

Final Report

Project Title: Characterizing Spotted Owl Habitat Using LiDAR

Cooperative Agreement: P17AC01530

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Introduction

This report summarizes the results of the University of Washington's (UW) analysis regarding the characterization of spotted owl habitat use through the application of light detection and ranging (lidar) data. The methodology and results presented were conducted following coordination and consultation with Yosemite National Park and the Point Reyes Bird Observatory to integrate the methodology and results reported here to characterize CSO habitat in burned and unburned areas, before and after the 2013 Rim Fire. The UW was responsible for achieving the following deliverables, which are described herein:

1. produce lidar metrics from the 2013 Rim Fire lidar acquisition, as described below;
2. acquire Landsat images to develop Normalized Difference Vegetation and Normalized Burn Ratio Indices and incorporating these data into analyses to characterize CSO habitat;
3. conduct niche overlap modeling to identify canopy metrics relevant to characterizing CSO habitat in Yosemite; and
4. develop a raster layer of potential CSO habitat.

This report details the methods and results of to produce these deliverables. Discussion of the interpretation of these results will be incorporated into the report for the larger study being conducted by Yosemite.

Statement of Completeness

This final report details the methodology and work products that were completed per the agreement. All of the objectives of the agreement were completed as required and as detailed below within the allocated budget.

Methodology

Data Description, Preparation, and Analysis

This comparative analysis of the available and used habitat within the range of California Spotted Owl, *Strix occidentalis* (CSO) in Yosemite National Park (Yosemite) included examining the portion of the 2013 Rim Fire area in Yosemite to the unburned portion of the range in Yosemite, pre and post fire, using remotely sensed data. The range of the CSO in Yosemite is the land area identified as Mixed Conifer Forest according to the California Wildlife Habitat Relationship System¹. For the purposes of the analytical steps included below, the niche overlap modeling was conducted on all locations within five

¹ <https://www.wildlife.ca.gov/data/cwhr>

km of any reported owl location (i.e. nesting and/or roosting) and the mapping of potential habitat was conducted over the entire Park boundary.

Lidar Data

Following the conclusion of the Rim fire on October 24, 2013, an airborne lidar acquisition was conducted over the burn area and an additional 2km buffer in November 2013. The data were collected by the National Center for Airborne Laser Mapping (NCALM), University of Houston, with an Optech Gemini Airborne Laser Mapper. The data were acquired at four returns per pulse, with a resolution of 12 points per meter squared; a scan angel of $\pm 14^\circ$; and a minimum 50% overlap in flight lines. Next, the lidar data were processed with the US Forest Service's Fusion software package (Mcgaughey, 2018) to create the canopy structure, canopy intensity (as a proxy for burn severity), as well as the topographic metrics that are averaged to a 90m pixel size, which were normalized to ensure all laser returns were of a height above the digital terrain model and provided in raster format, which also included the canopy area and large gap metrics.

Landsat Data

Landsat data were downloaded to provide metrics for the entire range of the CSO in Yosemite for pre and post fire, 2013 and 2014 as the lidar data only captured the post-fire portion of range affected by the Rim Fire. The Landsat metrics that were included were; canopy cover and height, topography (aspect, elevation, and slope), and relative differenced normalized burn ratio (corresponding to the lidar intensity). The Landsat data was also acquired to calculate the normalized difference of vegetation index (NDVI) for 2013 and 2014, which cannot be measured with airborne lidar data exclusively. All of the Landsat data were downloaded from the USGS Earth Explorer website² at a resolution of 90 meter in raster format.

Analysis

As the presence of California Spotted Owls are correlated with the cover of tall trees (North et al., 2017), the mapping of available and used nesting habitat, pre and post fire, was evaluated following the methods of North et al. 2017 by applying niche overlap modeling for each of the canopy structure, topographic, Relative differenced Normalized Burn Ratio (RdNBR), and Normalized Difference in Vegetation Index (NDVI) for 2013 and 2014 metrics within the occupied nest (diameter=112.8m), associated core areas (diameter=700m), and the range outside of the core areas. First, the Landsat and lidar-based metrics were brought into ESRI's ArcMap, Version 10.3.1³ and visually inspected for accuracy prior to initiating the analysis in R-Studio, Version 1.1.419. Next, each of the Landsat and lidar-based metrics was projected to UTM, Zone 10N aligned, and clipped to the study area. After the values of each metric were added to new a data frame, niche overlap modeling was conducted for all the lidar-based and eight Landsat-based metrics (Table 1) to aid in the selection of suitable metrics. Niche overlap measures the similarity of two distributions, as a value between 0 and 1, 0 being no similarity, 1 being complete similarity. In this scenario we compared the distribution of known used owl habitat with available habitat which was defined as the whole landscape within 5km of any nest. This range was used to excluded landscape that is not available (i.e. different ecotype, etc.) and keep the focus on areas that owls had real potential to access. In our case a lower niche overlap value indicates the used habitat is different from the available (or that the owls exhibit a preference with regard to this metric) and that it might be a good metric to indicate owl habitat. The metrics selected for the lidar and Landsat based metrics are highlighted in blue in Table 1; the selected metrics included canopy area and height metrics

² <https://earthexplorer.usgs.gov/>

³ ESRI software version 2.2: <https://pro.arcgis.com/en/pro-app/>

as well as burn severity, NDVI, slope, aspect and elevation. A cold-air pooling layer acquired from Dr. Jessica Lundquist, University of Washington, was analyzed with the niche-overlap modeling; however, no correlation with used nesting locations was observed. The cold-air pooling layer was a coarser resolution than the lidar or Landsat derived metrics (as it only indicated an area as exhibit pooling, some pooling, or no pooling), and the determination was made to exclude this variable from further analysis (it is not included in Table 1).

Following the niche-overlap modeling, the mean values of the nine nesting locations in the Rim fire footprint of Yosemite for each of the selected metrics was applied to conservatively identify “available” habitat. For each metric, available habitat was identified through a neighboring window analysis in R-studio. This analysis identified a 30mx30m pixel as suitable habitat (in a Boolean fashion) if its associated circular window ($r = 700\text{m}$), had a mean value above the 10th percentile and below the 90th percentile of the distribution for mean values of observed nests, for each of the selected metrics. The only selected metric where this methodology was not applied was the percent canopy area in the height class of greater than 48m. For this metric, a pixel was considered suitable as long as its value was above the 10th percentile alone. Raster layers were created for each selected metric that delineated available and used nesting habitat as described, and these layers were intersected (using a ‘logical and’ operation) to identify areas that have similar structure as known habitat for the range of CSO in Yosemite in the burned and unburned area. In order to be identified as potential available habitat, the location for each of the metrics had to be mapped as available.

Results

The results of the niche overlap modeling for the selected metrics by distance away from the nests for the lidar and Landsat based metrics are in Figures 1 and 2, respectively. Violin plots were created to display the frequency of the range of values for the selected lidar and Landsat based metrics for the nine nesting locations in the Rim fire portion of Yosemite compared to 10,000 randomly selected ‘nest windows’ identified as “available”, Figure 3. Finally, a map layer of the potential available habitat was created, which may be viewed in ArcMap or R-studio.

Deliverables

1. The 2013 and 2014 Landsat image data was provided to Lynn Schofield in October 2018 via a 1TB external harddrive via standard mail.
2. The lidar metrics and associated raster products produced as a result of the analyses as described above are available for download at the following **dropbox.com location:** <https://www.dropbox.com/sh/asbimixh6n6pfwa/AACiWVuqW28Slxacdnb-iAq6a?dl=0>
3. The niche overlay modeling decay curves are provided in Figures 1 and 2, and the violin plot of nesting locations compared to randomly selected locations within the potential available habitat are depicted in Figure 3.

Literature Cited

Mcgaughey, R.J., 2018. FUSION / LDV : Software for LIDAR Data Analysis and Visualization.

North, M.P., Kane, J.T., Kane, V.R., Asner, G.P., Berigan, W., Churchill, D.J., Conway, S., Gutiérrez, R.J., Jeronimo, S., Keane, J., Koltunov, A., Mark, T., Moskal, M., Munton, T., Peery, Z., Ramirez, C., Sollmann, R., White, A.M., Whitmore, S., 2017. Cover of tall trees best predicts California spotted owl habitat. For. Ecol. Manage. 405, 166–178. <https://doi.org/10.1016/j.foreco.2017.09.019>

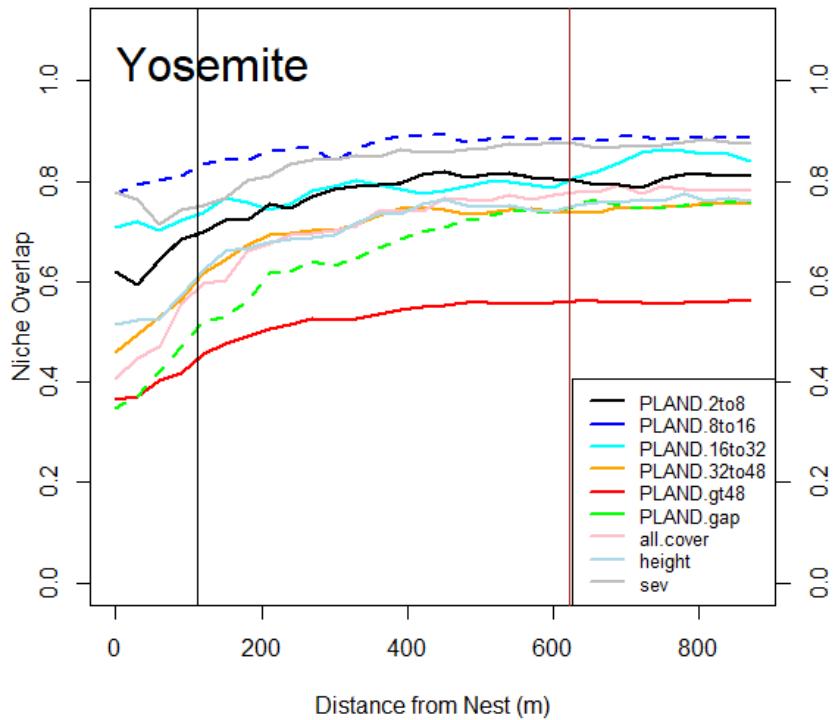


Figure 1: Niche-overlap modeling results for the post-fire, lidar-based metrics Niche overlap as a function of distance from nest. The black vertical line represents the nest distance for an owl (112.8m) which was imputed as a function of latitude from the nest distances in North et. al. 2017. The brown line represents the area of heavy utilization (700m). PLAND = Percent of Landscape in canopy height strata.

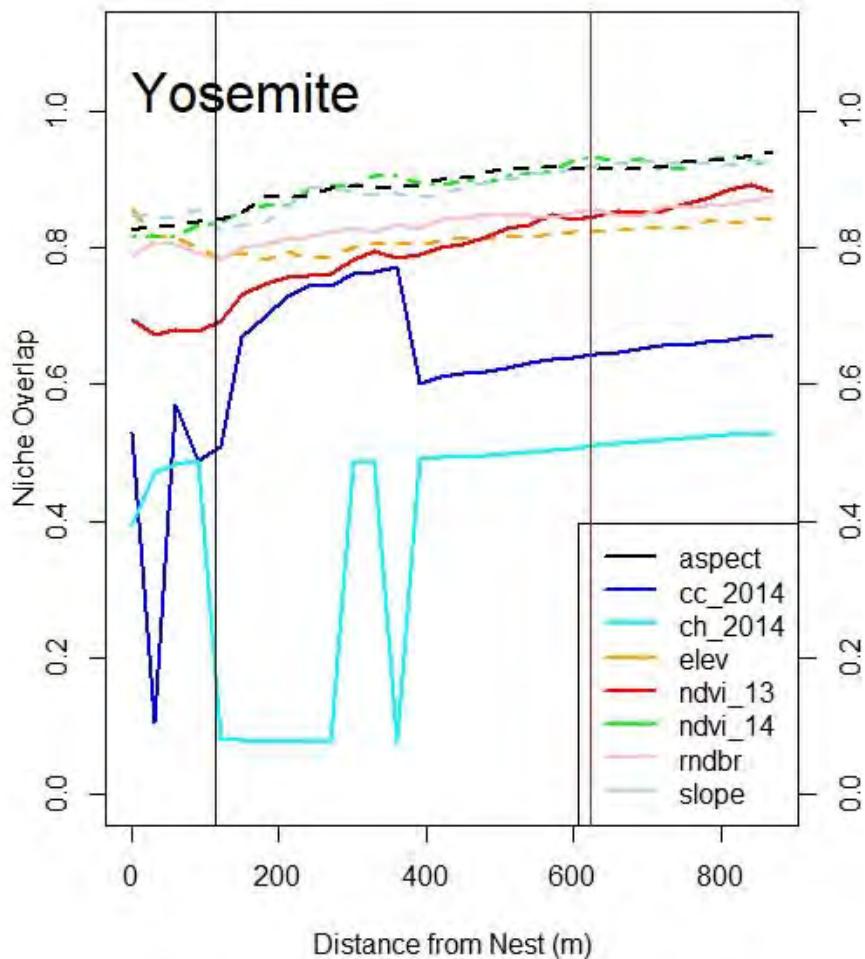


Figure 2: Niche-overlap modeling results for pre and post fire, Landsat-based metrics: The metrics are defined as $cc_{-}2014$ = Canopy cover 2014, $Ch_{-}2014$ = Canopy height 2014. The patterns observed in the niche overlap modeling is likely attributed to the factored nature of the data and the coarseness/patchiness of the layers.

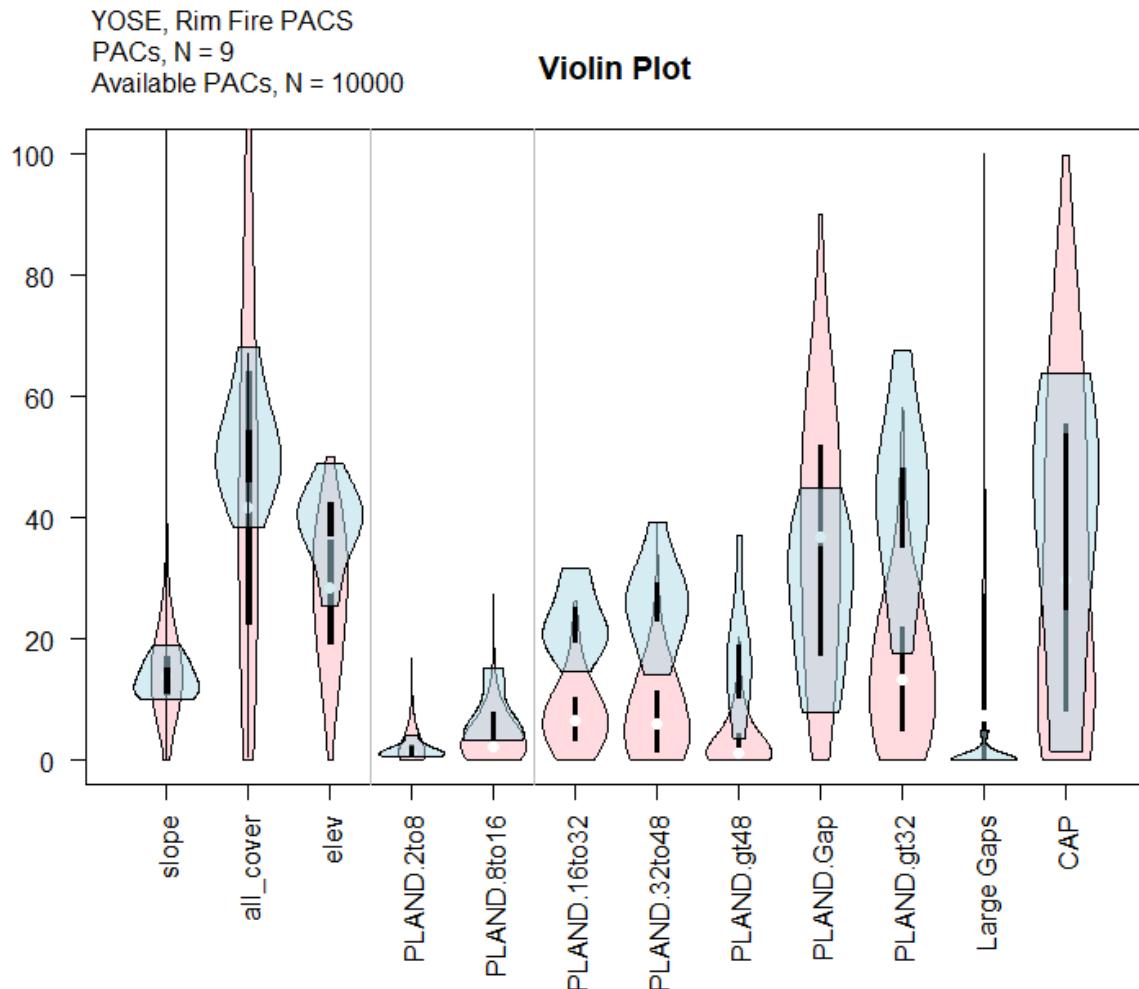


Figure 3: Violin plots of frequency of lidar and Landsat based metrics for nesting locations in the Rim fire portion of Yosemite National Park. The pink frequencies represent the distribution of values for each metric for the 10,000 samples of the random available potential habitat, and the blue frequencies represent the distribution of values for each of the metrics of the nine nesting locations, respectively.

Table 1: Lidar-based Canopy Structure and Topographic Metrics⁴

Selected Metrics	Landsat-based Metric	Lidar-based Metric	Niche Overlap at X Distance	Niche Overlap Rank
Selected		All canopy cover above 2m from the ground (all_cover_above2_30METERS.img)	0.471	17
Selected		95 th percentile of height of all lidar returns above 2m from the ground-height of tallest portion of overstory canopy (elev_P95_2plus_30METERS.img)	0.544	50
Selected		The percent of area of canopy cover between 16 and 32m in height (PLAND.16to32_90m.img)	0.745	227
Selected		The percent of area of canopy cover between 2 and 8m in height (PLAND.2to8_90m.img)	0.622	229
Selected		The percent of area of canopy cover between 32 and 48m in height (PLAND.32to48_90m.img)	0.490	231
Selected		The percent of area of canopy cover between 8 to 16m in height (PLAND.8to16_90m.img)	0.777	233
Selected		The percent of area of canopy cover between 48 to 90m in height (PLAND.gt48_90m.img)	0.420	239
Selected		The percent of area not covered by vegetation, Gaps in total canopy area (PLAND.Gap_90m.img)	0.410	237
Selected	Relative differenced normalized burn ration (RdNBR)	Relative differenced normalized burn ration (RdNBR based on satellite, analyzed with lidar-based metrics)		
Selected	Aspect			
Selected	Canopy Cover 2014			
Selected	Canopy Height 2014			
Selected	Ground Elevation			
Selected	Normalized Difference Vegetation Index (NDVI) 2013			
Selected	NDVI 2014			
Selected	Slope			
		1000M_tpi_tpi_30METERS.img	0.518	373
		135M_topo_aspect_30METERS.img	0.832	374
		135M_topo_curvature_30METERS.img	0.663	375
		135M_topo_elevation_30METERS.img	0.737	376
		135M_topo_plancurv_30METERS.img	0.693	377
		135M_topo_profilecurv_30METERS.img	0.721	378
		135M_topo_slope_30METERS.img	0.770	379
		135M_topo_sri_30METERS.img	0.822	380
		15M_topo_aspect_30METERS.img	0.834	381
		15M_topo_curvature_30METERS.img	0.894	382
		15M_topo_elevation_30METERS.img	0.737	383
		15M_topo_plancurv_30METERS.img	0.910	384

⁴ Many lidar metrics are highly correlated (for example, alternative methods for calculating canopy cover). For highly correlated metrics, the best performing metric was incorporated into the model.

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	15M_topo_sri_30METERS.img	0.894	387
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	1st_cnt_above2_30METERS.img	0.507	3
	1st_cover_above_mean_30METERS.img	0.527	4
	1st_cover_above_mode_30METERS.img	0.646	5
	1st_cover_above2_30METERS.img	0.459	6
	2000M_tpi_tpi_30METERS.img	0.631	388
	200M_tpi_tpi_30METERS.img	0.714	389
	270M_topo_aspect_30METERS.img	0.779	390
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	270M_topo_elevation_30METERS.img	0.737	392
	270M_topo_plancurv_30METERS.img	0.559	393
	270M_topo_profilecurv_30METERS.img	0.564	394
	270M_topo_slope_30METERS.img	0.783	395
	270M_topo_sri_30METERS.img	0.815	396
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	45M_topo_curvature_30METERS.img	0.804	399
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	all_1st_cover_above2_30METERS.img	0.479	9
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	all_cover_above_mode_30METERS.img	0.685	16
	CA.16to32_30m.img	0.776	184
	CA.16to32_90m.img	0.745	185
	CA.2to8_30m.img	0.756	186

	CA.2to8_90m.img	0.622	187
	CA.32to48_30m.img	0.589	188
	CA.32to48_90m.img	0.490	189
	CA.8to16_30m.img	0.793	190
	CA.8to16_90m.img	0.777	191
	CA.Canopy_30m.img	0.501	192
	CA.Canopy_90m.img	0.410	193
	CA.Gap_30m.img	0.501	194
	CA.Gap_90m.img	0.410	195
	CA.gt48_30m.img	0.321	196
	CA.gt48_90m.img	0.420	197
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	Height.CV_30m.img	0.938	198
	Height.CV_90m.img	0.748	199
	Height.Mean_30m.img	0.583	200
	Height.Mean_90m.img	0.509	201
	Height.P25_30m.img	0.650	202
	Height.P25_90m.img	0.539	203
	Height.P50_30m.img	0.628	204
	Height.P50_90m.img	0.563	205
	Height.P75_30m.img	0.595	206
	Height.P75_90m.img	0.525	207
	Height.P95_30m.img	0.540	208
	Height.P95_90m.img	0.486	209
	Height.QuadMean_30m.img	0.575	210
	Height.QuadMean_90m.img	0.506	211
	Height.SD_30m.img	0.683	212
	Height.SD_90m.img	0.547	213
	int_AAD_2plus_30METERS.img	0.596	146
	int_ave_2plus_30METERS.img	0.659	147
	int_CV_2plus_30METERS.img	0.738	148
	int_IQ_2plus_30METERS.img	0.873	149
	int_kurtosis_2plus_30METERS.img	0.592	150

	int_L1_2plus_30METERS.img	0.670	151
	int_L2_2plus_30METERS.img	0.837	152
	int_L3_2plus_30METERS.img	0.804	153
	int_L4_2plus_30METERS.img	0.824	154
	int_LCV_2plus_30METERS.img	0.830	155
	int_Lkurtosis_2plus_30METERS.img	0.869	156
	int_Lskewness_2plus_30METERS.img	0.854	157
	int_max_2plus_30METERS.img	0.594	158
	int_min_2plus_30METERS.img	0.435	159
	int_mode_2plus_30METERS.img	0.666	160
	int_P01_2plus_30METERS.img	0.833	161
	int_P05_2plus_30METERS.img	0.867	162
	int_P10_2plus_30METERS.img	0.820	163
	int_P20_2plus_30METERS.img	0.871	164
	int_P25_2plus_30METERS.img	0.845	165
	int_P30_2plus_30METERS.img	0.835	166
	int_P40_2plus_30METERS.img	0.789	167
	int_P50_2plus_30METERS.img	0.793	168
	int_P60_2plus_30METERS.img	0.792	169
	int_P70_2plus_30METERS.img	0.780	170
	int_P75_2plus_30METERS.img	0.814	171
	int_P80_2plus_30METERS.img	0.773	172
	int_P90_2plus_30METERS.img	0.806	173
	int_P95_2plus_30METERS.img	0.809	174
	int_P99_2plus_30METERS.img	0.794	175
	int_skewness_2plus_30METERS.img	0.717	176
	int_stddev_2plus_30METERS.img	0.577	177
	int_variance_2plus_30METERS.img	0.590	178
	Ntao.16to32_30m.img	0.722	214
	Ntao.16to32_90m.img	0.706	215
	Ntao.2to8_30m.img	0.749	216
	Ntao.2to8_90m.img	0.585	217
	Ntao.32to48_30m.img	0.477	218
	Ntao.32to48_90m.img	0.491	219
	Ntao.8to16_30m.img	0.601	220
	Ntao.8to16_90m.img	0.793	221
	Ntao.Gap_30m.img	NA	222
	Ntao.Gap_90m.img	NA	223
	Ntao.gt48_30m.img	NA	224
	Ntao.gt48_90m.img	NA	225
	PLAND.16to32_30m.img	0.776	226

	PLAND.2to8_30m.img	0.756	228
	PLAND.32to48_30m.img	0.589	230
	PLAND.8to16_30m.img	0.793	232
	PLAND.Canopy_30m.img	0.501	234
	PLAND.Canopy_90m.img	0.410	235
	PLAND.Gap_30m.img	0.501	236
	PLAND.gt48_30m.img	0.321	238
	pulsecnt_30METERS.img	0.887	179
	r1_cnt_2plus_30METERS.img	0.528	180
	r2_cnt_2plus_30METERS.img	0.513	181
	r3_cnt_2plus_30METERS.img	0.513	182
	r4_cnt_2plus_30METERS.img	0.524	183
	ShannonEven.Canopyonly_30m.img	0.732	240
	ShannonEven.Canopyonly_90m.img	0.711	241
	strata_Op5to1M_CV_30METERS.img	0.880	263
	strata_Op5to1M_kurtosis_30METERS.img	0.901	264
	strata_Op5to1M_max_30METERS.img	0.769	265
	strata_Op5to1M_mean_30METERS.img	0.921	266
	strata_Op5to1M_median_30METERS.img	0.913	267
	strata_Op5to1M_min_30METERS.img	0.846	268
	strata_Op5to1M_mode_30METERS.img	0.847	269
	strata_Op5to1M_return_proportion_30METERS.img	0.773	270
	strata_Op5to1M_skewness_30METERS.img	0.917	271
	strata_Op5to1M_stddev_30METERS.img	0.916	272
	strata_Op5to1M_total_return_cnt_30METERS.img	0.833	273
	strata_OtoOp5M_CV_30METERS.img	0.999	274
	strata_OtoOp5M_kurtosis_30METERS.img	0.932	275
	strata_OtoOp5M_max_30METERS.img	0.832	276
	strata_OtoOp5M_mean_30METERS.img	0.887	277
	strata_OtoOp5M_median_30METERS.img	0.854	278
	strata_OtoOp5M_min_30METERS.img	0.875	279
	strata_OtoOp5M_mode_30METERS.img	0.845	280
	strata_OtoOp5M_return_proportion_30METERS.img	0.496	281
	strata_OtoOp5M_skewness_30METERS.img	0.853	282
	strata_OtoOp5M_stddev_30METERS.img	0.860	283
	strata_OtoOp5M_total_return_cnt_30METERS.img	0.665	284
	strata_16to32M_CV_30METERS.img	0.761	285
	strata_16to32M_kurtosis_30METERS.img	0.809	286
	strata_16to32M_max_30METERS.img	0.433	287
	strata_16to32M_mean_30METERS.img	0.725	288
	strata_16to32M_median_30METERS.img	0.753	289

	strata_16to32M_min_30METERS.img	0.893	290
	strata_16to32M_mode_30METERS.img	0.782	291
	strata_16to32M_return_proportion_30METERS.img	0.541	292
	strata_16to32M_skewness_30METERS.img	0.809	293
	strata_16to32M_stddev_30METERS.img	0.700	294
	strata_16to32M_total_return_cnt_30METERS.img	0.530	295
	strata_1to2M_CV_30METERS.img	0.898	296
	strata_1to2M_kurtosis_30METERS.img	0.890	297
	strata_1to2M_max_30METERS.img	0.763	298
	strata_1to2M_mean_30METERS.img	0.941	299
	strata_1to2M_median_30METERS.img	0.949	300
	strata_1to2M_min_30METERS.img	0.777	301
	strata_1to2M_mode_30METERS.img	0.808	302
	strata_1to2M_return_proportion_30METERS.img	0.800	303
	strata_1to2M_skewness_30METERS.img	0.973	304
	strata_1to2M_stddev_30METERS.img	0.894	305
	strata_1to2M_total_return_cnt_30METERS.img	0.839	306
	strata_2to4M_CV_30METERS.img	0.870	307
	strata_2to4M_kurtosis_30METERS.img	0.881	308
	strata_2to4M_max_30METERS.img	0.864	309
	strata_2to4M_mean_30METERS.img	0.810	310
	strata_2to4M_median_30METERS.img	0.815	311
	strata_2to4M_min_30METERS.img	0.759	312
	strata_2to4M_mode_30METERS.img	0.829	313
	strata_2to4M_return_proportion_30METERS.img	0.811	314
	strata_2to4M_skewness_30METERS.img	0.830	315
	strata_2to4M_stddev_30METERS.img	0.907	316
	strata_2to4M_total_return_cnt_30METERS.img	0.802	317
	strata_32to48M_CV_30METERS.img	0.696	318
	strata_32to48M_kurtosis_30METERS.img	0.870	319
	strata_32to48M_max_30METERS.img	0.493	320
	strata_32to48M_mean_30METERS.img	0.714	321
	strata_32to48M_median_30METERS.img	0.729	322
	strata_32to48M_min_30METERS.img	0.900	323
	strata_32to48M_mode_30METERS.img	0.756	324
	strata_32to48M_return_proportion_30METERS.img	0.491	325
	strata_32to48M_skewness_30METERS.img	0.874	326
	strata_32to48M_stddev_30METERS.img	0.700	327
	strata_32to48M_total_return_cnt_30METERS.img	0.477	328
	strata_48to64M_CV_30METERS.img	0.827	329
	strata_48to64M_kurtosis_30METERS.img	0.933	330

	strata_48to64M_max_30METERS.img	0.797	331
	strata_48to64M_mean_30METERS.img	0.822	332
	strata_48to64M_median_30METERS.img	0.831	333
	strata_48to64M_min_30METERS.img	0.818	334
	strata_48to64M_mode_30METERS.img	0.793	335
	strata_48to64M_return_proportion_30METERS.img	0.263	336
	strata_48to64M_skewness_30METERS.img	0.939	337
	strata_48to64M_stddev_30METERS.img	0.824	338
	strata_48to64M_total_return_cnt_30METERS.img	0.323	339
	strata_4to8M_CV_30METERS.img	0.919	340
	strata_4to8M_kurtosis_30METERS.img	0.902	341
	strata_4to8M_max_30METERS.img	0.863	342
	strata_4to8M_mean_30METERS.img	0.825	343
	strata_4to8M_median_30METERS.img	0.836	344
	strata_4to8M_min_30METERS.img	0.894	345
	strata_4to8M_mode_30METERS.img	0.842	346
	strata_4to8M_return_proportion_30METERS.img	0.815	347
	strata_4to8M_skewness_30METERS.img	0.842	348
	strata_4to8M_stddev_30METERS.img	0.894	349
	strata_4to8M_total_return_cnt_30METERS.img	0.780	350
	strata_64M_plus_CV_30METERS.img	0.803	351
	strata_64M_plus_kurtosis_30METERS.img	0.866	352
	strata_64M_plus_max_30METERS.img	0.772	353
	strata_64M_plus_mean_30METERS.img	0.795	354
	strata_64M_plus_median_30METERS.img	0.832	355
	strata_64M_plus_min_30METERS.img	0.922	356
	strata_64M_plus_mode_30METERS.img	0.791	357
	strata_64M_plus_return_proportion_30METERS.img	0.328	358
	strata_64M_plus_skewness_30METERS.img	0.921	359
	strata_64M_plus_stddev_30METERS.img	0.801	360
	strata_64M_plus_total_return_cnt_30METERS.img	0.436	361
	strata_8to16M_CV_30METERS.img	0.852	362
	strata_8to16M_kurtosis_30METERS.img	0.841	363
	strata_8to16M_max_30METERS.img	0.730	364
	strata_8to16M_mean_30METERS.img	0.786	365
	strata_8to16M_median_30METERS.img	0.803	366
	strata_8to16M_min_30METERS.img	0.895	367
	strata_8to16M_mode_30METERS.img	0.830	368
	strata_8to16M_return_proportion_30METERS.img	0.740	369
	strata_8to16M_skewness_30METERS.img	0.824	370
	strata_8to16M_stddev_30METERS.img	0.801	371

	strata_8to16M_total_return_cnt_30METERS.img	0.666	372
	TotalArea_30m.img	NA	242
	TotalArea_90m.img	NA	243
	Volume.16to32_30m.img	0.776	244
	Volume.16to32_90m.img	0.734	245
	Volume.2to8_30m.img	0.765	246
	Volume.2to8_90m.img	0.633	247
	Volume.32to48_30m.img	0.587	248
	Volume.32to48_90m.img	0.488	249
	Volume.8to16_30m.img	0.796	250
	Volume.8to16_90m.img	0.783	251
	Volume.Canopy_30m.img	0.459	252
	Volume.Canopy_90m.img	0.395	253
	Volume.Gap_30m.img	NA	254
	Volume.Gap_90m.img	NA	255
	Volume.gt48_30m.img	0.320	256
	Volume.gt48_90m.img	0.415	257