

Durability of Bonded Aircraft Structure

AMTAS 2019

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Outline

Characterizing adhesives

- Experimental data
 - Shear strain in a scarf joint
 - Cyclic Loading
 - Varying frequency
 - ► Varying R ratio
- Viscoelastic-Viscoplastic Model
 - Model introduction
 - 1D model for bulks
 - ▶ 3D model for scarf joints



Scarf Joint

- Scarf joint coupon with strain gauge bonded over adhesive
- Scarf Angle: 10 degrees





Measuring Strain

- Divided each strain by the percentage of the gage covering the adhesive
- Strain Gauge Area: 0.064in x 0.05in
- Adhesive Thickness: 0.008in

$$\begin{array}{c} & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\$$

 $\varepsilon_1 = \varepsilon_1 * a/t$ $\varepsilon_2 = \varepsilon_2 * a \cos(45^\circ)/t$ $\varepsilon_3 = \varepsilon_3 * b/t$

$$\gamma_{xy} = 2\epsilon'_2 - \epsilon'_1 - \epsilon'_3$$

Monotonic Testing

Shear Modulus

	EA9696	FM300-2
Strain Gauge	88200 psi	122000 psi
Bulk Coupon data	88700 psi	129794 psi
Digital Imaging Correlation	87100 psi	





Elastic Region

Failure surfaces Monotonic Testing



FM300-2

EA9696



Cyclic Testing

- Sine Wave
- 10,000 Cycles
- Variables
 - Frequency
 - R Ratio



Stress Input for 3 Hz, 0.1 R, 50% USS

$$R = \frac{\sigma_{min}}{\sigma_{max}}$$



Time

Change in Frequency

• 50% USS

Sine Wave

• 0.1 R

- EA9696
- 10,000 cycles



Change in R Ratio

- Sine Wave 3 Hz
- 10,000 Cycles $R = \frac{\sigma_{min}}{\sigma_{max}}$



Stress Input for 3 Hz, -1 R, 50% USS



Compression Grips

Change in R Ratio

- 20% USS Sine Wave
- 3 Hz



Change in R Ratio

- 50% USS Sine Wave
- 3 Hz



EA9696 50% USS -1 R





Summary

- Thin bond adhesive behaves differently than bulk adhesive
- Strain gages can be used to measure strain over an adhesive bond
- Cyclic Testing
 - Cycle frequency has no effect on strain
 - Positive R ratio responds similar to creep
 - ► Negative R ratio creates considerable strain growth at 50% USS

Nonlinear Viscoelastic-Viscoplastic Model Total Strain:

 $\varepsilon = \varepsilon^{ve} + \varepsilon^{vp}$

Viscoelastic Model (Schapery)

$$\varepsilon^{ve}(t) = g_0 D_0 \sigma^t + g_1 \int_0^t \Delta D^{(\psi^t - \psi^\tau)} \frac{d(g_2 \sigma^\tau)}{d\tau} d\tau$$

$$\psi^{t} = \frac{t}{a}$$
$$\Delta D^{\psi^{t}} = \sum_{n=1}^{N} D_{n} (1 - \exp(-\lambda_{n} \psi^{t}))$$



 g_0, g_1, g_2, a - nonlinear parameters dependent on stress at current time t, σ^t D_0, D_n, λ_n - parameters in Prony series (n=7)

Nonlinear Viscoelastic-Viscoplastic Model

Viscoplastic Model (Perzyna)

$$\dot{\varepsilon}^{\nu p} = \dot{\lambda}m = \eta \langle \phi(f) \rangle \frac{\partial f}{\partial \sigma_{ij}} = \eta \langle \left(\frac{f}{\sigma_y^0}\right)^N \rangle \frac{\partial f}{\partial \sigma_{ij}}$$

- η viscosity parameter
- N constant
- *f* Yield Function

Von Mises Yield criterion + Nonlinear Kinematic Hardening

$$f = \sigma_e - \sigma_y^0 = \sqrt{\frac{3}{2}} (S_{ij} - \alpha'_{ij}) (S_{ij} - \alpha'_{ij}) - \sigma_y^0$$
$$\dot{\alpha}_{ij} = \frac{c}{\sigma_v^0} (\sigma_{ij} - \alpha_{ij}) \dot{\varepsilon}_e^{\nu p} - \kappa \alpha_{ij} \dot{\varepsilon}_e^{\nu p}$$

 α_{ij} - back stress ε_e^{vp} - effective viscoplastic strain



1D Model

• Flowchart



Parameters Calibration



1D Model- Simulated For Bulk Coupons CREEP





3D Model-Algorithm-Stress Update

$$\left(\Delta\sigma_{ij}^{t}\right)^{k+1} = \left(\Delta\sigma_{ij}^{t}\right)^{k} - \left[\left(\frac{\partial R_{ij}^{t}}{\partial\sigma_{kl}^{t}}\right)^{k}\right]^{-1} (R_{kl}^{t})^{k}$$

$$\begin{split} \frac{\partial R_{ij}^{t}}{\partial \sigma_{kl}^{t}} &= \frac{\partial \Delta \varepsilon_{ij}^{vp,t}}{\partial \sigma_{kl}^{t}} + \frac{\partial \Delta \varepsilon_{ij}^{vp,t}}{\partial \sigma_{kl}^{t}} \\ &= \bar{J}^{t} \delta_{ik} \delta_{jl} + \frac{\partial \bar{J}^{t}}{\partial \sigma_{kl}^{t}} \frac{\partial \bar{\sigma}^{t}}{\partial \sigma_{kl}^{t}} \sigma_{jj}^{t} + \frac{1}{3} (\bar{B}^{t} - \bar{J}^{t}) \delta_{kl} \delta_{ij} + \frac{1}{3} \sigma_{mm}^{t} \delta_{ij} \frac{\partial \bar{\sigma}^{t}}{\partial \sigma_{kl}^{t}} \left(\frac{\partial \bar{B}^{t}}{\partial \bar{\sigma}^{t}} - \frac{\partial \bar{J}^{t}}{\partial \bar{\sigma}^{t}} \right) \\ &- \frac{\partial \bar{\sigma}^{t}}{\partial \sigma_{kl}^{t}} \left\{ \frac{1}{2} \frac{\partial g_{l}^{t}}{\partial \bar{\sigma}^{t}} \sum J_{n} \left(e^{-\lambda_{n} \Delta \psi^{t}} q_{ij,n}^{t-\Delta t} - g_{2}^{t-\Delta t} S_{ij}^{t-\Delta t} \frac{1 - e^{-\lambda_{n} \Delta \psi^{t}}}{\lambda_{n} \Delta \psi^{t}} \right) \right. \\ &+ \frac{1}{2} \frac{\partial a^{t}}{\partial \bar{\sigma}^{t}} g_{1}^{t} \sum J_{n} \left[e^{-\lambda_{n} \Delta \psi^{t}} \frac{q_{ij,n}^{t-\Delta t} \lambda_{n} \Delta \psi^{t}}{(a^{t})^{2}} + g_{2}^{t-\Delta t} S_{ij}^{t-\Delta t} \left(\frac{e^{-\lambda_{n} \Delta \psi^{t}}}{a^{t}} - \frac{1 - e^{-\lambda_{n} \Delta \psi^{t}}}{\lambda_{n} \Delta \psi^{t}} \right) \right] \\ &+ \frac{1}{9} \frac{\partial g_{1}^{t}}{\partial \bar{\sigma}^{t}} \sum B_{n} \left(e^{-\lambda_{n} \Delta \psi^{t}} q_{mm,n}^{t-\Delta t} - g_{2}^{t-\Delta t} \sigma_{mm}^{t-\Delta t} \frac{1 - e^{-\lambda_{n} \Delta \psi^{t}}}{\lambda_{n} \Delta \psi^{t}} \right) \delta_{ij} \\ &+ \frac{1}{9} \frac{\partial a^{t}}{\partial \bar{\sigma}^{t}} g_{1}^{t} \sum B_{n} \left[e^{-\lambda_{n} \Delta \psi^{t}} q_{mm,n}^{t-\Delta t} - g_{2}^{t-\Delta t} \sigma_{mm}^{t-\Delta t} \frac{1 - e^{-\lambda_{n} \Delta \psi^{t}}}{\lambda_{n} \Delta \psi^{t}} \right) \delta_{ij} \\ &+ \Delta t \eta \left(\frac{f}{\sigma y_{y}^{0}} \right)^{N} \left(\frac{N}{f} \frac{\partial f}{\partial \sigma_{ij}^{t}} \frac{\partial f}{\partial \sigma_{kl}^{t}} + \frac{\partial^{2} f}{\partial \sigma_{kl}^{t}} \partial \sigma_{kl}^{t} \right) \end{split}$$

3D Model- Simulated For Bulk Coupons



Time (s)

3D Model- Simulated For Scarf Joints Ratcheting, R=0.1, 50% USS, EA9696





	Model (strain unit: με)			Experiment(strain unit: με)		
	Cycles	Permanent Strain	Cycles	Estimated Permanent Strain	Cycles	Permanent Strain
0.5 Hz	z 300	63	10 K	2100	10 K	2000
5 Hz		28		933		1300

3D Model- Simulated For Scarf Joints Ratcheting, 3 Hz, R=-1, 50% USS, EA9696



Conclusion

- 1D model can predict the ratcheting behavior of bulk coupons with parameters from creep tests.
- 3D model can predict the ratcheting behavior (0.1R) of scarf joints with the recalibrated parameters.
- 3D model can not yet describe the hysteresis for scarf joints when R=-1.

Future Work

- Simulation of bonded joints under shear (-Dec 2020):
- > Parameters Recalibration, Model Modification