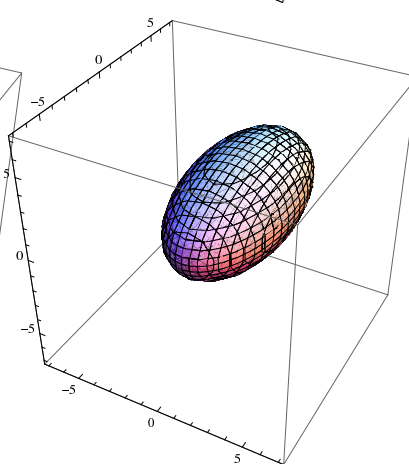
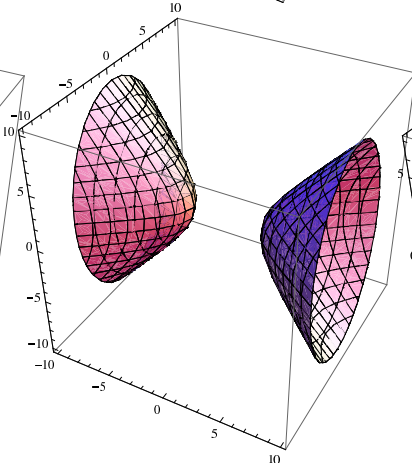
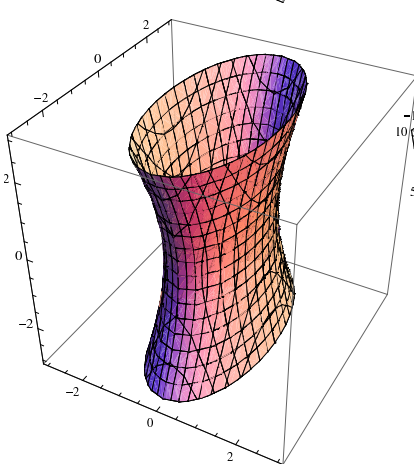
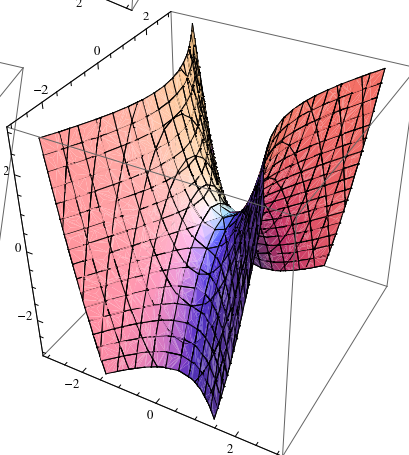
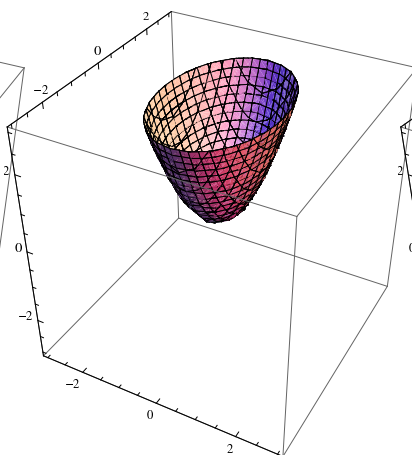
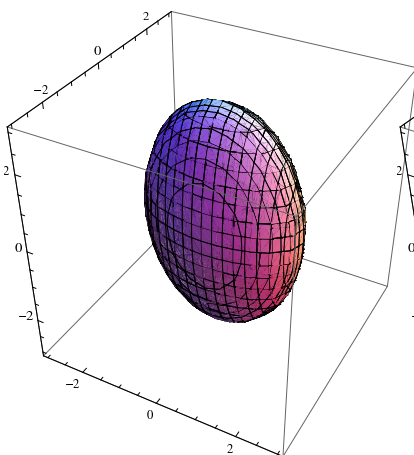
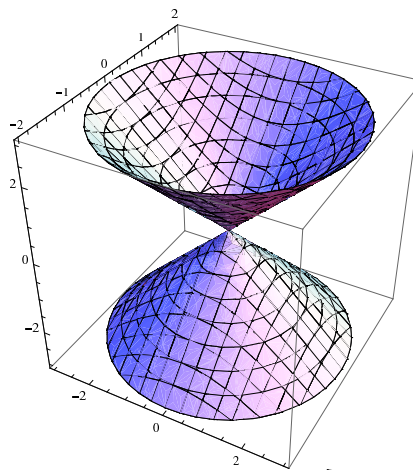


CALCULUS & ANALYTIC GEOMETRY III

Quadratic Equations in 3-D

Match each function to its graph

1. $9x^2 + 36y^2 + 4z^2 = 36$
2. $4x^2 + 9y^2 - 4z^2 = 0$
3. $36x^2 + 9y^2 - 4z^2 = 36$
4. $4x^2 - 9y^2 - 4z^2 = 36$
5. $9x^2 + 4y^2 - 6z = 0$
6. $9x^2 - 4y^2 - 6z = 0$
7. $4x^2 + y^2 + 4z^2 - 4y - 4z + 36 = 0$
8. $4x^2 + y^2 + 4z^2 - 4y - 4z - 36 = 0$



cone • ellipsoid • elliptic paraboloid • hyperbolic paraboloid • hyperboloid of one sheet • hyperboloid of two sheets

 CALCULUS & ANALYTIC GEOMETRY III

Parametric Equations (§10.1) and Vector Functions (§13.1)

Definition. If x and y are given as continuous function

$$x = f(t) \qquad y = g(t)$$

over an interval of t -values, then the set of points $(x, y) = (f(t), g(t))$ defined by these equation is a *parametric curve* (sometimes called a *plane curve*). The equations are *parametric equations* for the curve.

Often we think of parametric curves as describing the movement of a particle in a plane over time.

Examples.

$$\left. \begin{array}{l} x = 2 \cos t \\ y = 3 \sin t \end{array} \right\} 0 \leq t \leq \pi \qquad \left. \begin{array}{l} x = e^t \\ y = \ln t \end{array} \right\} 1 \leq t \leq e$$

Can we find parameterizations of known curves?

the line segment
from $(1, 3)$ to $(5, 1)$

circle $x^2 + y^2 = 1$

Why restrict ourselves to only moving through planes? Why not space? And why not use our nifty vector notation?

Definition. If x , y , and z are given as continuous functions

$$x = f(t) \qquad y = g(t) \qquad z = h(t)$$

over an interval of t -values, then the set of points $(x, y, z) = (f(t), g(t), h(t))$ defined by these equations is a *parametric curve* (sometimes called a *space curve*). The equations are *parametric equations* for the curve.

Examples.

$$\left. \begin{array}{l} x = 2 \cos t \\ y = 3 \sin t \\ z = t \end{array} \right\} 0 \leq t \leq \pi$$

$$\left. \begin{array}{l} x = 5 + t \\ y = 1 + 4t \\ z = 3 - 2t \end{array} \right\} 0 \leq t \leq 1$$

An oval helix

The line in 3-D

$$\mathbf{r}(t) = (5 + t)\mathbf{i} + (1 + 4t)\mathbf{j} + (3 - 2t)\mathbf{k}$$

from §12.5

The *vector function* $\mathbf{r}(t) = \langle f(t), g(t), h(t) \rangle$ is the position vector of the point $P(f(t), g(t), h(t))$ on the space curve C . The tip of the moving vector \mathbf{r} traces out the space curve—provided everything is continuous.

Questions.

1. Do vector functions make sense with our original definition of function as a rule that assigns one output for each input?

2. What should the domain of a vector function be?

State the natural domains for:

$$\mathbf{r}(t) = \langle t^2, t^3, \sqrt{t} \rangle$$

$$\mathbf{r}(t) = \langle \sin^{-1}(t), \ln(t), 1 \rangle$$

3. What should it mean for a vector function to have a limit at a point a ?

Find the limits:

$$\lim_{t \rightarrow 0} \langle t^2, t^3, \frac{\sin t}{t} \rangle$$

$$\lim_{t \rightarrow 0^+} \langle \sin^{-1}(t), \ln(t), 1 \rangle$$

4. What should it mean for a vector function to be continuous at a point a ?

5. Can you see that we are leading to asking calculus questions about vector functions?

Describe the graphs for

$$\mathbf{r}(t) = \langle \cos(4t), t, \sin 4t \rangle$$

$$\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + \sin 5t \mathbf{k}$$