

Thermal Camera For Climate Change Prevention

Ramses Alcaide

John Thomson

Adrian Haruta

Team Lead

Electrical Lead

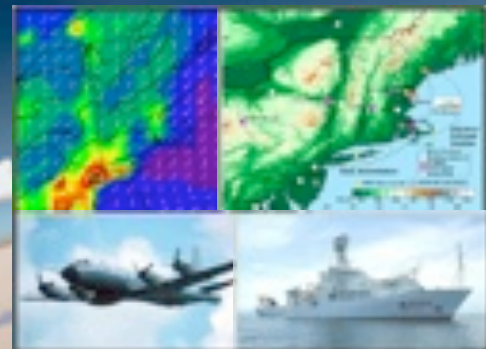
Mechanical Lead



ICARTT: COORDINATED ATMOSPHERIC CHEMISTRY CAMPAIGN OVER EASTERN NORTH AMERICA AND NORTH ATLANTIC IN SUMMER 2004



ICARTT Focus areas: regional air quality, intercontinental transport, and radiation balance



NOAA New England Air Quality Study (NEAQS) mission



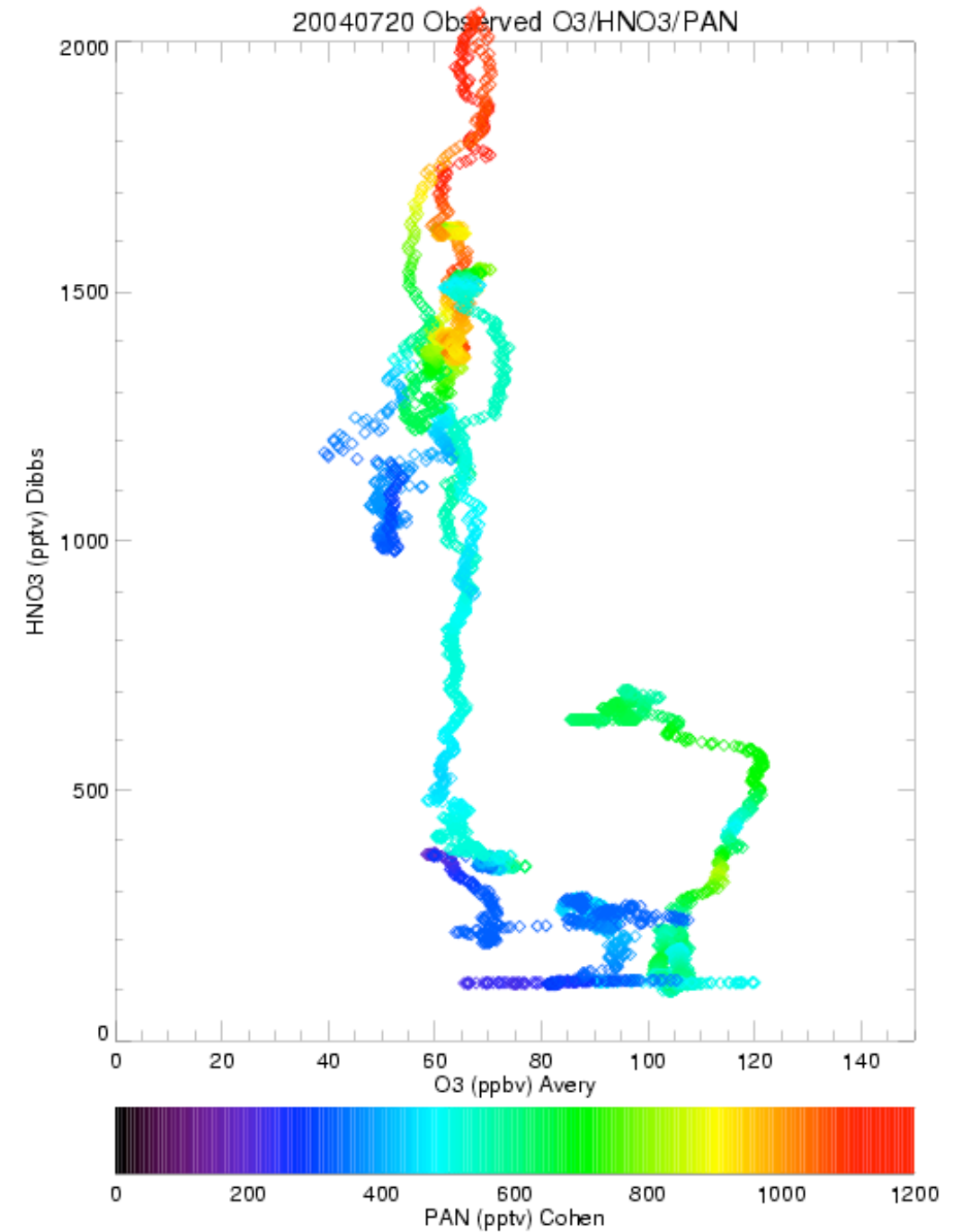
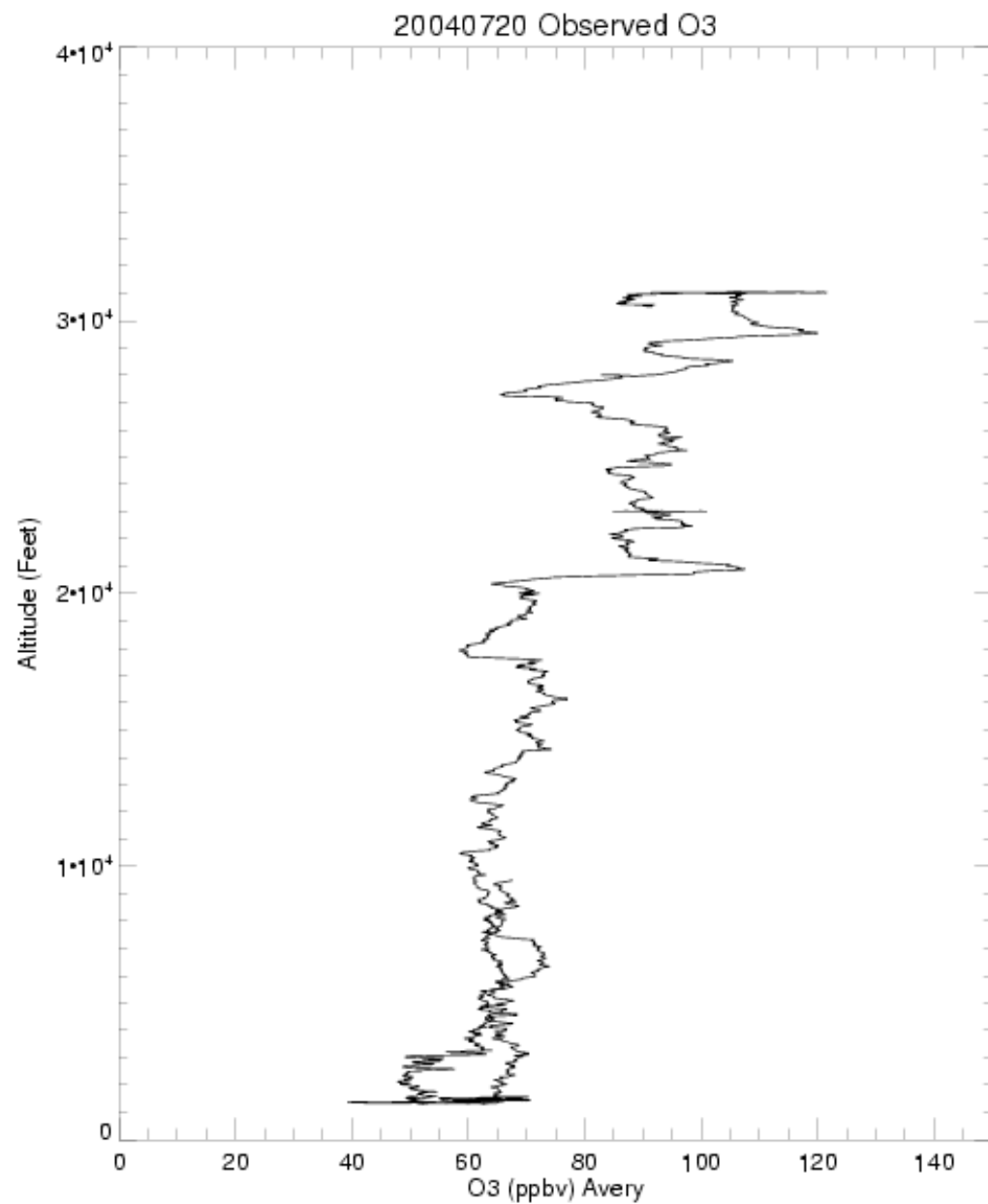
NASA Intercontinental Chemical Transport Experiment- North America (INTEX-NA) mission



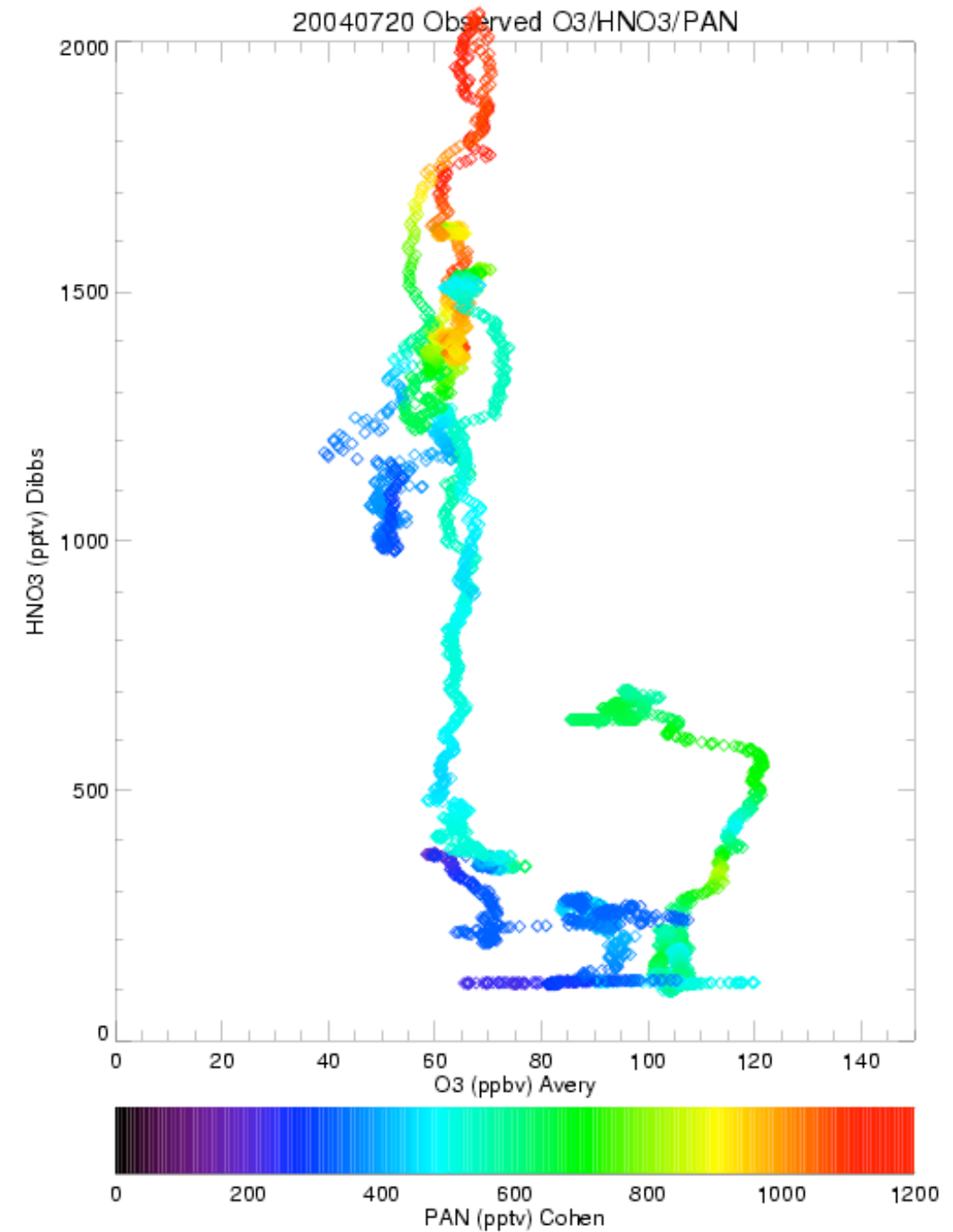
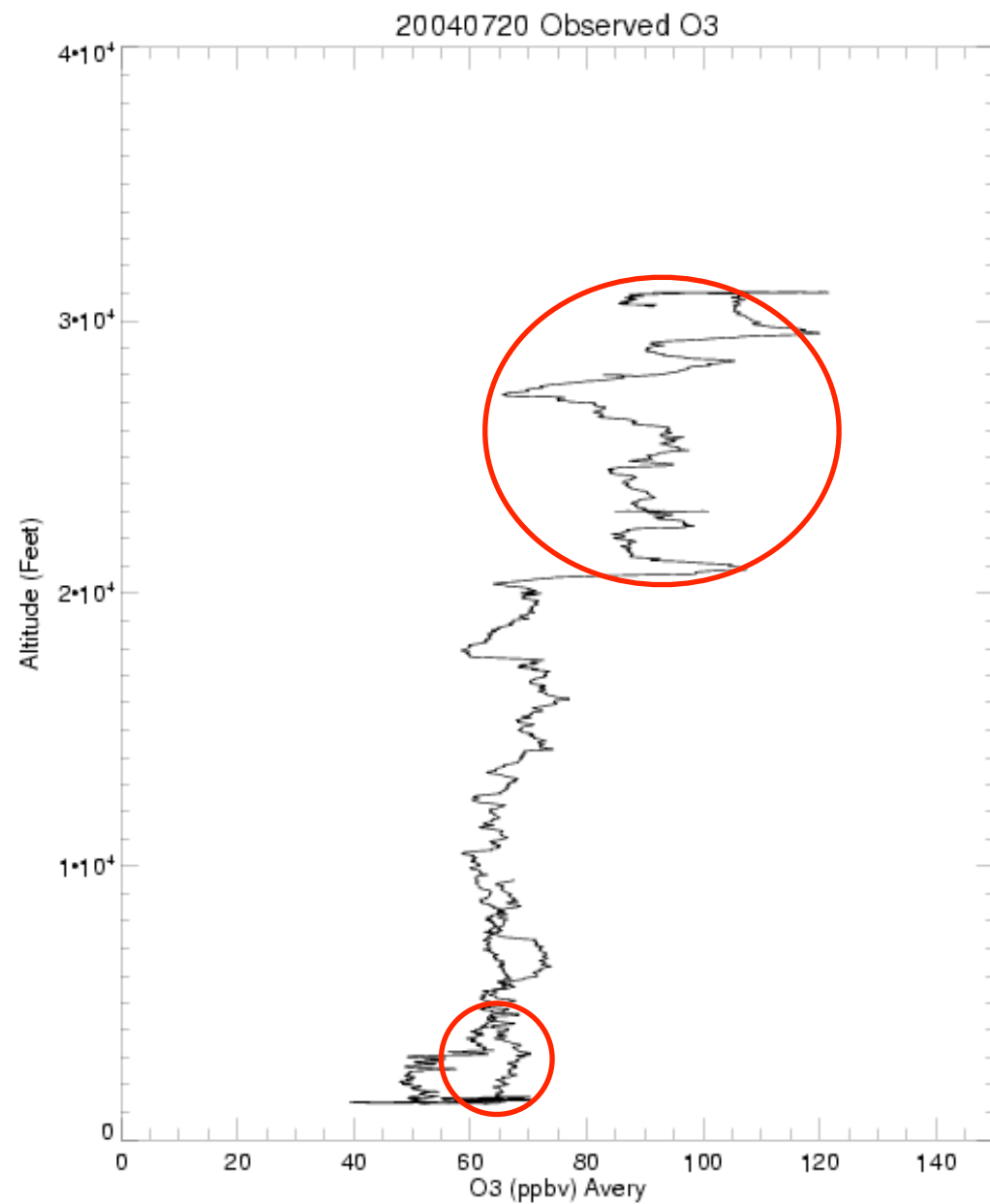
EU International Transport of Pollution (ITOP) mission

JULY 20, 2004

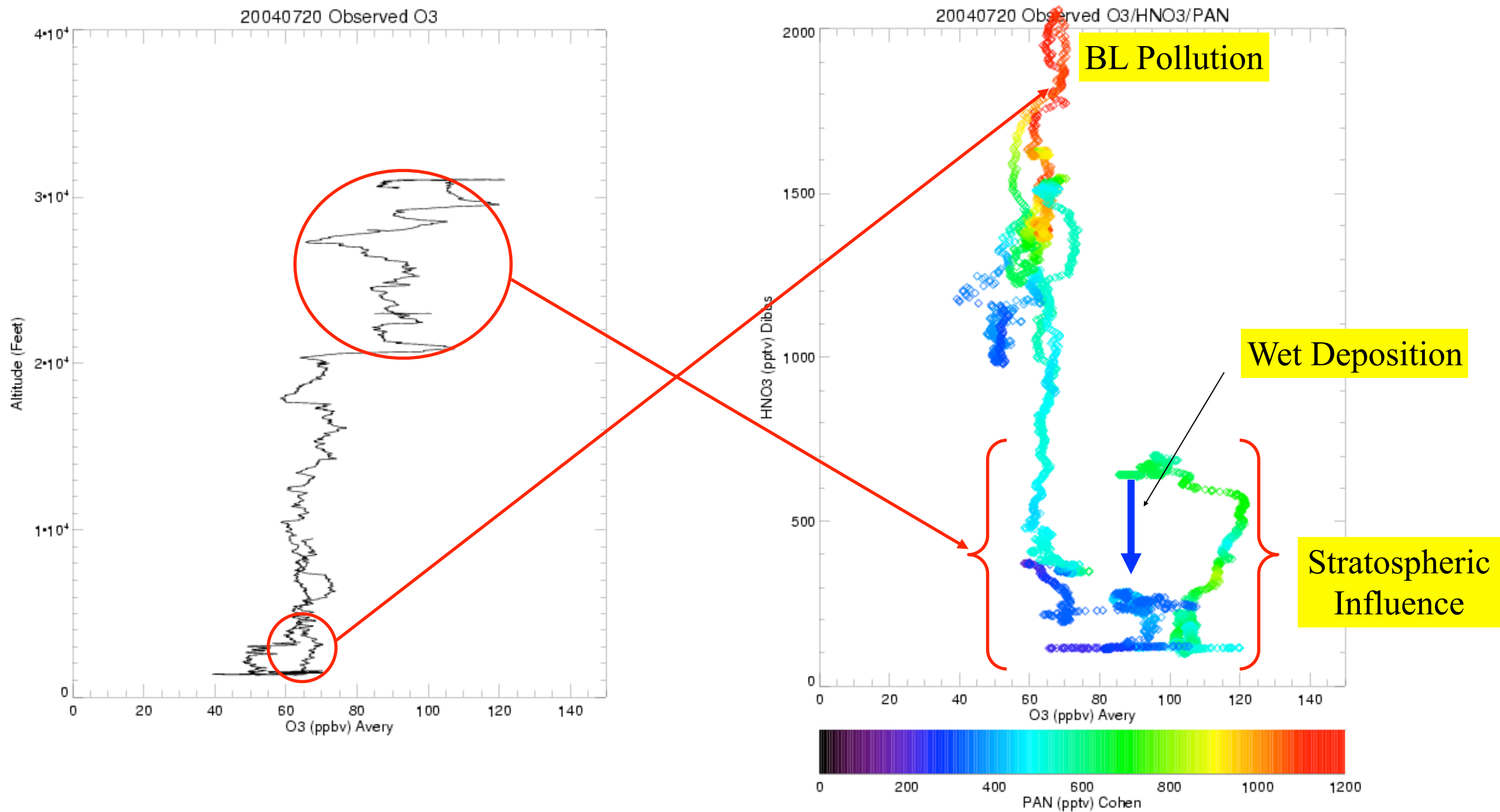
DC-8 In-situ chemical properties: NC/VA flight leg



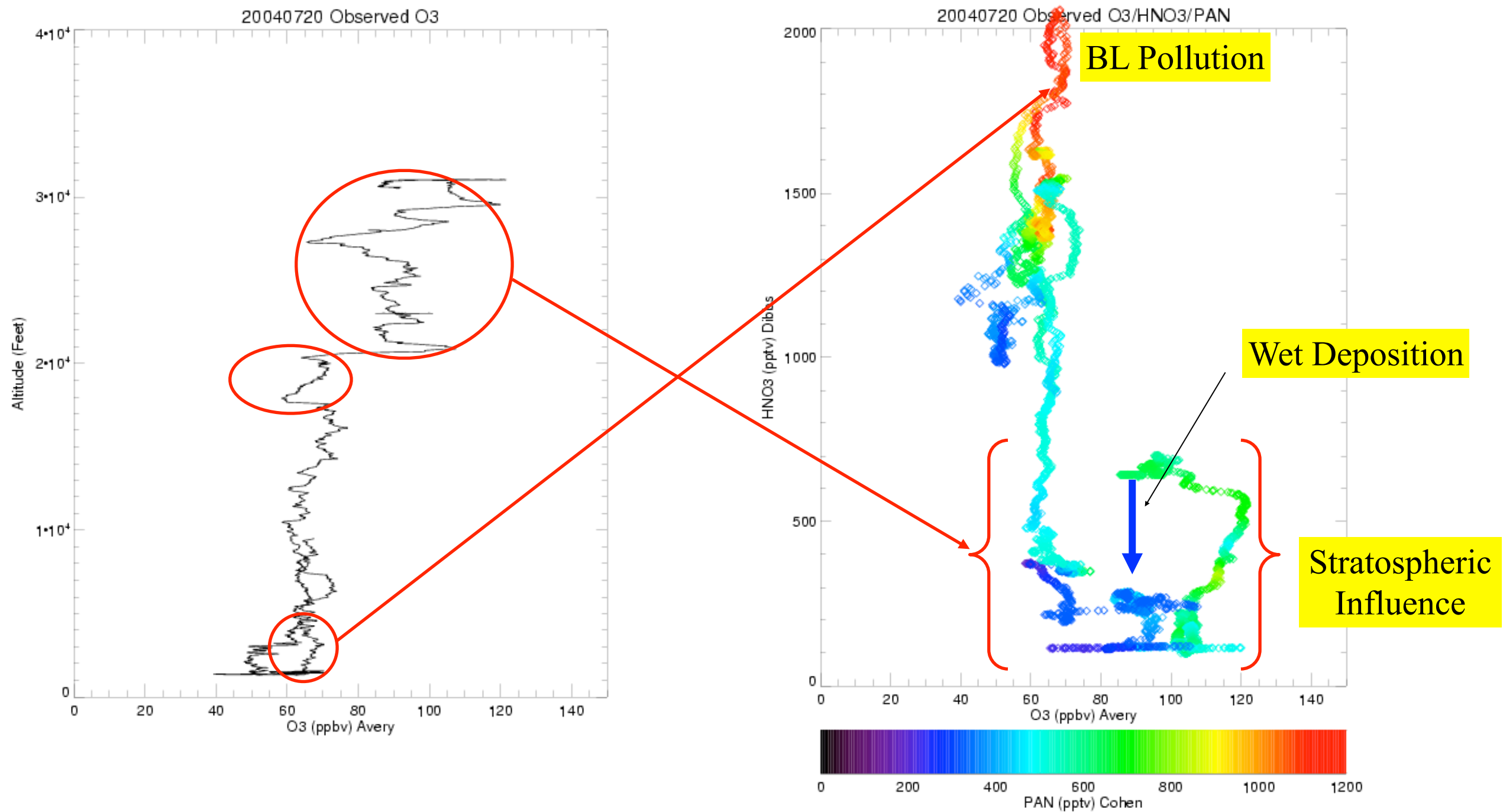
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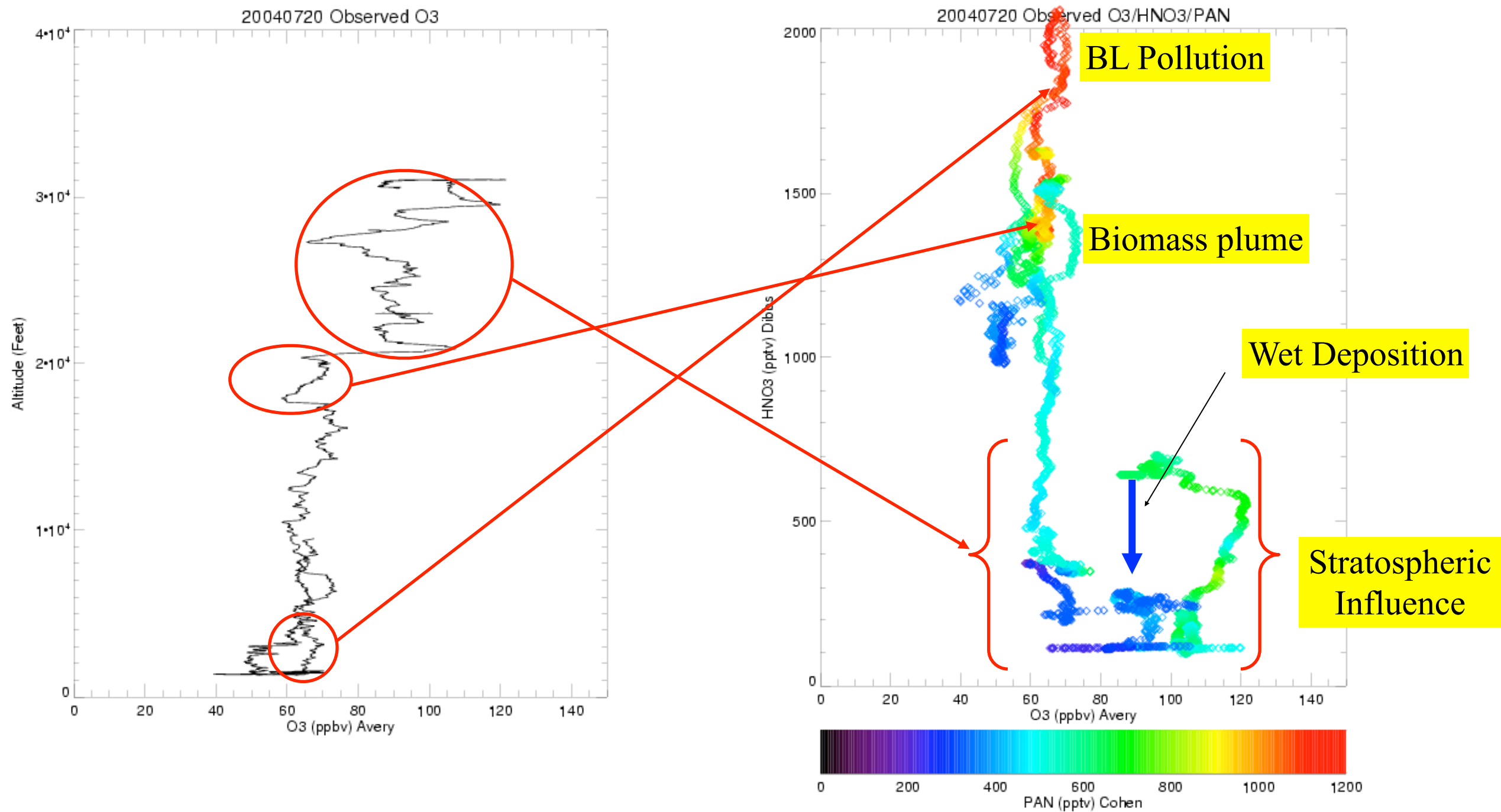
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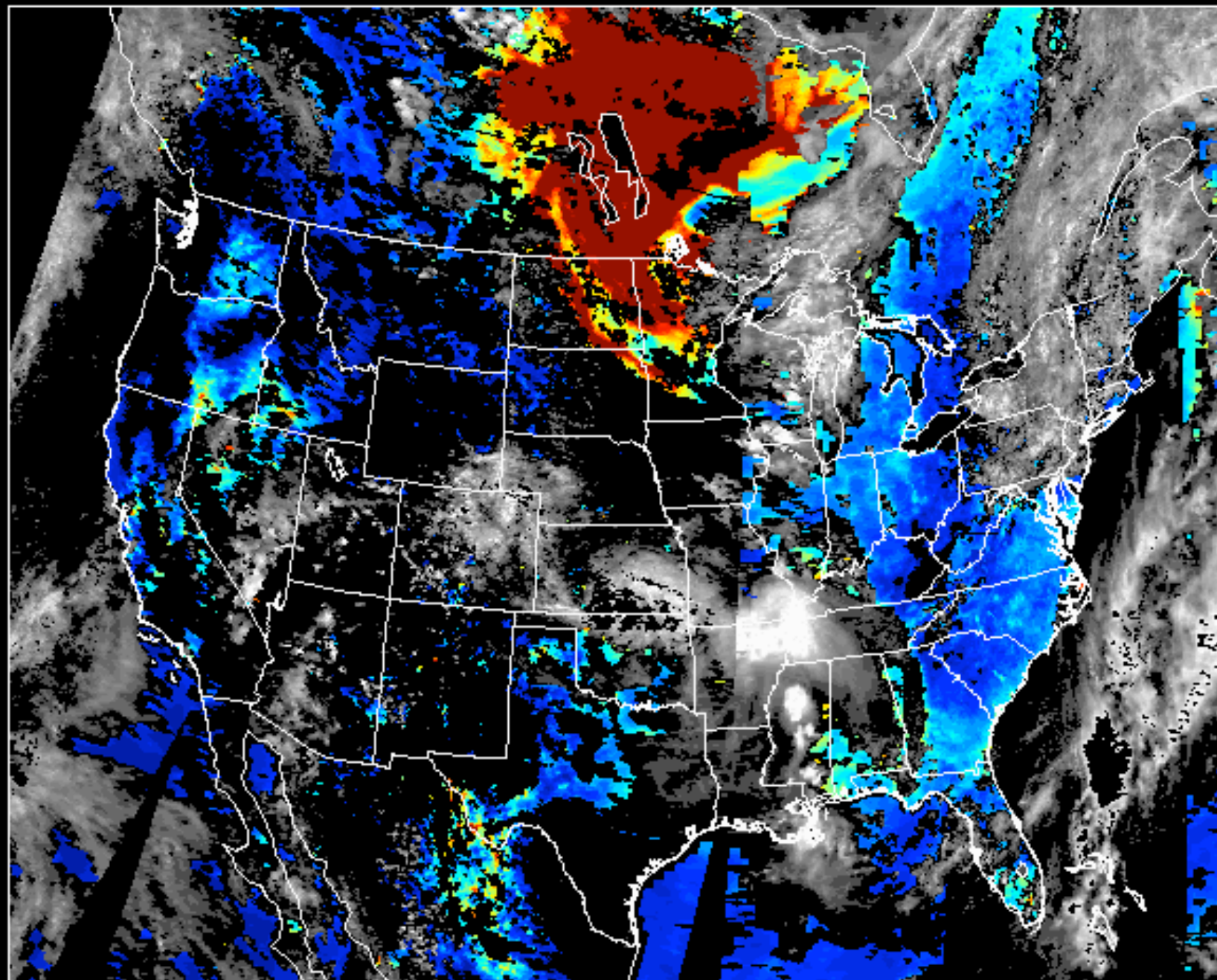
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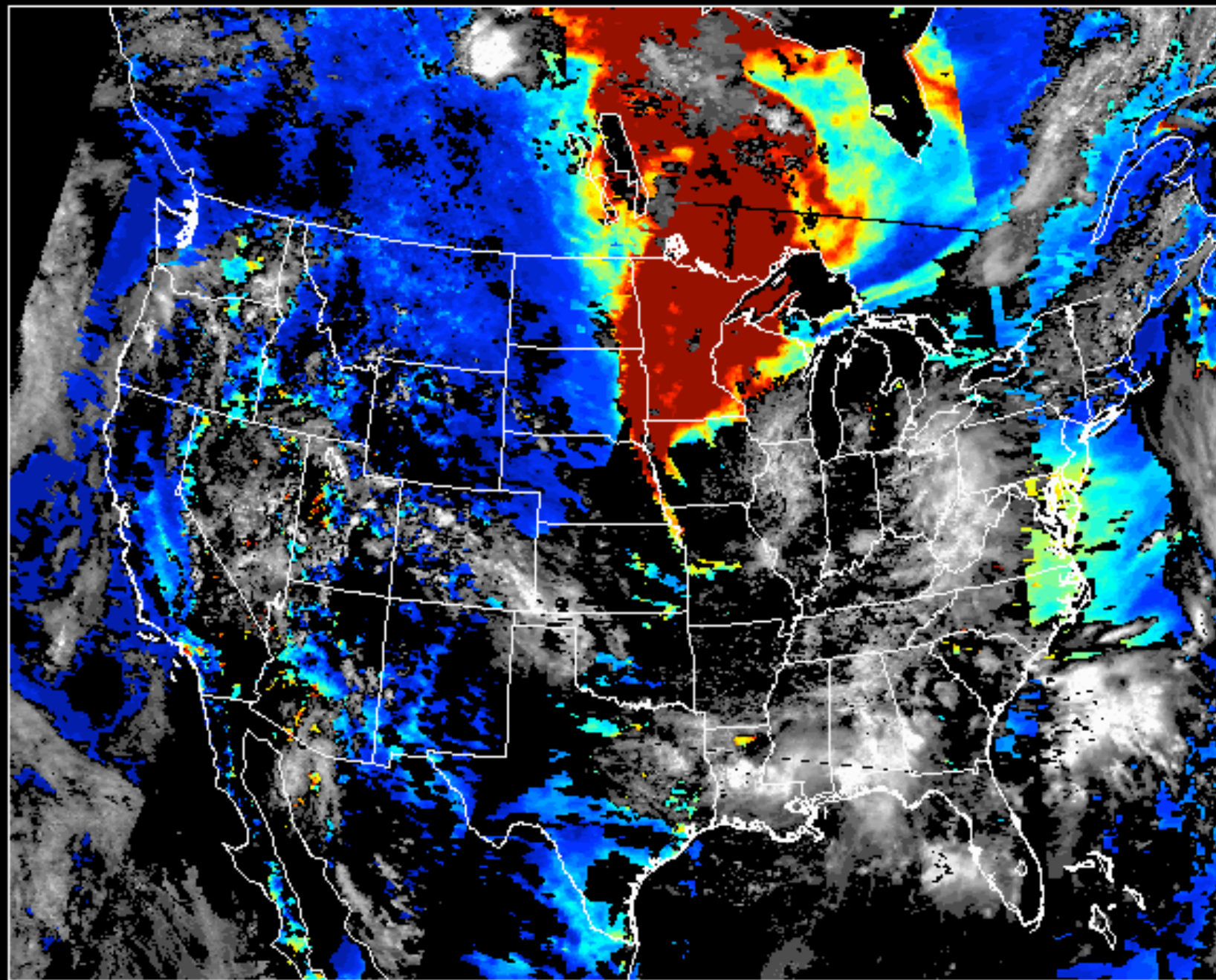
MODIS (Terra) 2004 07 16



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AOD

0 10 20 30 40 50 60 70
COT

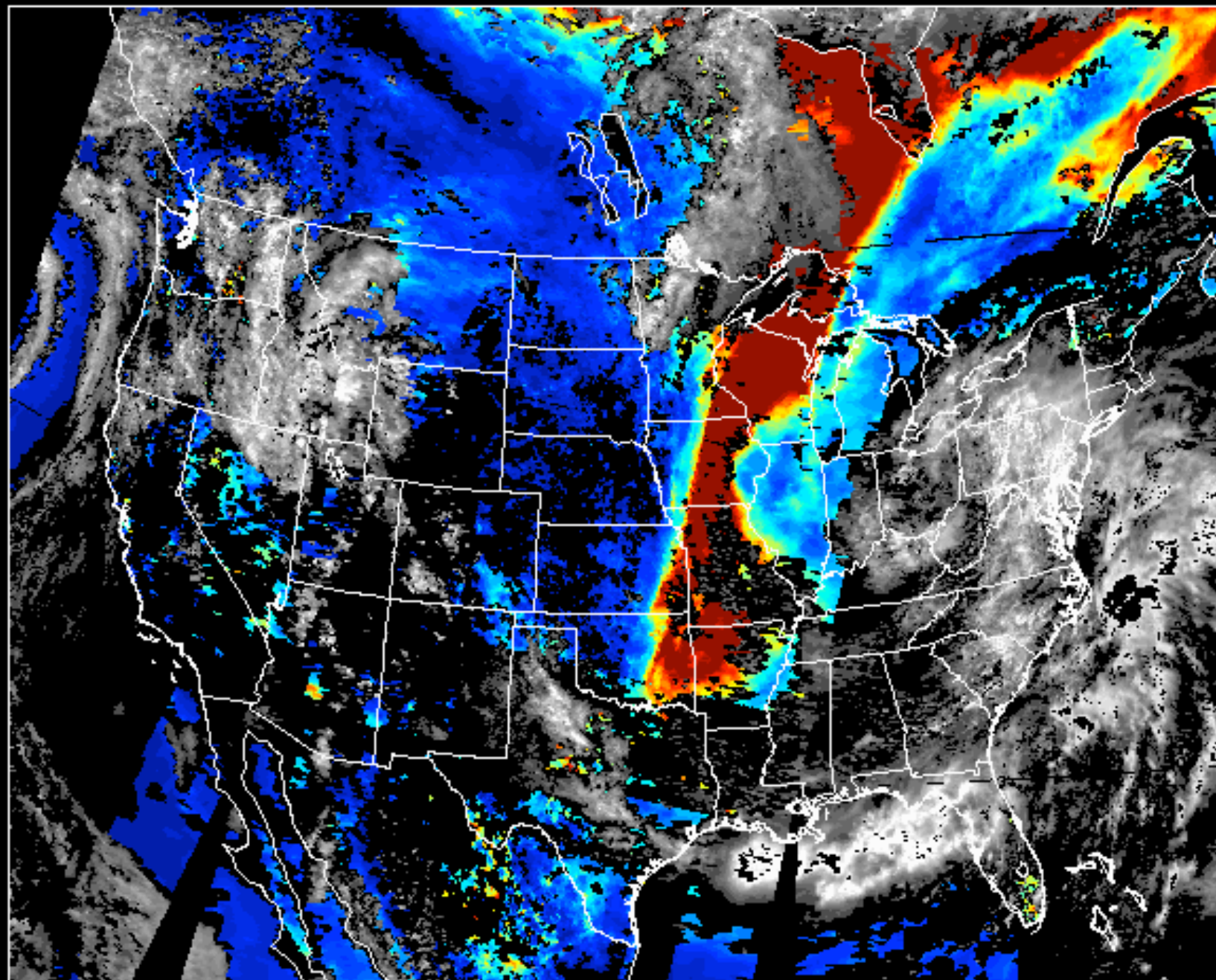
MODIS (Terra) 2004 07 17



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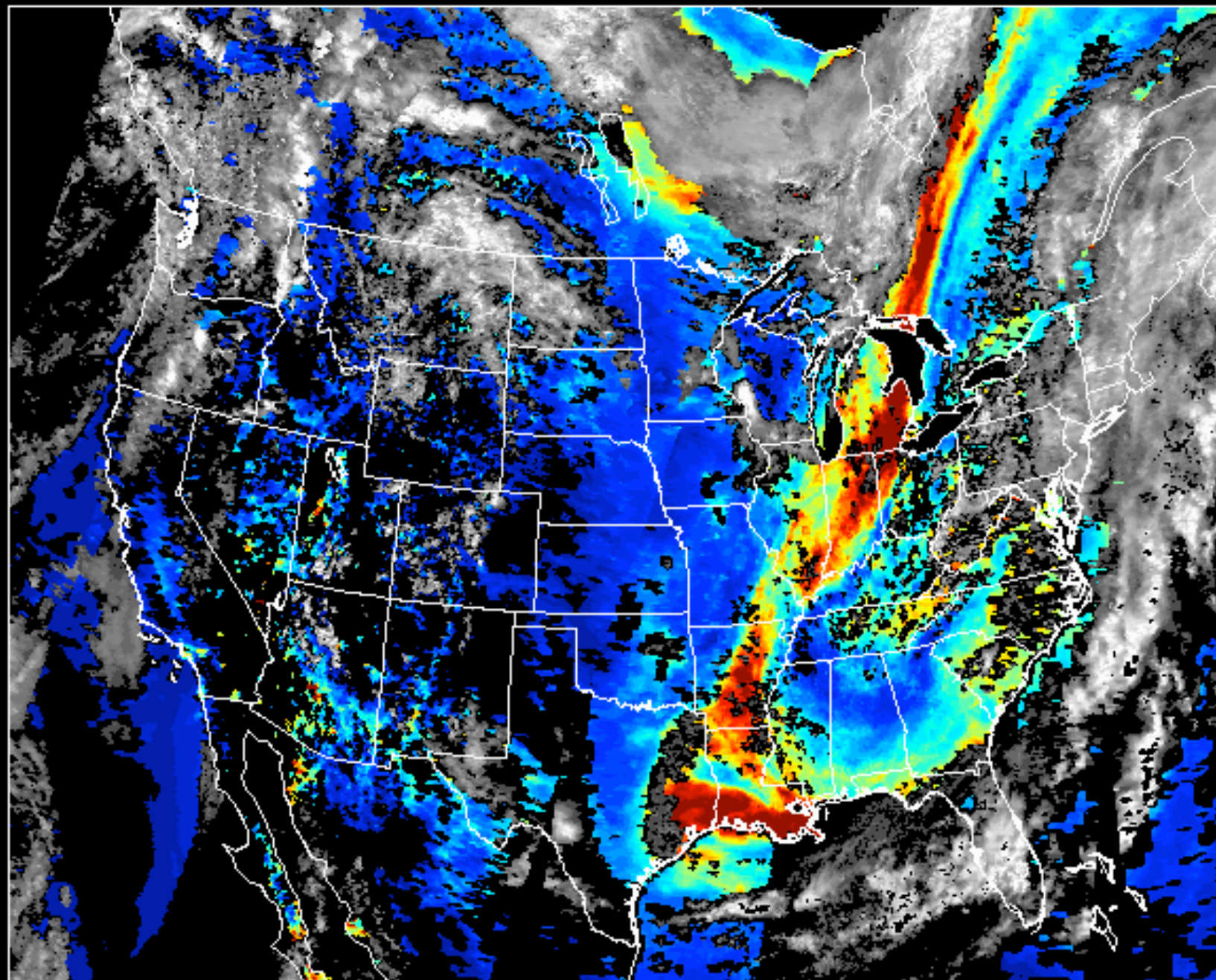
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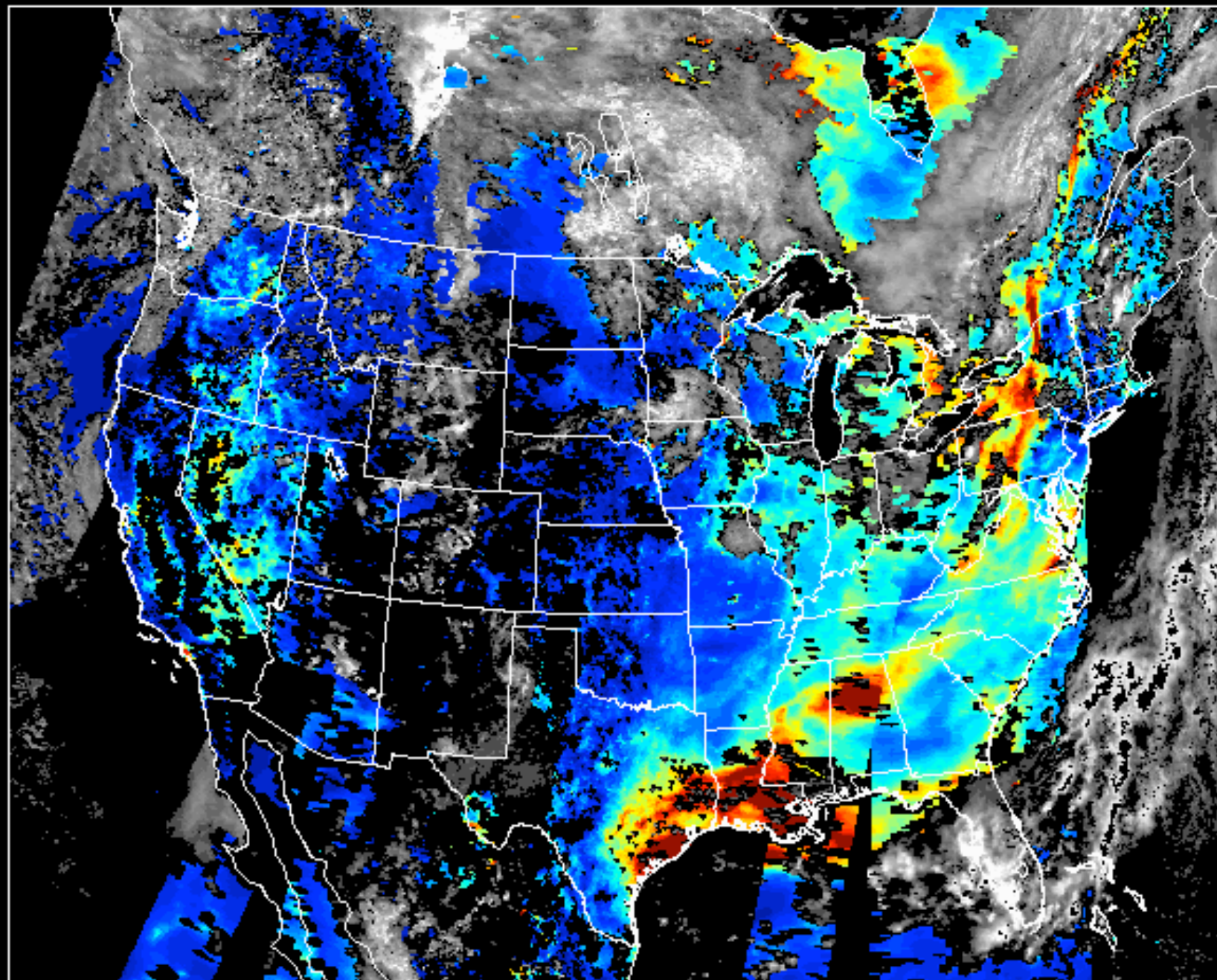
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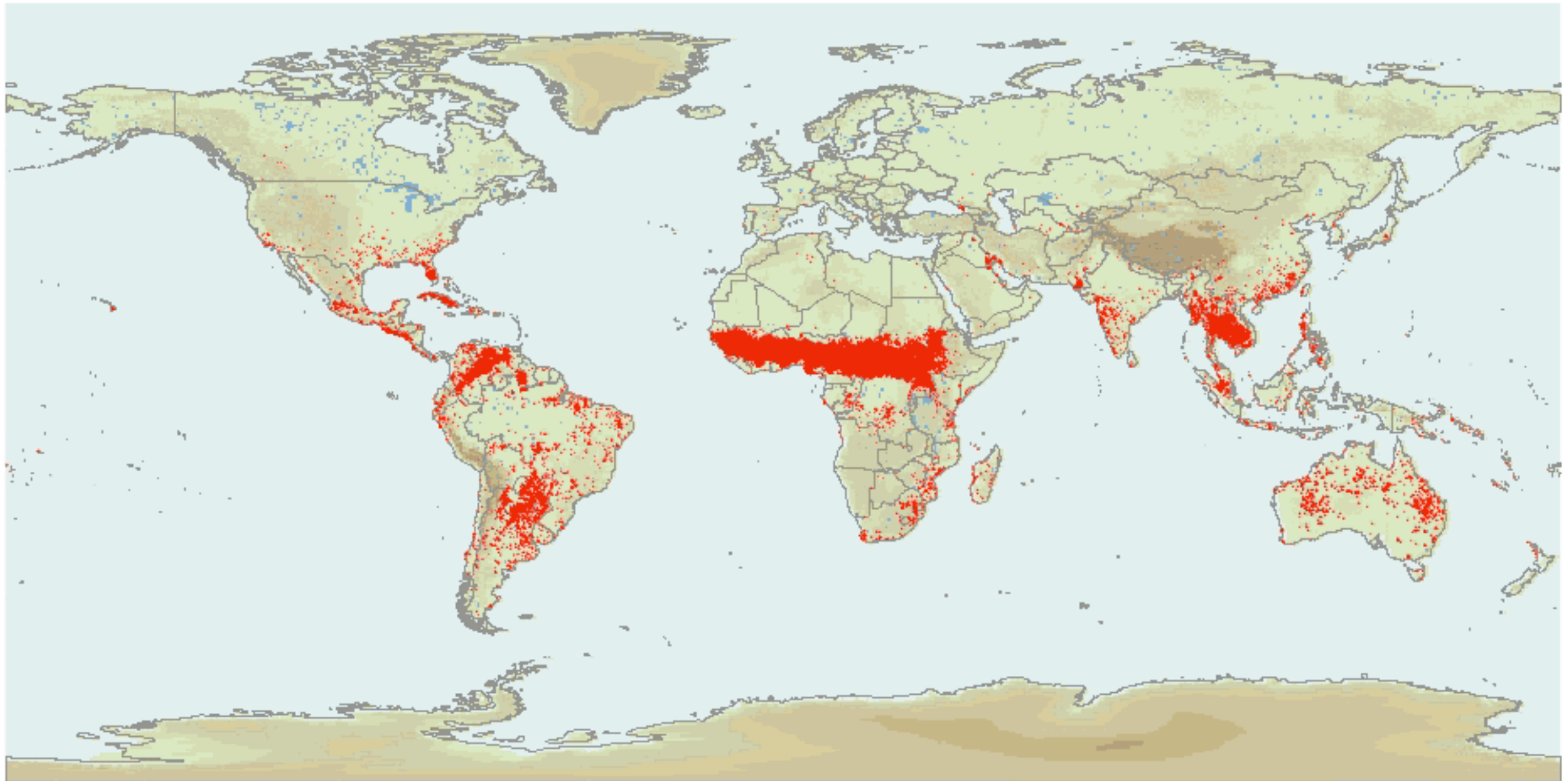
MODIS (Terra) 2004 07 20



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MODIS Rapid Response Fire Detections for 2004



JANUARY FEBRUARY MARCH APRIL MAY JUNE JULY AUGUST SEPTEMBER OCTOBER NOVEMBER DECEMBER



- MODIS Active Fire Detections
- World Countries

Active fires are detected using MODIS data from the Terra satellite.
Source: MODIS Rapid Response <http://rapidfire.sci.gsfc.nasa.gov>
Web Fire Mapper <http://maps.geog.umd.edu>









Friday, April 9, 2010

Mechanical Development

Adrian Haruta

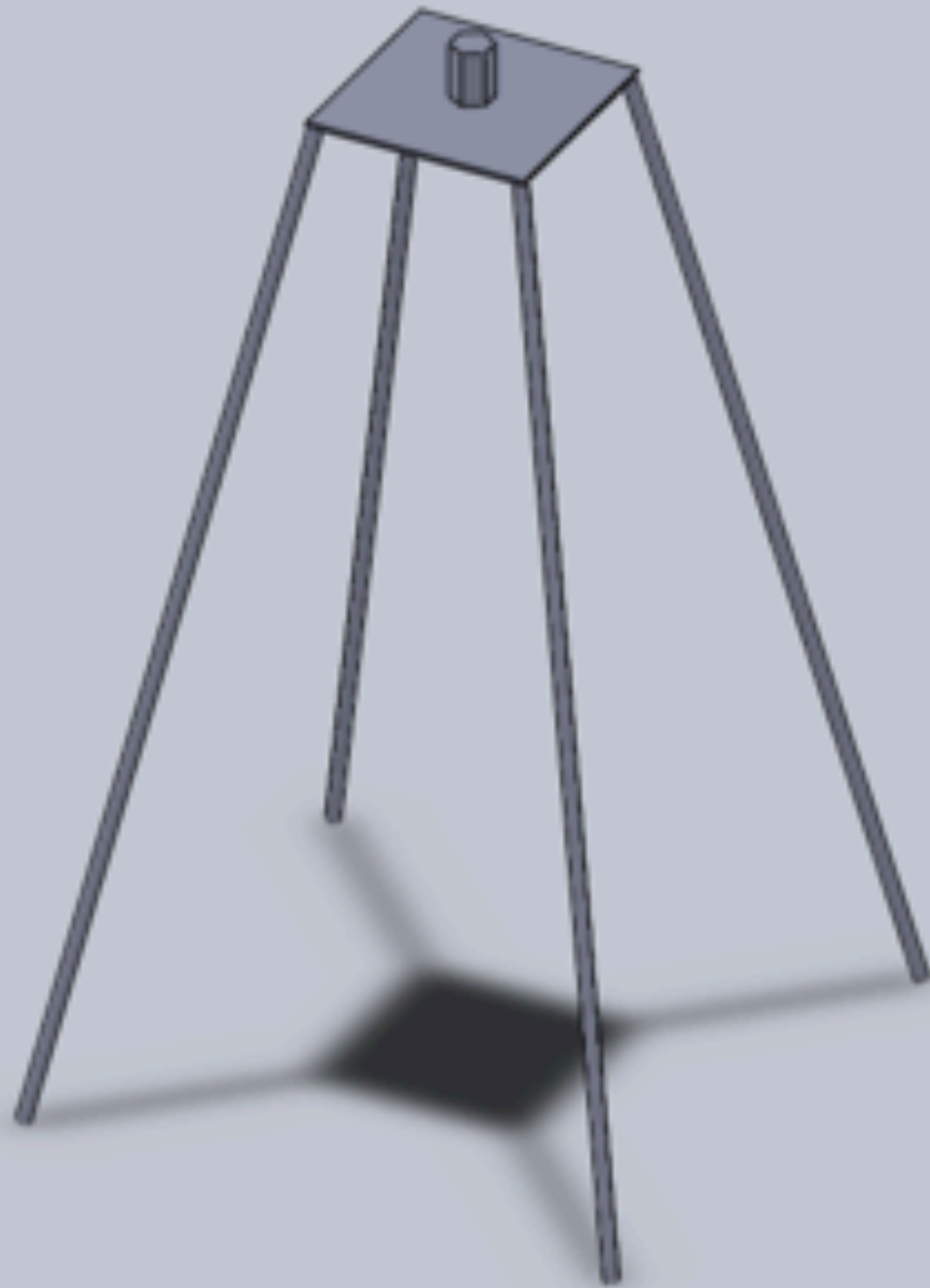


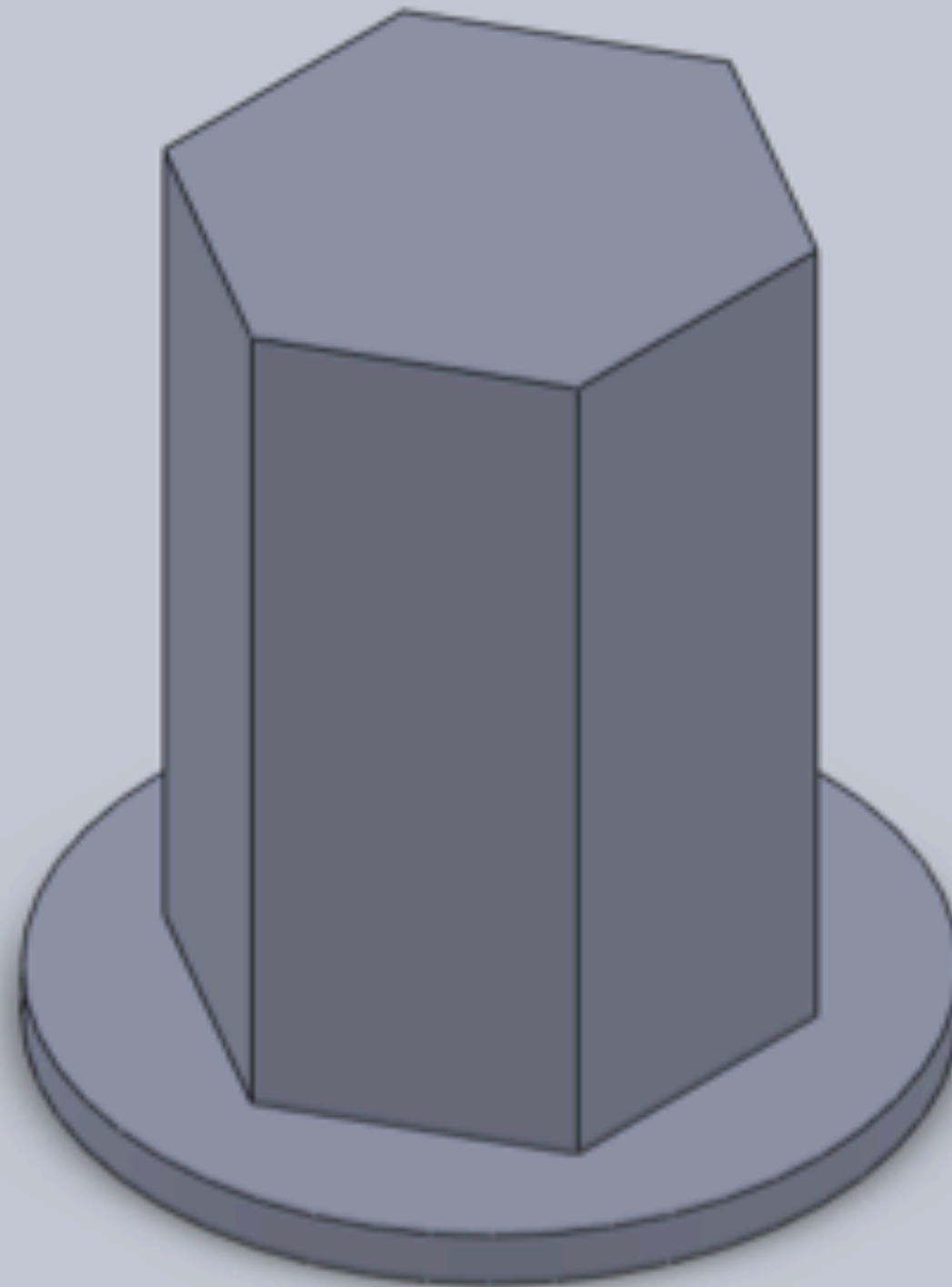
Mechanical Eng. Goals

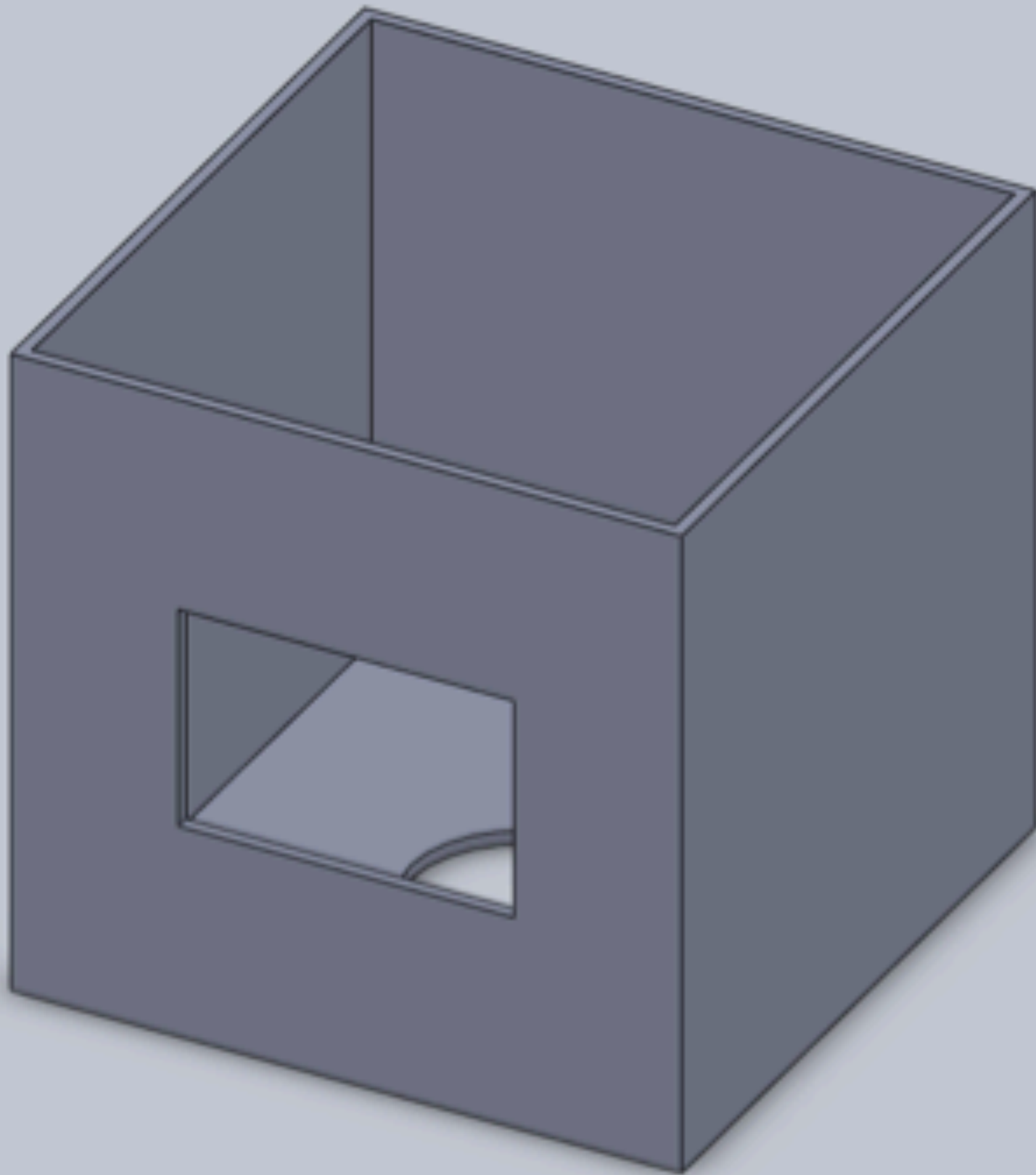
Design Philosophy: Use-Centered Design

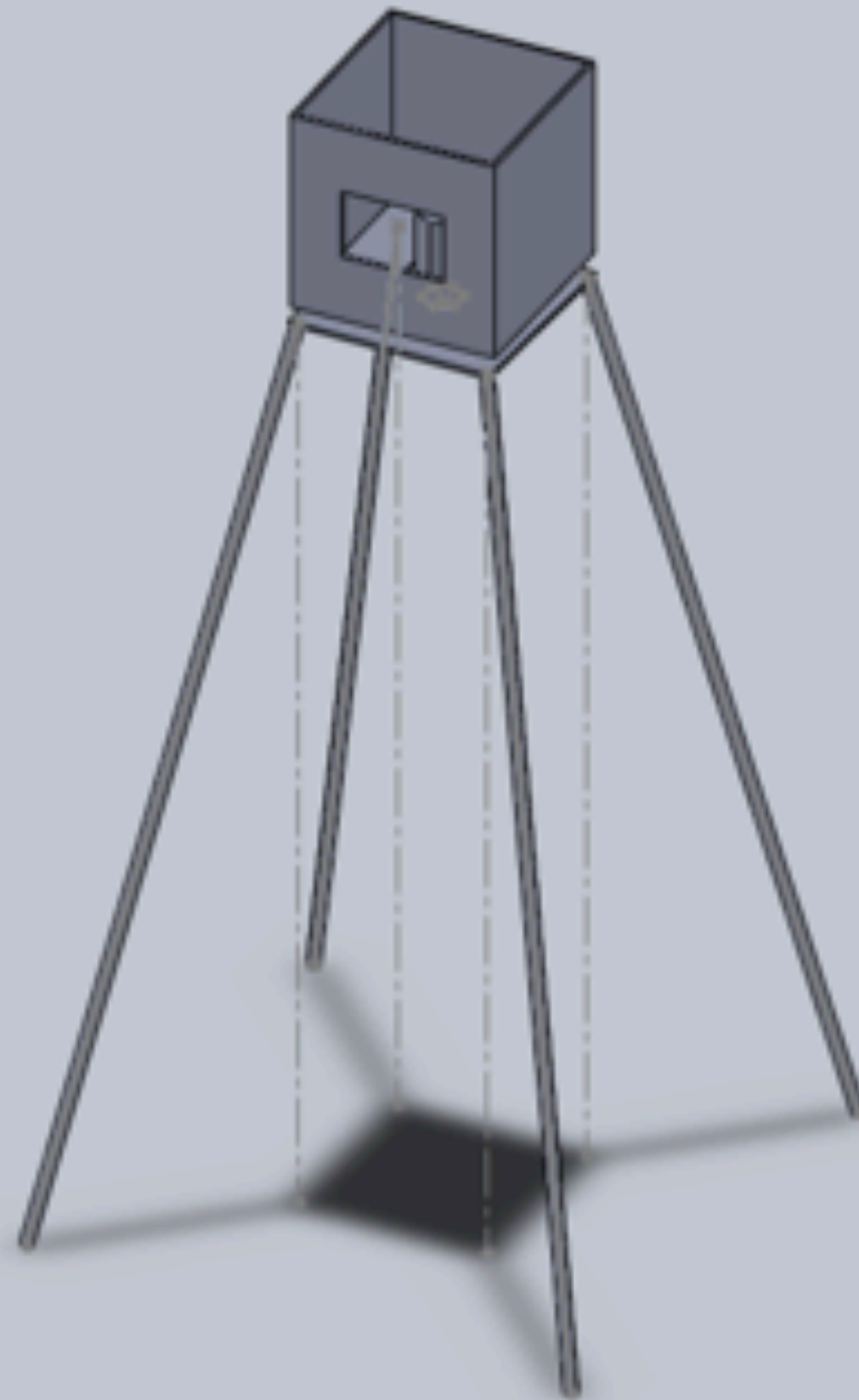
Requirements:

- Protects Camera In 900-1200° C Temps
- Withstand 50 mph Winds
- Less Than 50 lbs.
- 360° Rotation
- 4.5 ft Height
- Internal Cooling No Need For Ice
- Reusable









Electrical Development

John Thomson



Electrical Eng. Goals

Design Philosophy: Simple and Inexpensive (KISS)

Requirements:

- Orient To Fire in ~20 Sec
- Battery:
 - 1 week Standby
 - Continuous 4h
- Maintain Camera Under 50° C
- Turn On When Fire Is 10m Away
- Video Tape IR
- Reuse Costs Under \$100

Parts Selection

- Controller: PI for Angular Position
 - Microcontroller: Atmega 168
 - Software: Arduino Framework
- Heat Sensing: PIR (Thermopiles)
 - Consumable
- Actuator:
 - Quad Encoded DC Motor
- Power: 12v Lithium Battery

Management

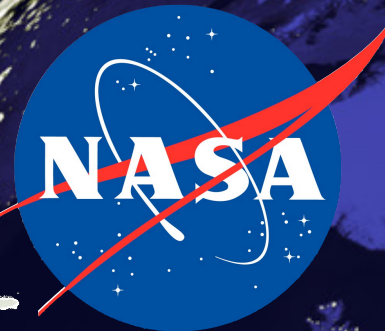
Ramses Alcaide



Cost

- No Budget Constraint
- \$3k Personal Goal
- Full Details Online

UNIVERSITY OF WASHINGTON
School of Forest Resources



Schedule

Week	Goals
1	ID Challenges
2	Mech. Modeling
3	Elec. Modeling
4	Mech. Development
5	Integration/Testing
6	Design Changes
7	Redevelopment
8	Testing

Thermal Camera For Climate Change Prevention

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