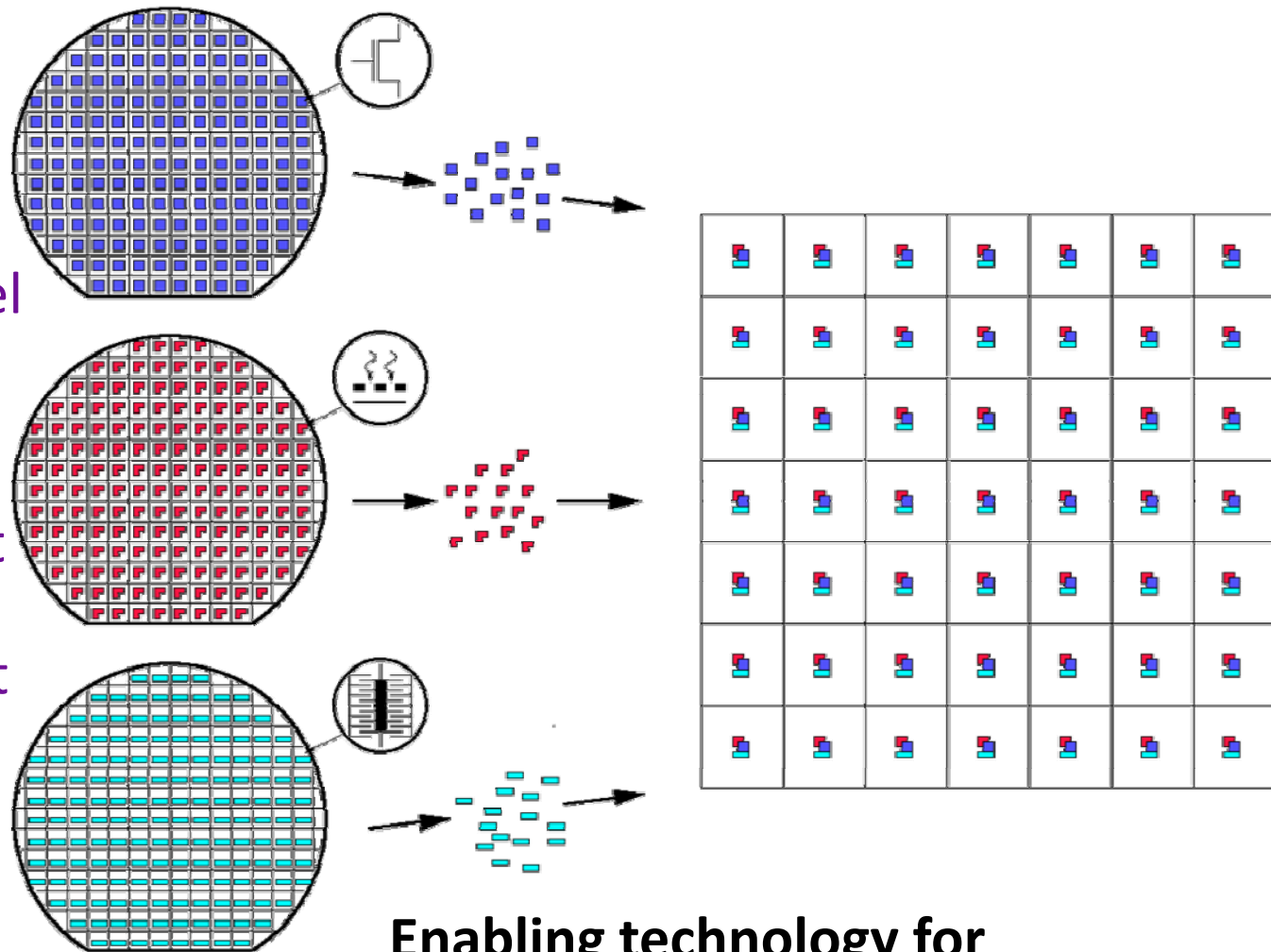
# Self-assembly Across Scales

- Goals:
  - High volume, flexible manufacturing
  - Complex heterogeneous microsystem integration



# Micro Self-assembly

- Very large numbers of very small components
- Independent parallel fabrication of components
- Fabrication at high density, assembly at lower density
- Hybrid systems built from standard components



**Enabling technology for  
complex integrated microsystems**

# Programmed Self-assembly

## **Self-assembly:**

autonomous and spontaneous organization of components into patterns or structures

- **Programmed self-assembly:**

self-assembly process with (spatial and temporal) control over binding mechanisms

- resulting structures can be adjusted on demand
- analogies: flexible robotic assembly; protein synthesis

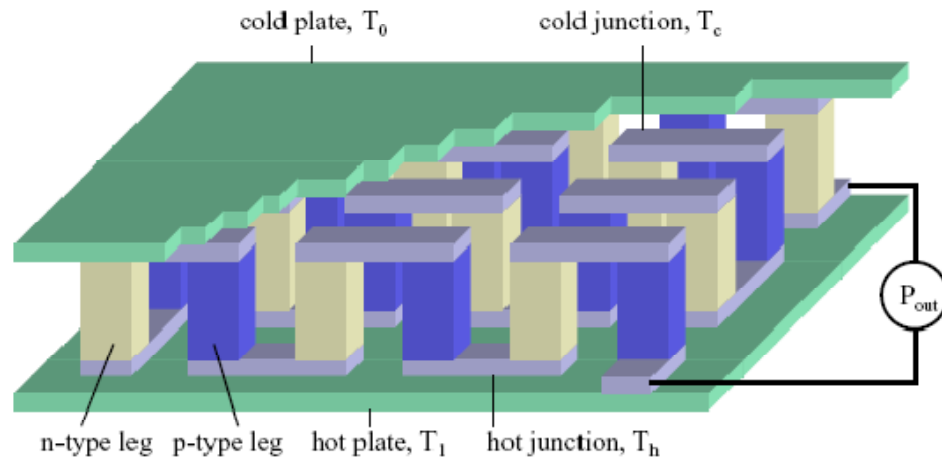
# Programmable Surface

- **An object whose surface properties can be controlled with good spatial and temporal resolution**
- **Crucial for programmed self-assembly**
- **Surface properties:**
  - Friction
  - Surface forces
  - Hydrophobicity (surface tension, contact angle)
  - Biological properties (e.g., adhesion of proteins)
  - Optical properties (color, transmission of light)
  - ...

# Goals / Applications

## 1. Thermoelectric cooling of hot spots

Assembly of p/n materials in checkerboard pattern



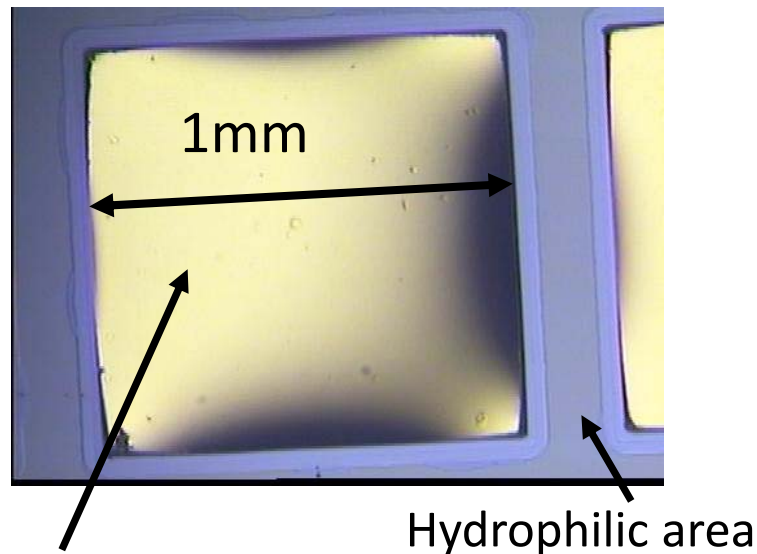
## 2. Extreme aspect ratio components

Tens of  $\mu\text{m}$  thin, mm's or cm's side length

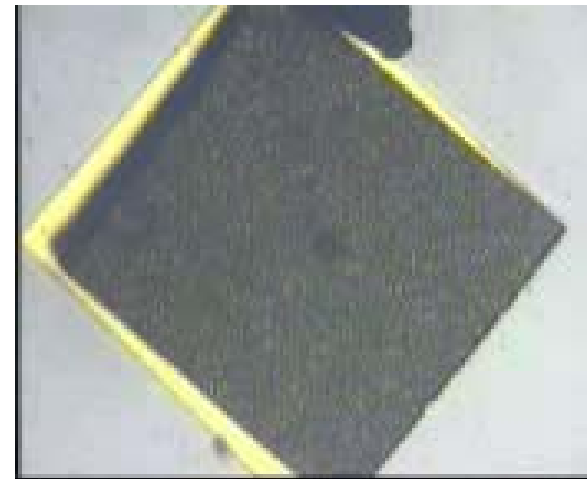
Ongoing joint work with Intel Corp. / DARPA

# Surface Tension Driven Self-assembly

- Dip coating forms adhesive droplet on hydrophobic areas
  - reduce friction
  - provide longer range capillary forces ( $\gg 1\mu\text{m}$ )
  - act as photo- or heat-polymerizable glue



Adhesive on hydrophobic area



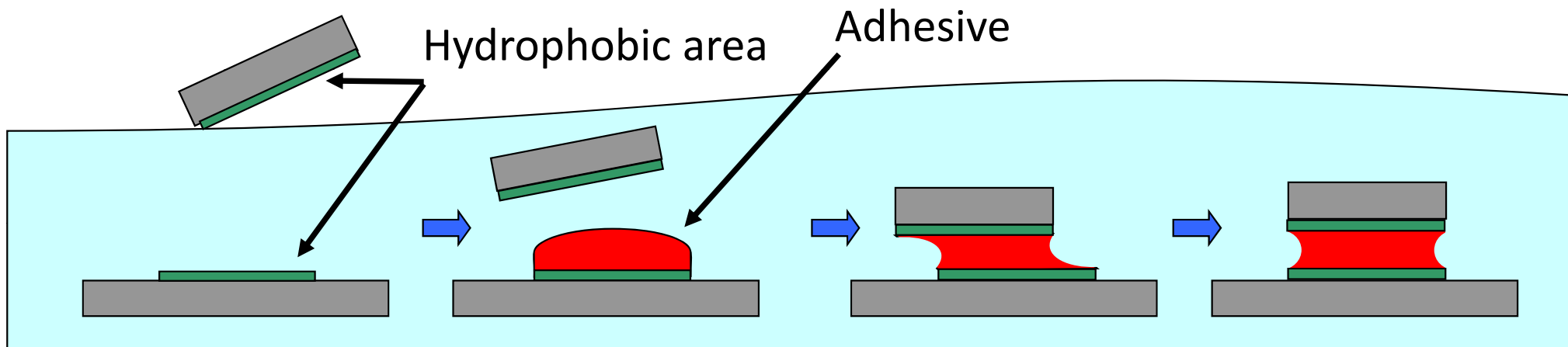
Video: X. Xiong '00



# Surface Tension Driven Self-assembly

Driving force for assembly: minimization of surface energy with hydrophobic-hydrophilic interfaces

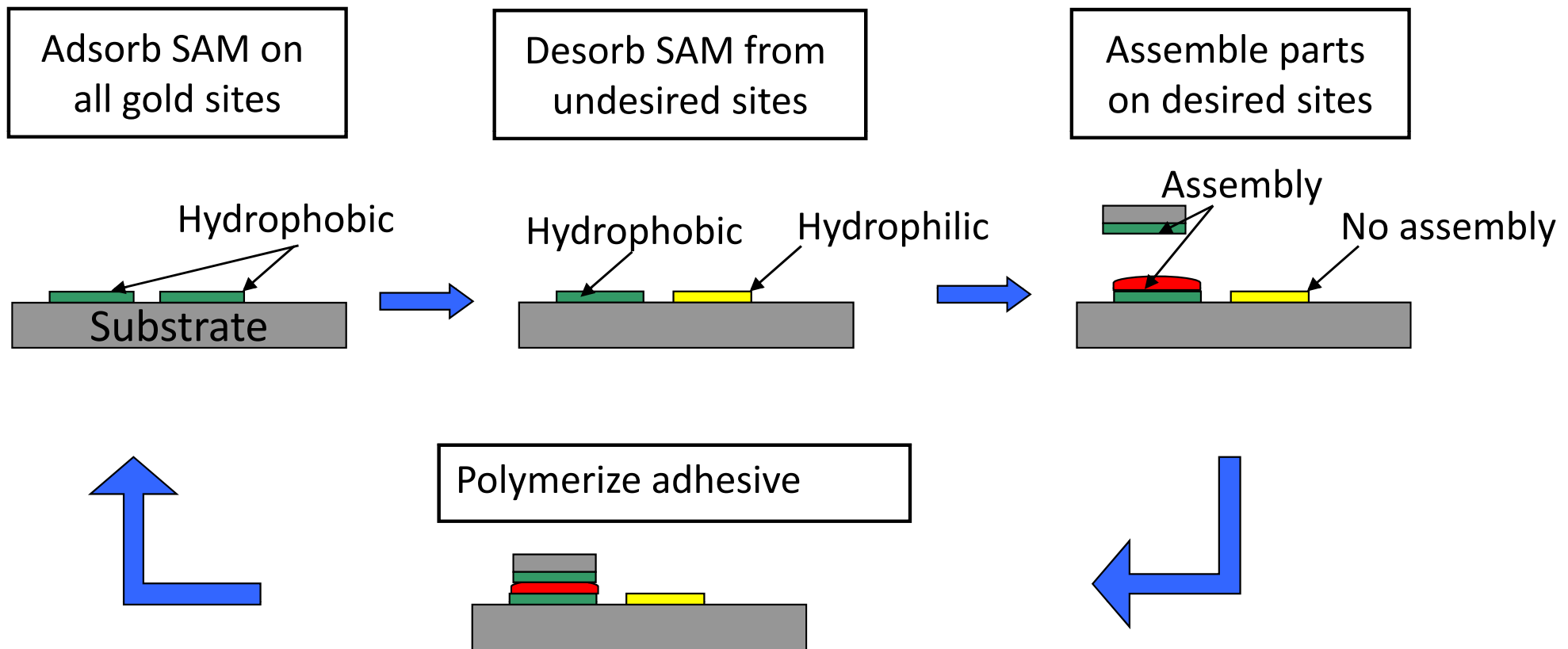
- Alkanethiol self-assembled monolayer (SAM) on Au forms hydrophobic surface
- Organic lubricant adhesive



[Srinivasan et al.'99, Whitesides et al.'90s]

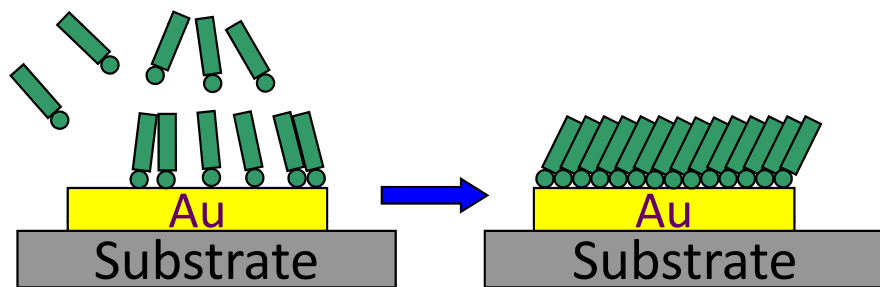
# Programmable Self-assembly

Organization of different parts onto desired locations



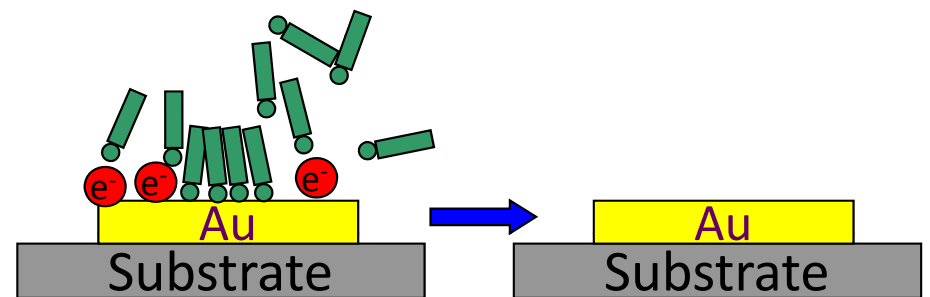
# Modulation of Surface Energies

Hydrophilic → Hydrophobic  
Adsorption of alkanethiol SAM



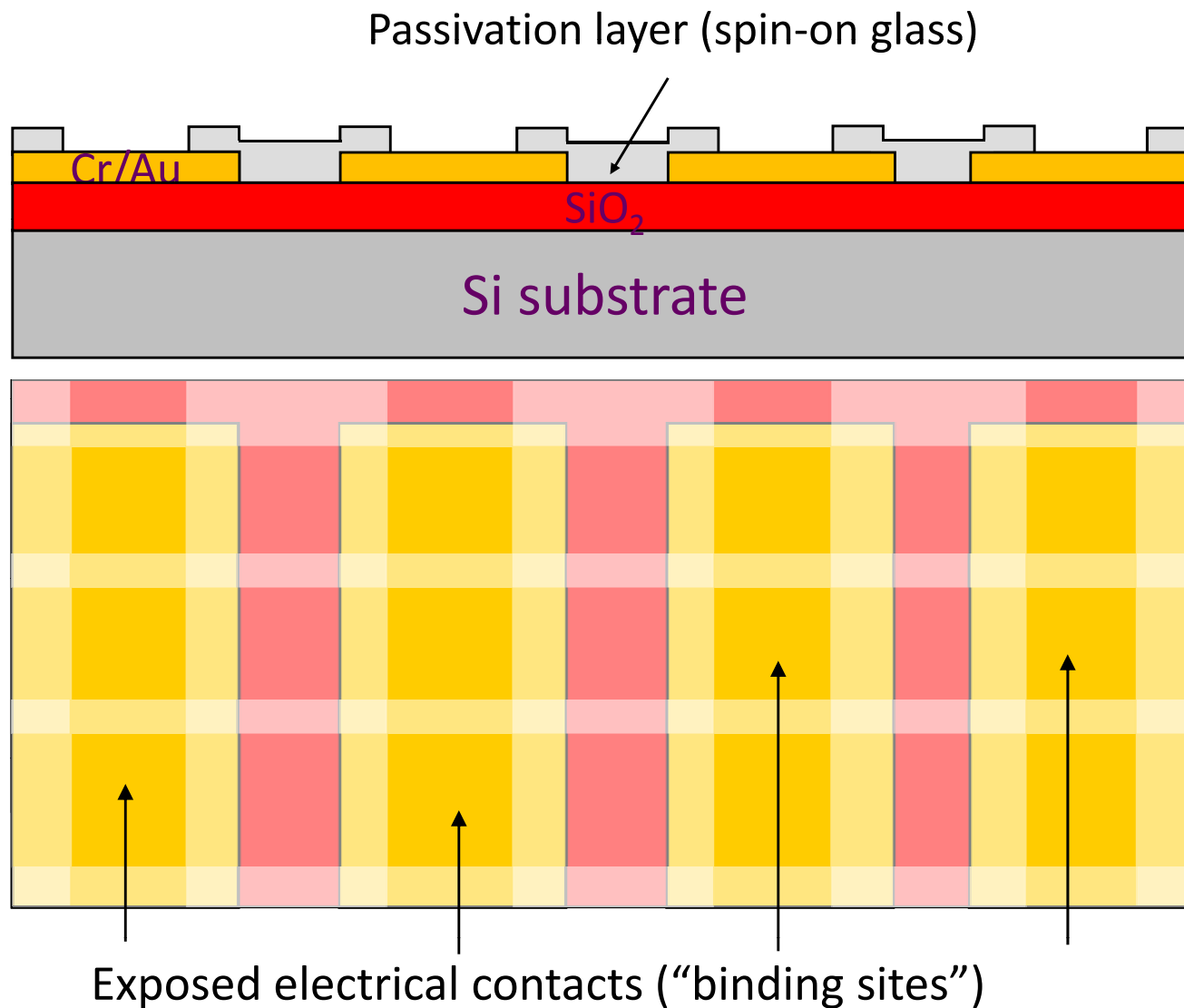
Adsorption is accomplished by soaking surfaces in ethanolic alkanethiol solution.

Hydrophobic → Hydrophilic  
Reductive desorption of SAM  
 $\text{CH}_3(\text{CH}_2)_n\text{S-Au} + e^- \rightarrow \text{CH}_3(\text{CH}_2)_n\text{S}^- + \text{Au}$



Desorption is accomplished by applying a negative voltage to the Au electrode.

# Fabrication of Substrate



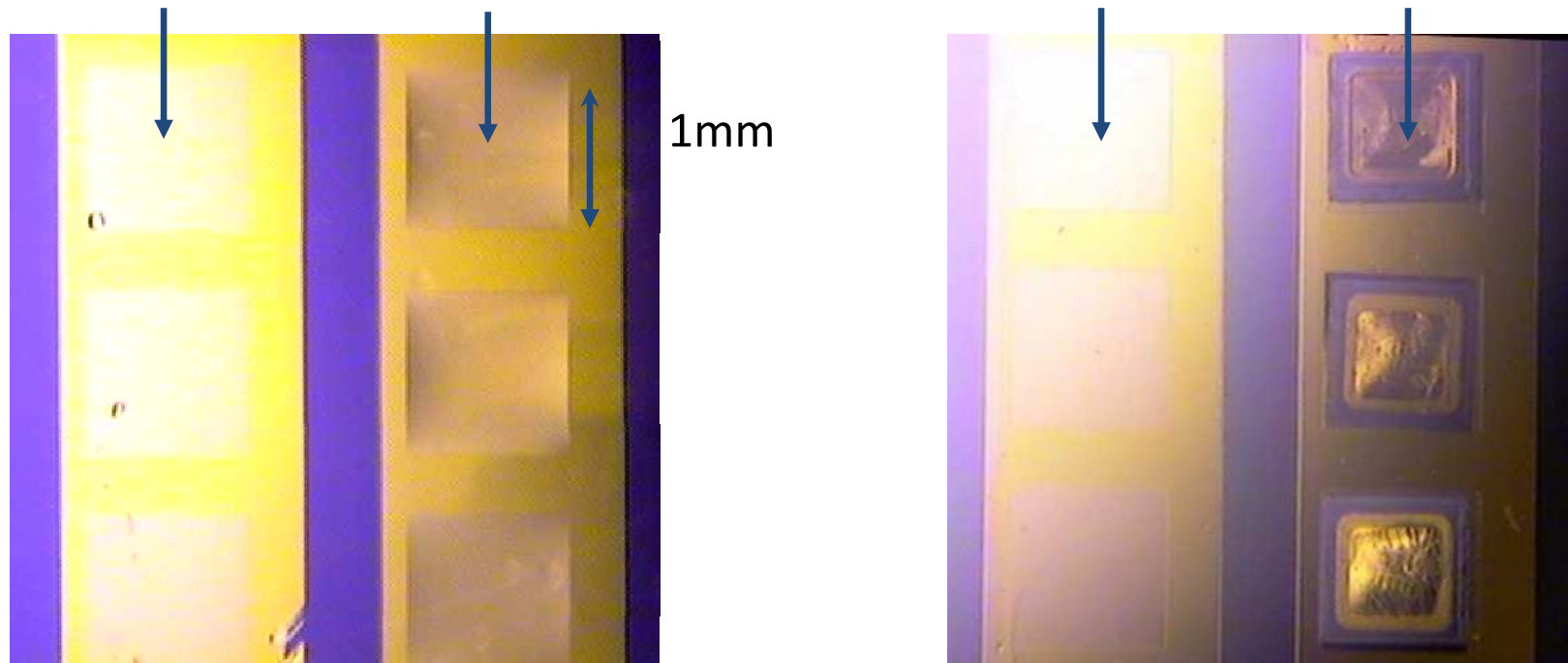
# SAM Desorption and First Assembly Batch

No adhesive on hydrophilic surfaces

Adhesive on hydrophobic surfaces

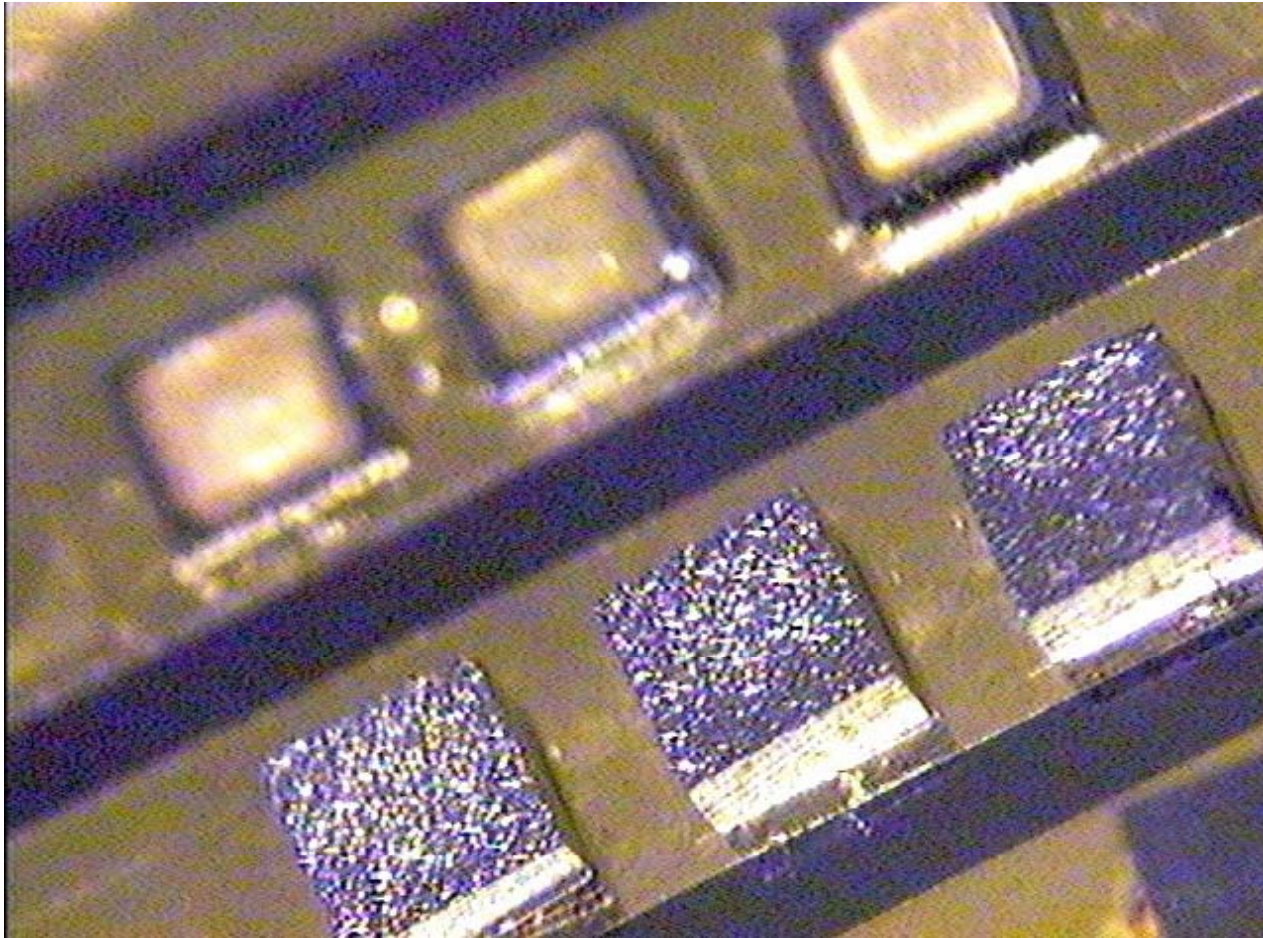
Free spot

Assembled part



SAM desorption from left column of sites only

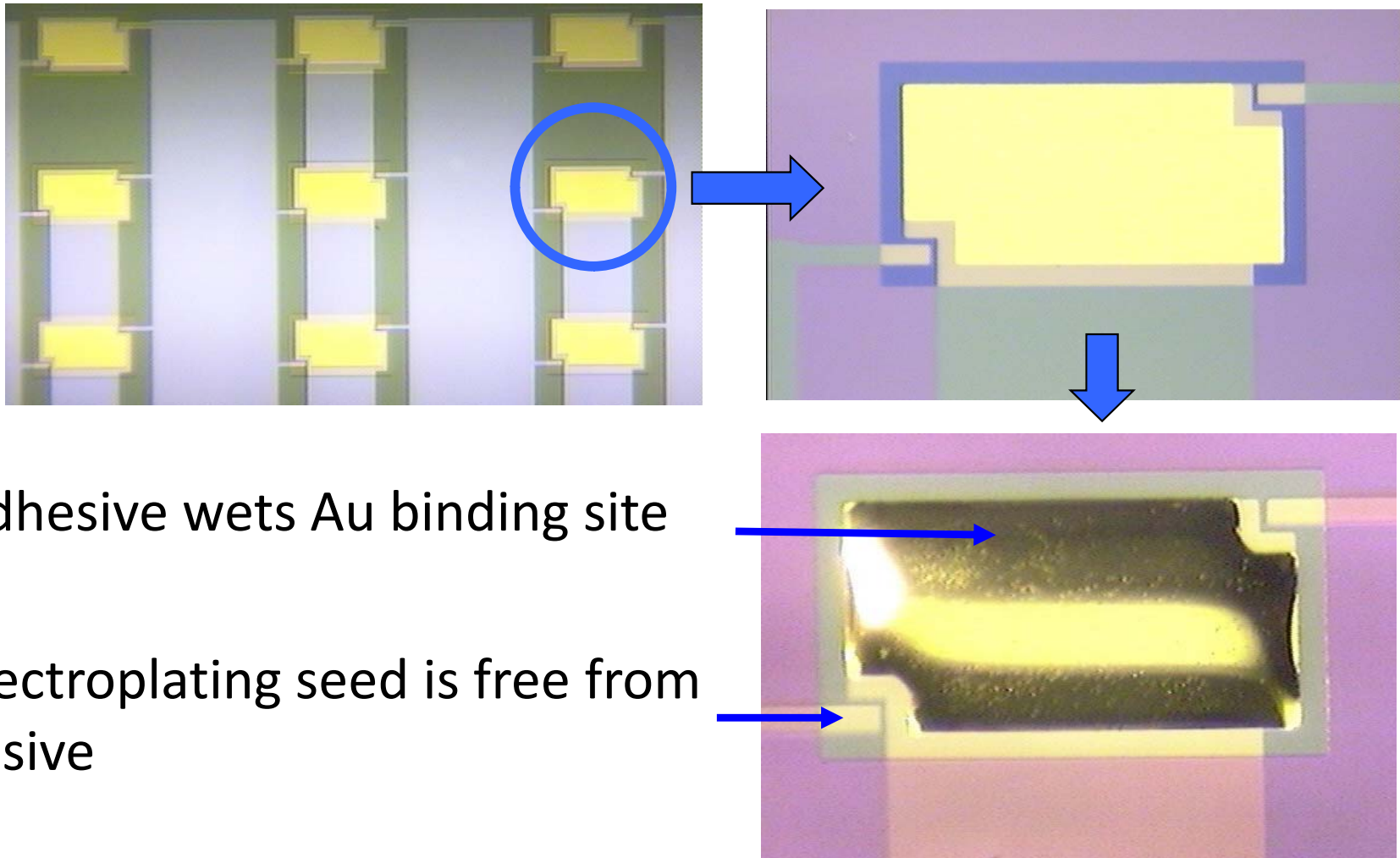
# Second Assembly Batch



[X. Xiong et al. *Transducers '01*, *JMEMS '03*]

# Adding Electrical Connectivity

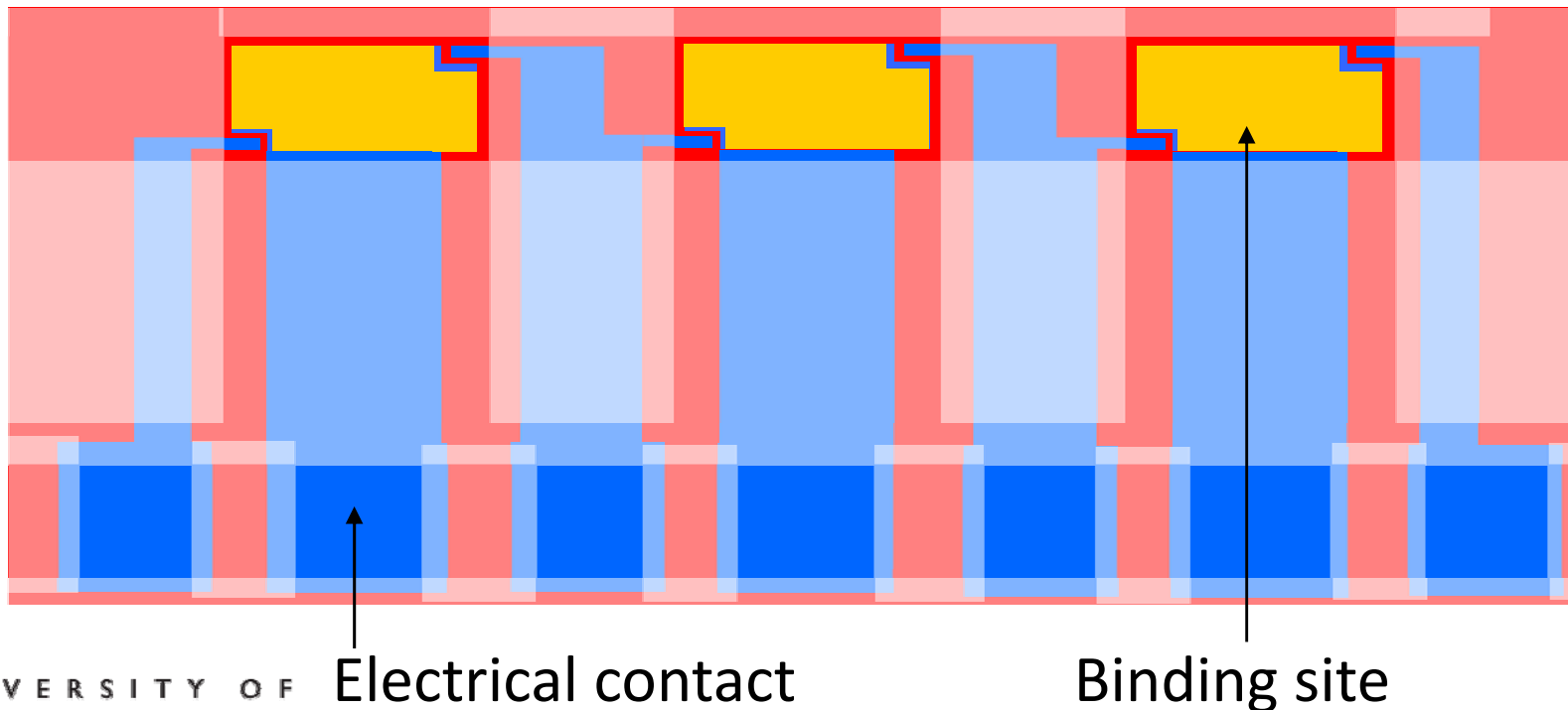
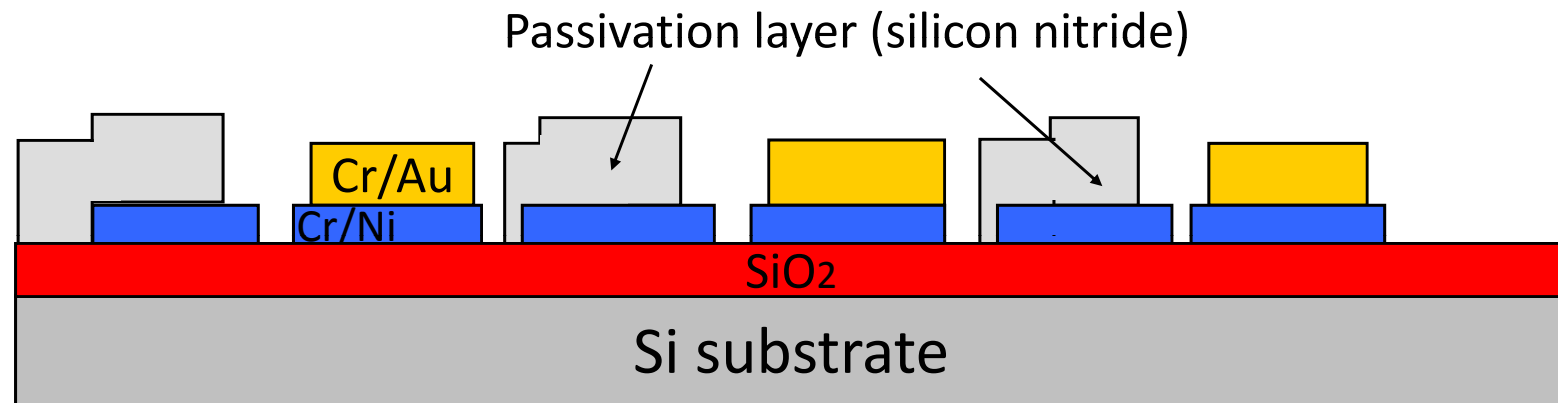
Top view of a fabricated substrate for LED assembly



Adhesive wets Au binding site

Ni electroplating seed is free from adhesive

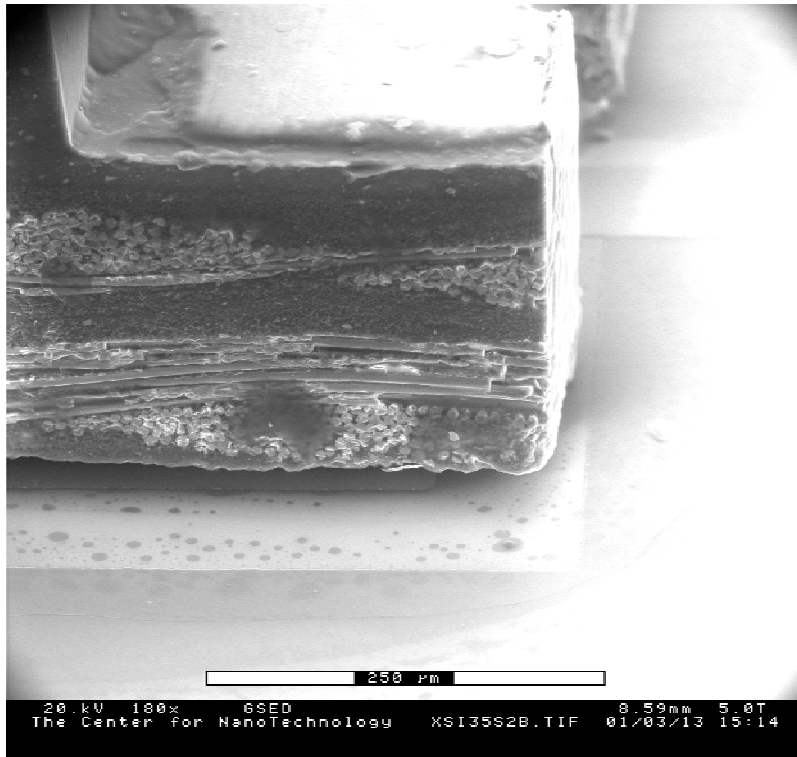
# Fabrication of the Substrate for LED Assembly



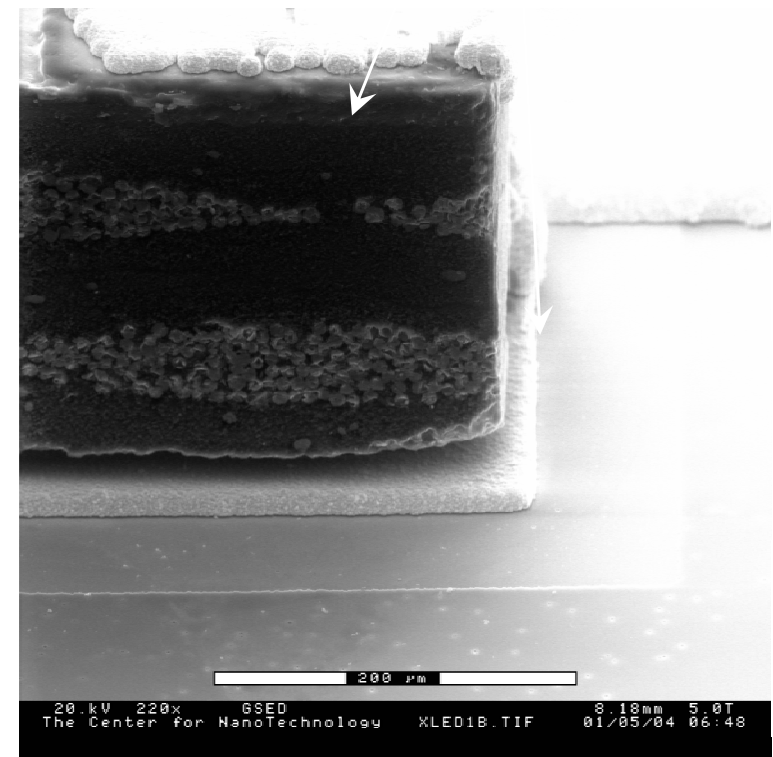


# Electrical Connection by Electroplating

Gap between an assembled LED and substrate is  $\sim 20\mu\text{m}$



Electrical connection established by plated solder

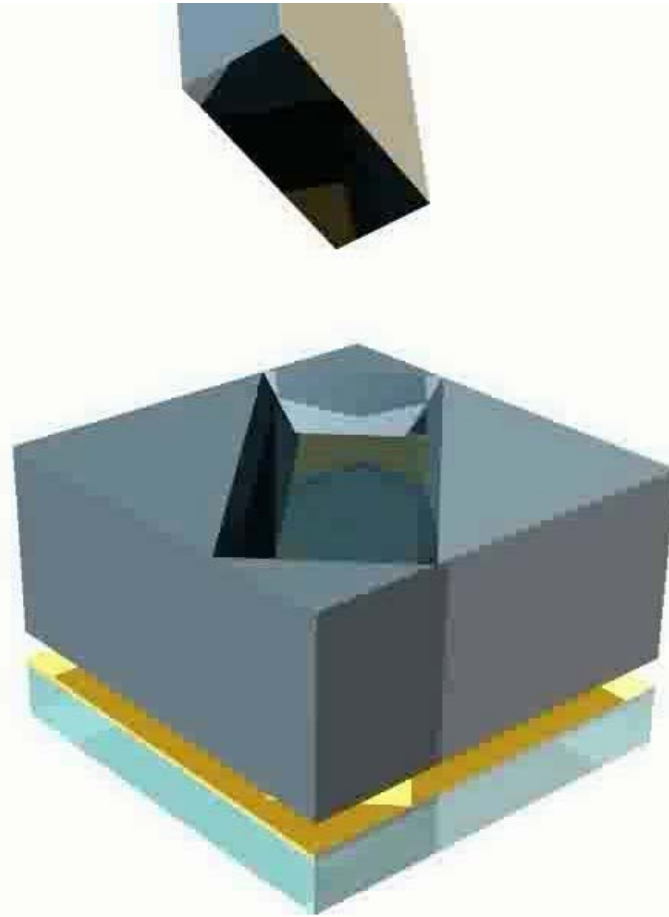


# Self-assembled LED with Electrical Connections

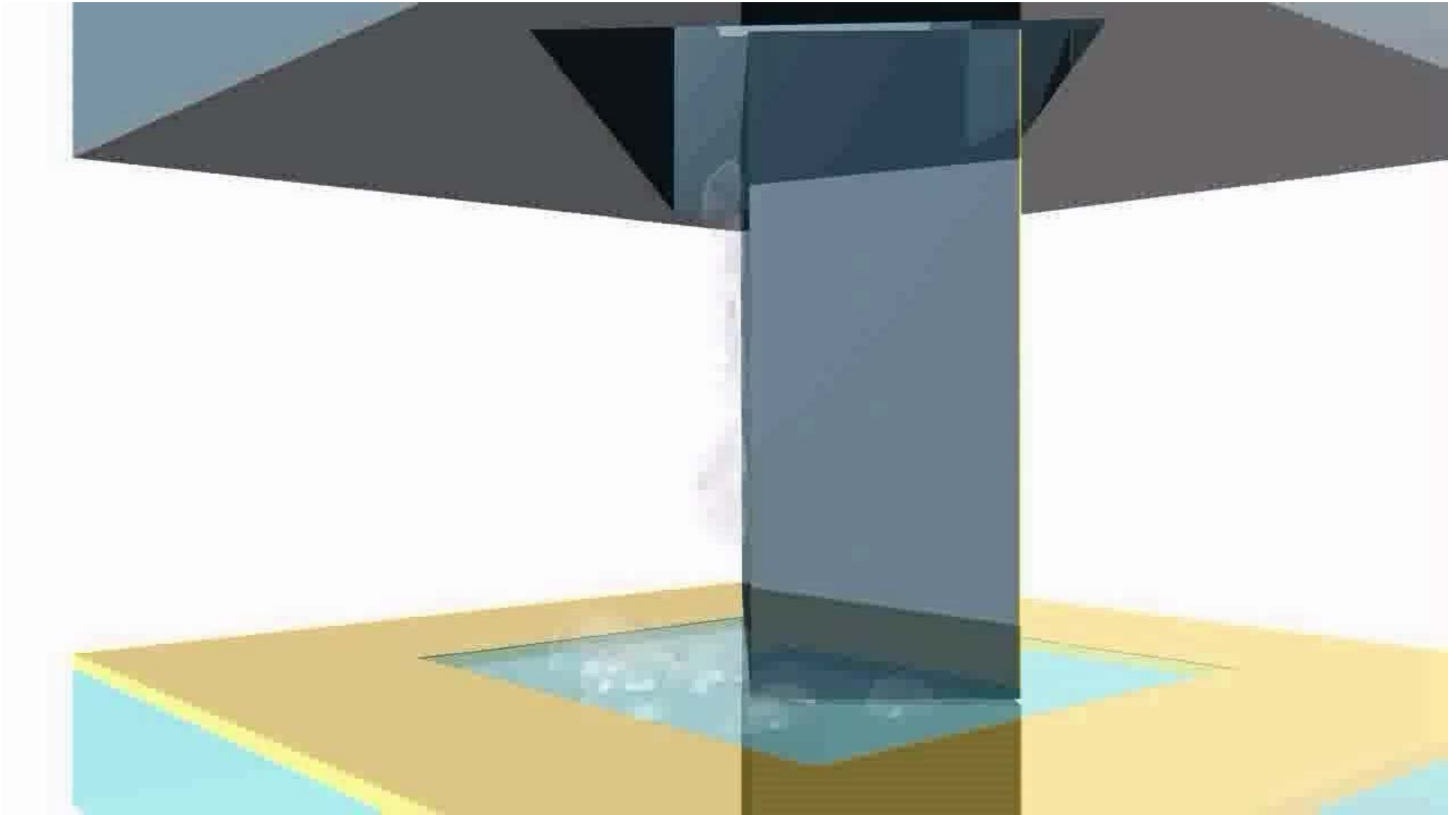


[X. Xiong et al., JMEMS '03]

# Templated Self-assembly

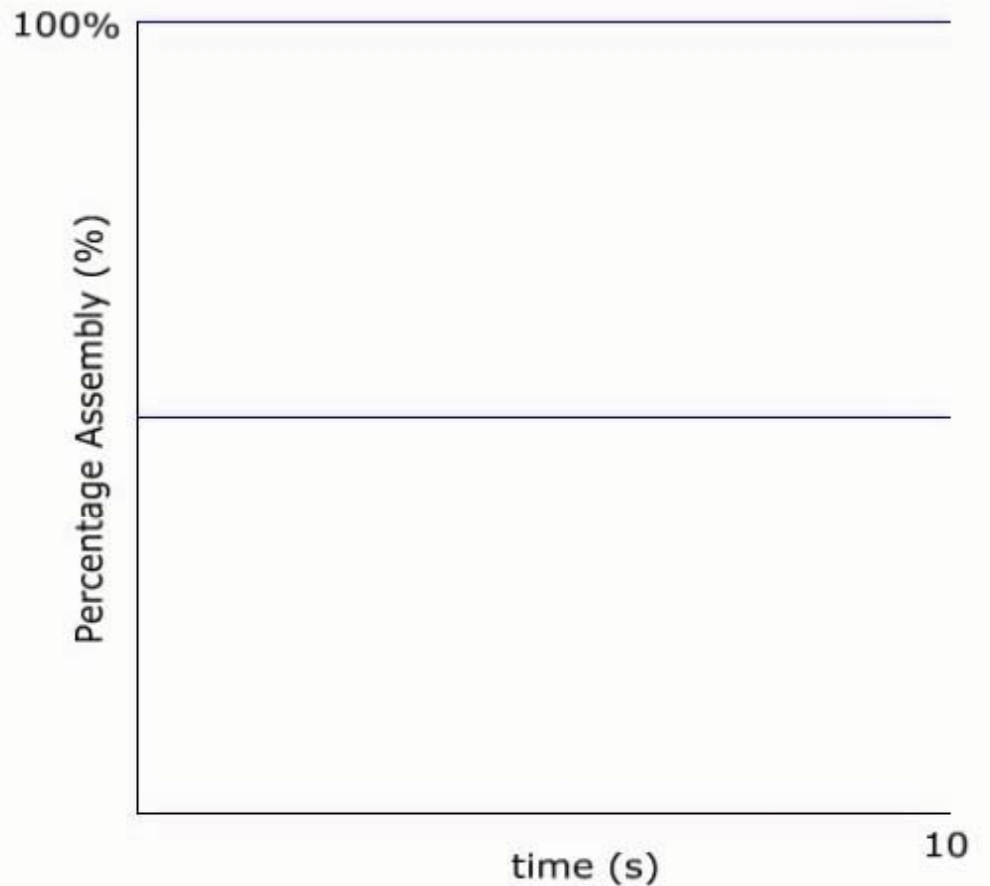
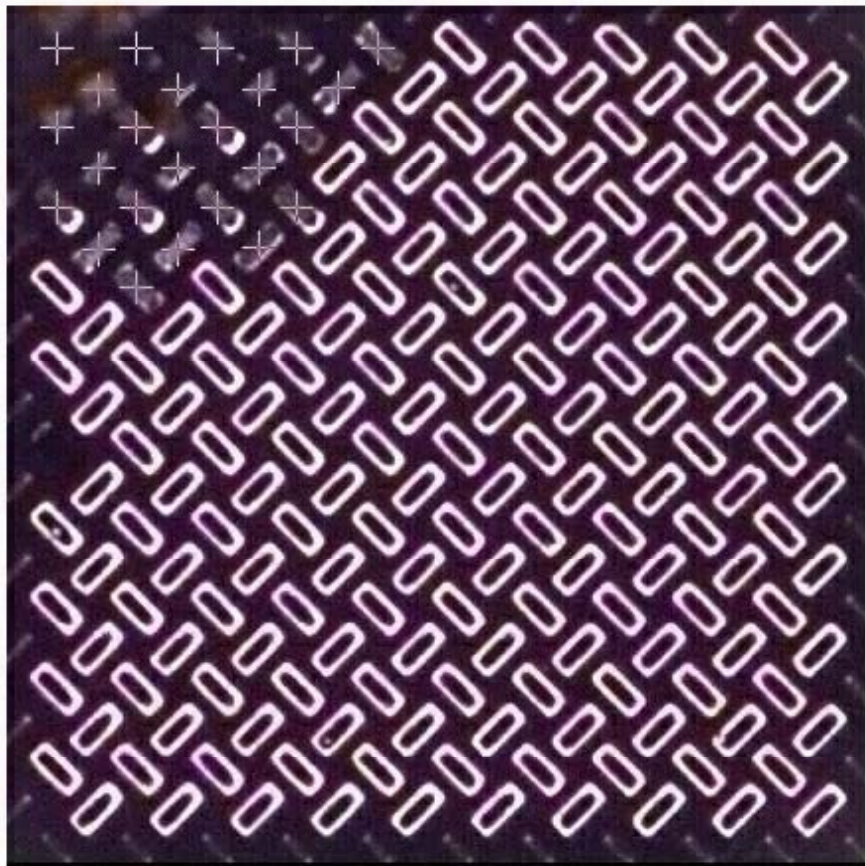


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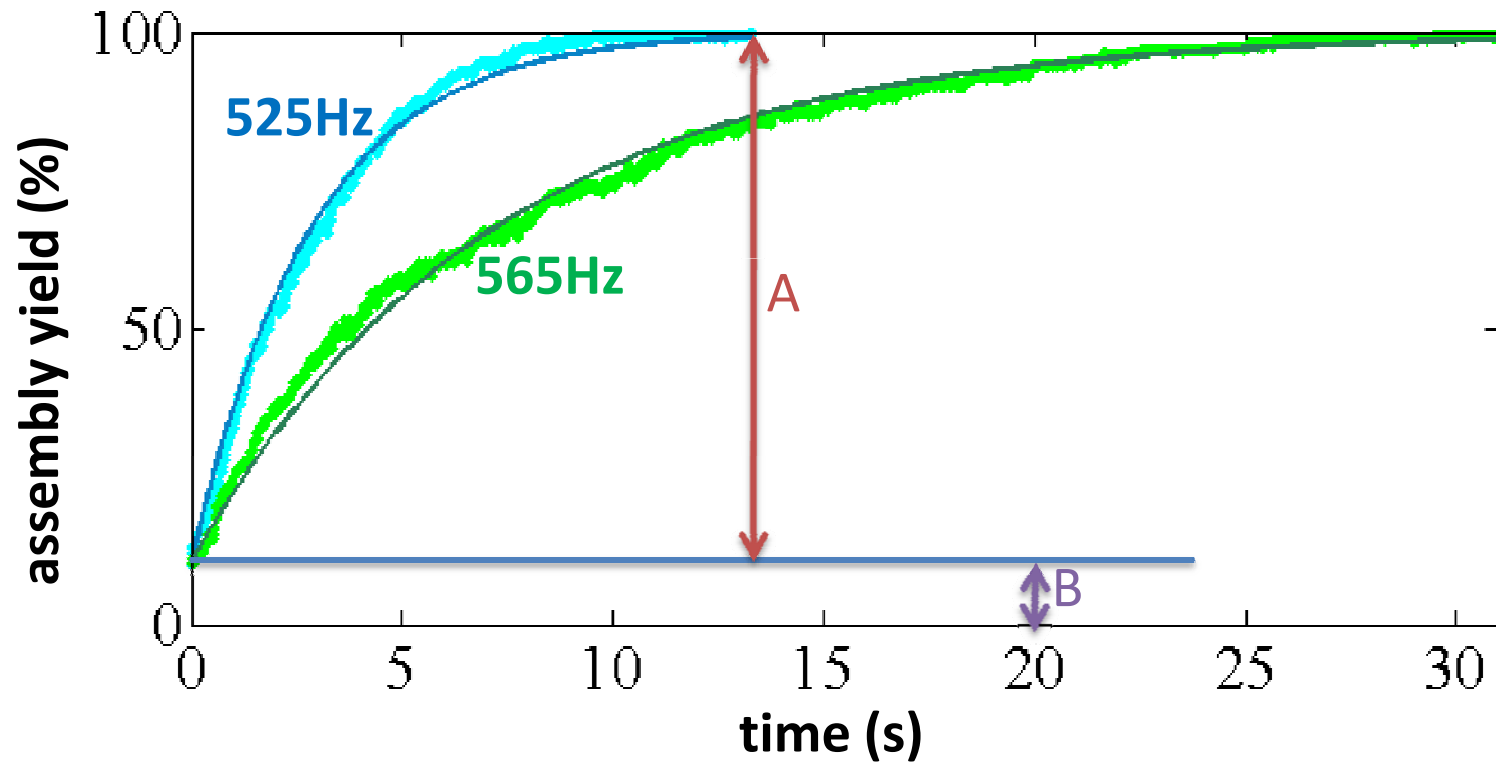


# Real-time Tracking of Self-assembly

aperture sites: 200; % excess parts: 50%;  
agitation frequency: 525Hz

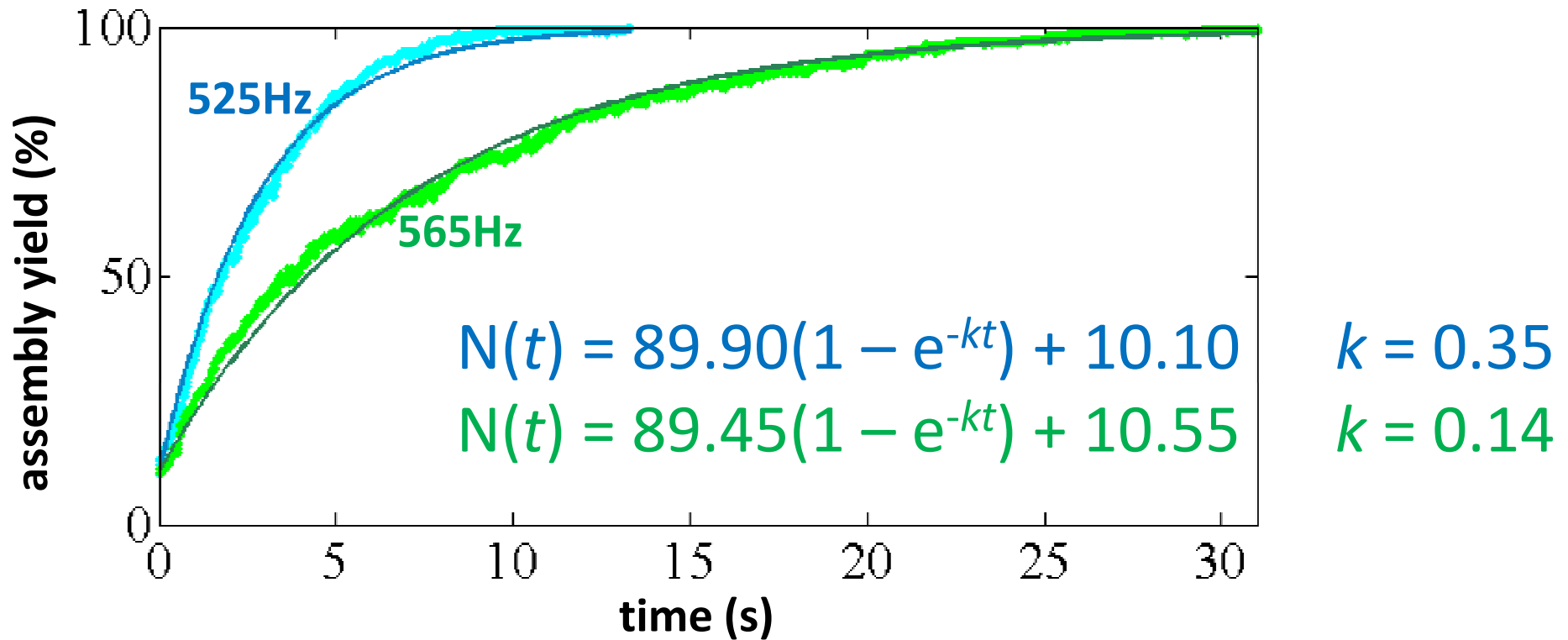


# Results: Assembly Kinetics



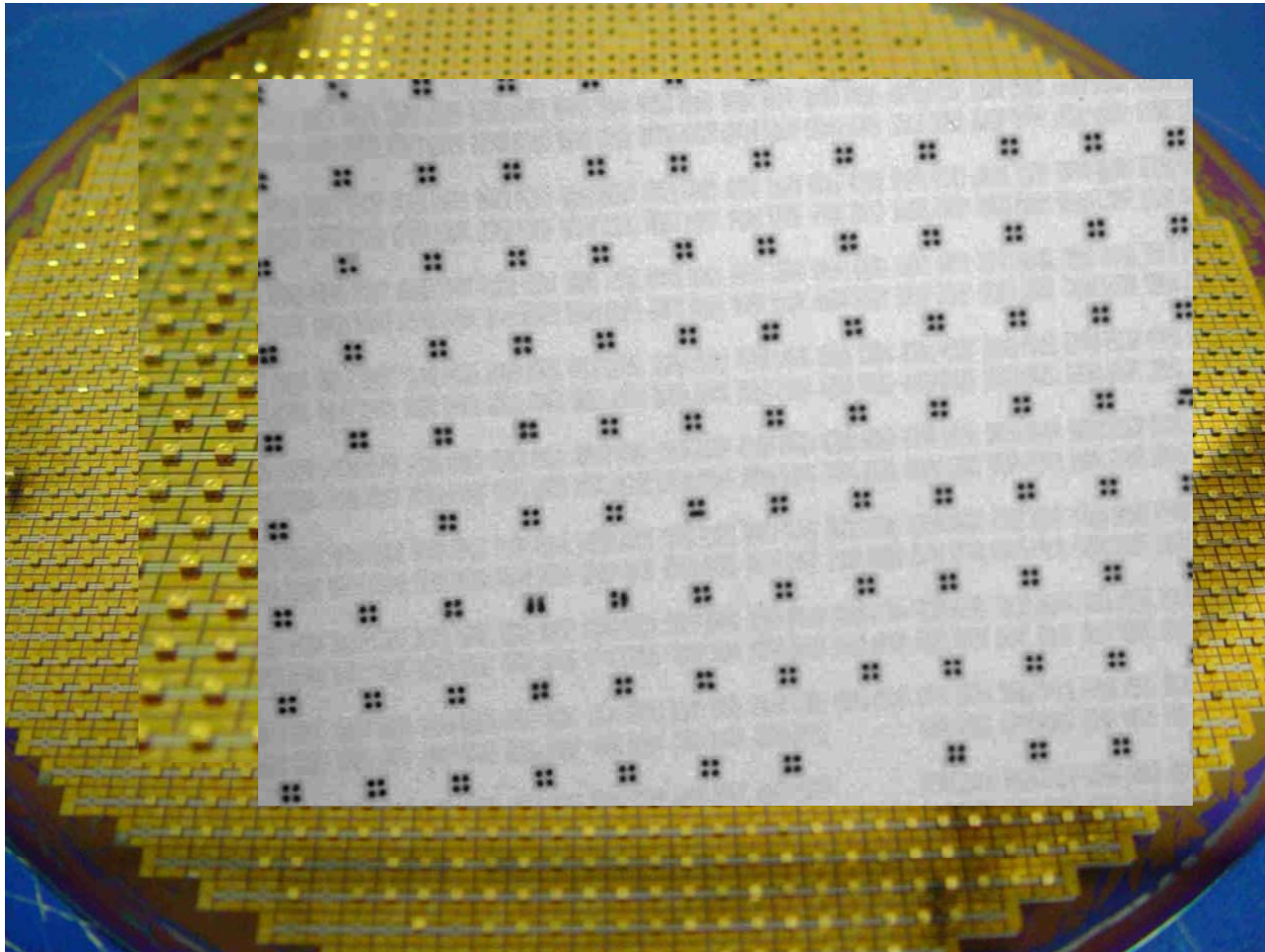
$$N(t) = A(1 - e^{-kt}) + B \quad A + B \leq 100\%$$

# Assembly Kinetics Model



$$N(t) = A(1 - e^{-kt}) + B \quad A + B \leq 100\%$$

# Assemblies with Shape Matching



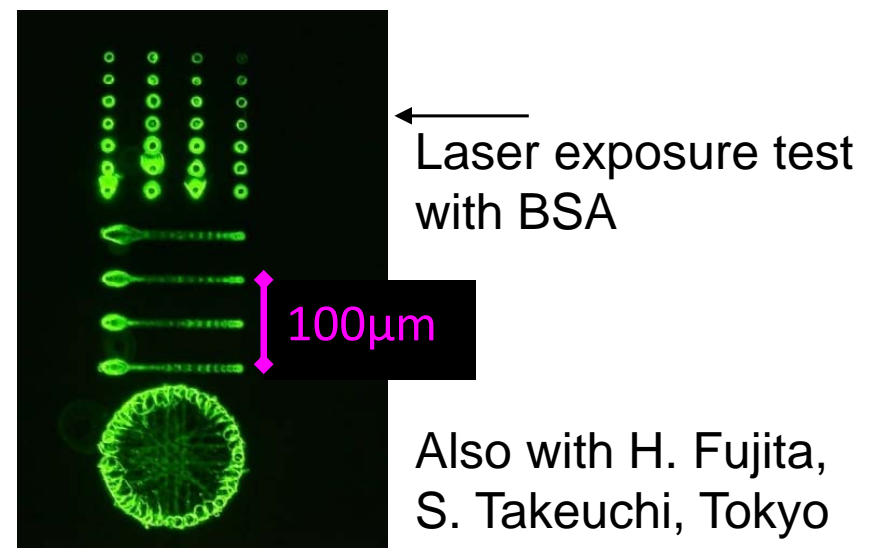
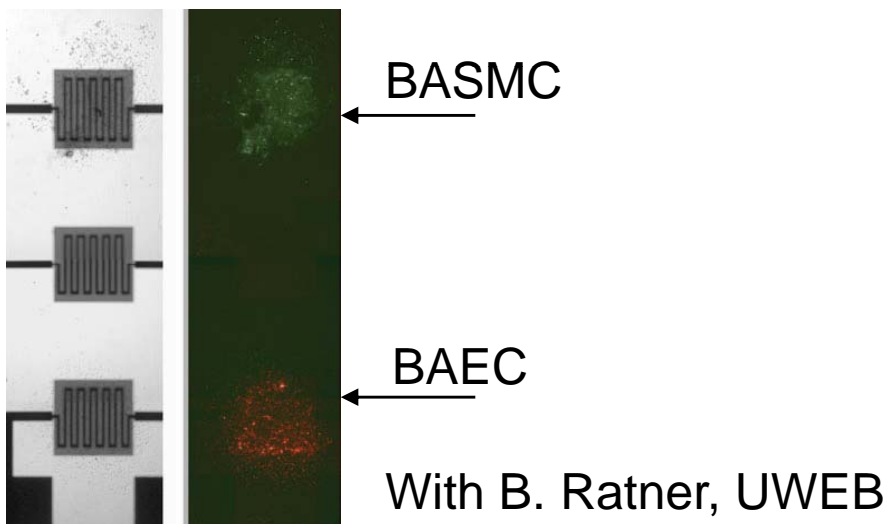
Self-assembly and gang bonding of chips on 8" wafer  
( collaboration with ASTAR IME, Singapore)



# Current / Future Work: Protein and Cell Arrays

## Programmable Surfaces for Proteins and Cells:

- Thermoresponsive polymer pNIPAM (poly N-isopropyl acrylamide) binds proteins and cells above 32°C.
- Thin film pNIPAM can be integrated with MEMS.
- Microheaters for protein and cell arrays.
- Programmable IR laser “protein printer.”

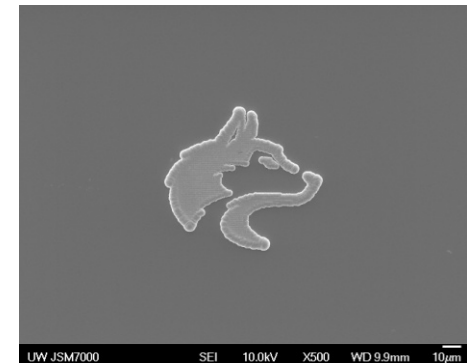
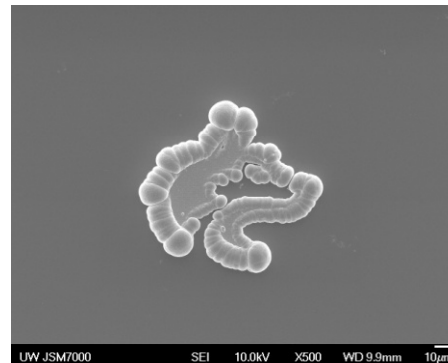


# Current / Future Work: Protein Guided Nanomanufacturing

## Orchestrated Structural Evolution (OSE):

- Use combinatorial biology to develop library of peptides.
- Peptides control nucleation, growth rate, and crystallinity of target inorganic materials.
- Place peptide patterns into appropriate aqueous electrolyte.
- Peptides can act as seeds in synthesis of heterogeneous, three-dimensional structures.
- Completely automated process from CAD design to optimized seed planting to growth of nano-structures

UW Husky pattern,  
automatically  
generated and  
grown with OSE  
(with D. Schwartz, UW)



— 10µm

# Conclusions

Tools for design, modeling, and manufacture of complex 2D and 3D self-assembled microsystems are becoming available.

They could lead to a paradigm shift in design and manufacture of complex micro and nano systems.

Effects of downscaling on assembly:

Meso



Micro

Volume forces



Surface forces

Deterministic



Stochastic

Serial



Parallel

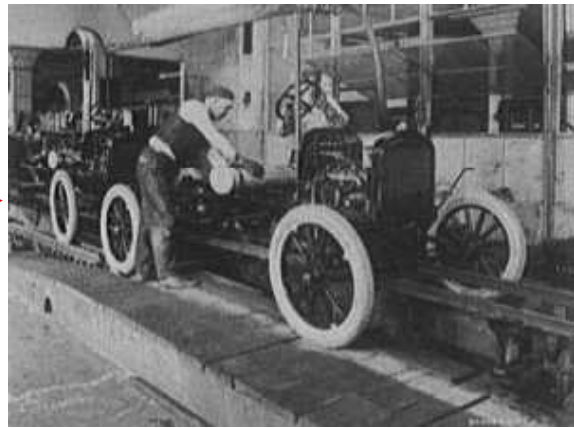
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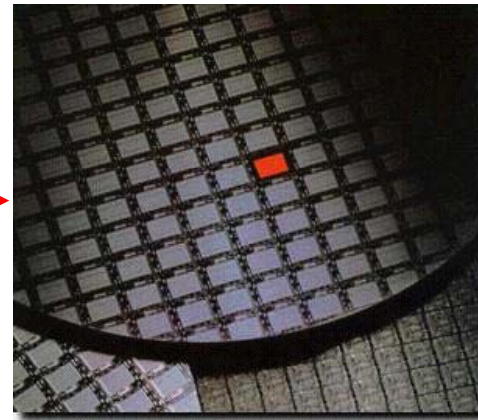
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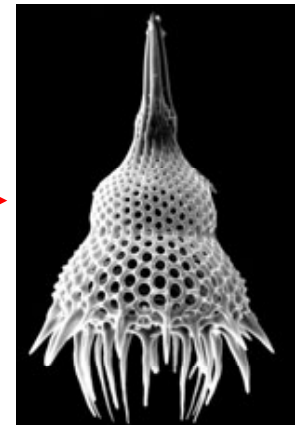
Manual labor: "0D"



Conveyor belt: "1D"



VLSI: "2D"



3D self-assembly in  
Nature:  
*Radiolarium l. maritalis*

# Acknowledgements

- S. Abassi, J. Fang, J. Hoo, K. Wang, X. Xiong (graduate students); J. Chang, J. Cheng, Y. Hanein, S. Park, A. Shastry, X. Xiong (postdocs), UW MEMS Laboratory
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