

Computing Spectra of Linear Operators Using Finite Differences

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Introduction: Spectral Stability

Consider the nonlinear PDE evolution

$$\dot{u} = N(x, u, u_x, u_{xx}, \dots)$$

Equilibrium solution

$$N(x, U, U_x, U_{xx}, \dots) = 0$$

Linear stability

$$u(x, t) = U(x) + \overset{\text{perturbation}}{\epsilon v(x, t)}$$

Associated Eigenvalue Problem

Separation of variables

$$v(x, t) = w(x)e^{\lambda t}$$

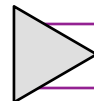
Eigenvalue problem $\mathcal{L}[U(x)] = \frac{\partial N}{\partial U} + \frac{\partial N}{\partial U_x} \partial_x + \frac{\partial N}{\partial U_{xx}} \partial_x^2 + \dots$

$$\mathcal{L}[U(x)]w(x) = \lambda w(x)$$

Linear stability

$\operatorname{Re}(\lambda) \leq 0$ **spectrally stable**

$\operatorname{Re}(\lambda) > 0$ **spectrally unstable**



Finite Differences and Taylor Series

Taylor expand

$$f(t + \Delta t) = f(t) + \Delta t \frac{df(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2 f(t)}{dt^2} + \frac{\Delta t^3}{3!} \frac{d^3 f(c_1)}{dt^3}$$

$$f(t - \Delta t) = f(t) - \Delta t \frac{df(t)}{dt} + \frac{\Delta t^2}{2!} \frac{d^2 f(t)}{dt^2} - \frac{\Delta t^3}{3!} \frac{d^3 f(c_2)}{dt^3}$$

Add

$$\frac{df(t)}{dt} = \underbrace{\frac{f(t + \Delta t) - f(t - \Delta t)}{2\Delta t}}_{\text{approximation}} - \underbrace{\frac{\Delta t^2}{6} \frac{d^3 f(c)}{dt^3}}_{\text{error}}$$

slope formula with error

Higher-Order Accuracy

Taylor expand again

$$f(t+\Delta t) - f(t-\Delta t) = 2\Delta t \frac{df(t)}{dt} + \frac{2\Delta t^3}{3!} \frac{d^3 f(t)}{dt^3} + \frac{\Delta t^5}{5!} \left(\frac{d^5 f(c_1)}{dt^5} + \frac{d^5 f(c_2)}{dt^5} \right)$$

$$f(t+2\Delta t) - f(t-2\Delta t) = 4\Delta t \frac{df(t)}{dt} + \frac{16\Delta t^3}{3!} \frac{d^3 f(t)}{dt^3} + \frac{32\Delta t^5}{5!} \left(\frac{d^5 f(c_3)}{dt^5} + \frac{d^5 f(c_4)}{dt^5} \right)$$

8 x (first) and subtract

	approximation		error
$\frac{df(t)}{dt} = \frac{-f(t+2\Delta t) + 8f(t+\Delta t) - 8f(t-\Delta t) + f(t-2\Delta t)}{12\Delta t} + \frac{\Delta t^4}{30} f^{(5)}(c)$			

slope formula with improved error

Finite Difference Tables

$O(\Delta t^2)$ center-difference schemes

$$f'(t) = [f(t + \Delta t) - f(t - \Delta t)]/2\Delta t$$

$$f''(t) = [f(t + \Delta t) - 2f(t) + f(t - \Delta t)]/\Delta t^2$$

$$f'''(t) = [f(t + 2\Delta t) - 2f(t + \Delta t) + 2f(t - \Delta t) - f(t - 2\Delta t)]/2\Delta t^3$$

$$f''''(t) = [f(t + 2\Delta t) - 4f(t + \Delta t) + 6f(t) - 4f(t - \Delta t) + f(t - 2\Delta t)]/\Delta t^4$$

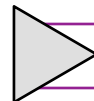
$O(\Delta t^4)$ center-difference schemes

$$f'(t) = [-f(t + 2\Delta t) + 8f(t + \Delta t) - 8f(t - \Delta t) + f(t - 2\Delta t)]/12\Delta t$$

$$f''(t) = [-f(t + 2\Delta t) + 16f(t + \Delta t) - 30f(t) + 16f(t - \Delta t) - f(t - 2\Delta t)]/12\Delta t^2$$

$$f'''(t) = [-f(t + 3\Delta t) + 8f(t + 2\Delta t) - 13f(t + \Delta t) + 13f(t - \Delta t) - 8f(t - 2\Delta t) + f(t - 3\Delta t)]/8\Delta t^3$$

$$f''''(t) = [-f(t + 3\Delta t) + 12f(t + 2\Delta t) - 39f(t + \Delta t) + 56f(t) - 39f(t - \Delta t) + 12f(t - 2\Delta t) - f(t - 3\Delta t)]/6\Delta t^4$$



neighboring points determine accuracy

Forward and Backward Differences

$O(\Delta t^2)$ forward- and backward-difference schemes

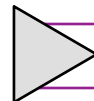
$$f'(t) = [-3f(t) + 4f(t + \Delta t) - f(t + 2\Delta t)]/2\Delta t$$

$$f'(t) = [3f(t) - 4f(t - \Delta t) + f(t - 2\Delta t)]/2\Delta t$$

$$f''(t) = [2f(t) - 5f(t + \Delta t) + 4f(t + 2\Delta t) - f(t + 3\Delta t)]/\Delta t^3$$

$$f''(t) = [2f(t) - 5f(t - \Delta t) + 4f(t - 2\Delta t) - f(t - 3\Delta t)]/\Delta t^3$$

Required for incorporating boundary conditions



asymmetric neighboring points

Numerical Round-Off

Consider the error in approximating the first derivative

$$\frac{dy}{dt} = \frac{-f(t + 2\Delta t) + 8f(t + \Delta t) - 8f(t - \Delta t) + f(t - 2\Delta t)}{12\Delta t} + E(y(t), \Delta t)$$

The error includes round-off and truncation

$$E = \frac{\text{round-off}}{-e(t + 2\Delta t) + 8e(t + \Delta t) - 8e(t - \Delta t) + e(t - 2\Delta t)}{12\Delta t} + \frac{\text{truncation}}{\frac{\Delta t^4}{30} \frac{d^5 y(c)}{dt^5}}$$

Assume round-off $|e(t + \Delta t)| \leq e_r$ and $M = \max \{|y''''''(c)|\}$

$$|E| = \frac{3e_r}{2\Delta t} + \frac{\Delta t^4 M}{30} \quad \text{minimum at} \quad \Delta t = \left(\frac{45e_r}{4M} \right)^{1/5}$$

round-off error dominates below $\Delta t \approx 10^{-3}$

Boundary Conditions: Pinned $u(0) = u(l) = 0$

$$\frac{\partial^2 u}{\partial x^2} \rightarrow \frac{1}{\Delta x^2} \begin{bmatrix} -2 & 1 & 0 & \cdots & 0 & 0 \\ 1 & -2 & 1 & 0 & \cdots & 0 \\ 0 & \ddots & \ddots & \ddots & & \\ \vdots & & & & & \\ & & & & & 0 \\ \vdots & \cdots & 0 & 1 & -2 & 1 \\ 0 & 0 & \cdots & 0 & 1 & -2 \end{bmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix}$$

pinned boundaries $u_0 = u_{n+1} = 0$

▶ tri-diagonal matrix structure

Boundary Conditions: Periodic $u(0) = u(l)$

$$\frac{\partial^2 u}{\partial x^2} \rightarrow \frac{1}{\Delta x^2} \begin{bmatrix} -2 & 1 & 0 & \cdots & 0 & 1 \\ 1 & -2 & 1 & 0 & \cdots & 0 \\ 0 & \ddots & \ddots & \ddots & & \\ \vdots & & & & & \vdots \\ & & & & 0 & \\ \vdots & \cdots & 0 & 1 & -2 & 1 \\ 1 & 0 & \cdots & 0 & 1 & -2 \end{bmatrix} \begin{pmatrix} u_0 \\ u_1 \\ \vdots \\ u_n \end{pmatrix}$$

periodic boundaries

$$u_0 = u_{n+1}$$

▶ tri-diagonal matrix structure with corners

Boundary Conditions: No Flux $\frac{\partial u(0)}{\partial x} = \frac{\partial u(l)}{\partial x} = 0$

no flux condition

$$\frac{\partial u(0)}{\partial x} = \frac{-3u_0 + 4u_1 - u_2}{2\Delta x} = 0 \rightarrow u_0 = \frac{4}{3}u_1 - \frac{1}{3}u_2$$

$$\frac{\partial^2 u}{\partial x^2} \rightarrow \frac{1}{\Delta x^2} \begin{bmatrix} -2/3 & 2/3 & 0 & \dots & 0 & 0 \\ 1 & -2 & 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \ddots & & \\ \vdots & & & & & \vdots \\ & & & & & 0 \\ \vdots & \dots & 0 & 1 & -2 & 1 \\ 0 & 0 & \dots & 0 & 2/3 & -2/3 \end{bmatrix}$$

no longer symmetry matrix

General Boundaries

General (Sturm-Liouville) boundary conditions

$$\alpha_1 u(0) + \beta_1 \frac{\partial u(0)}{\partial x} = \gamma_1$$

$$\alpha_2 u(l) + \beta_2 \frac{\partial u(l)}{\partial x} = \gamma_2$$

Difficult to incorporate into matrix structure

- shooting methods
- relaxation methods

no longer symmetry matrix

Algorithm

- choose domain length and discretization size
- construct linear operator
- implement boundary conditions
- use eigenvalue/eigenvector solver: $O(N^3)$
(or shooting/relaxation methods)
- construct eigenfunctions

Example: Mathieu Equation

Classic Example

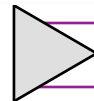
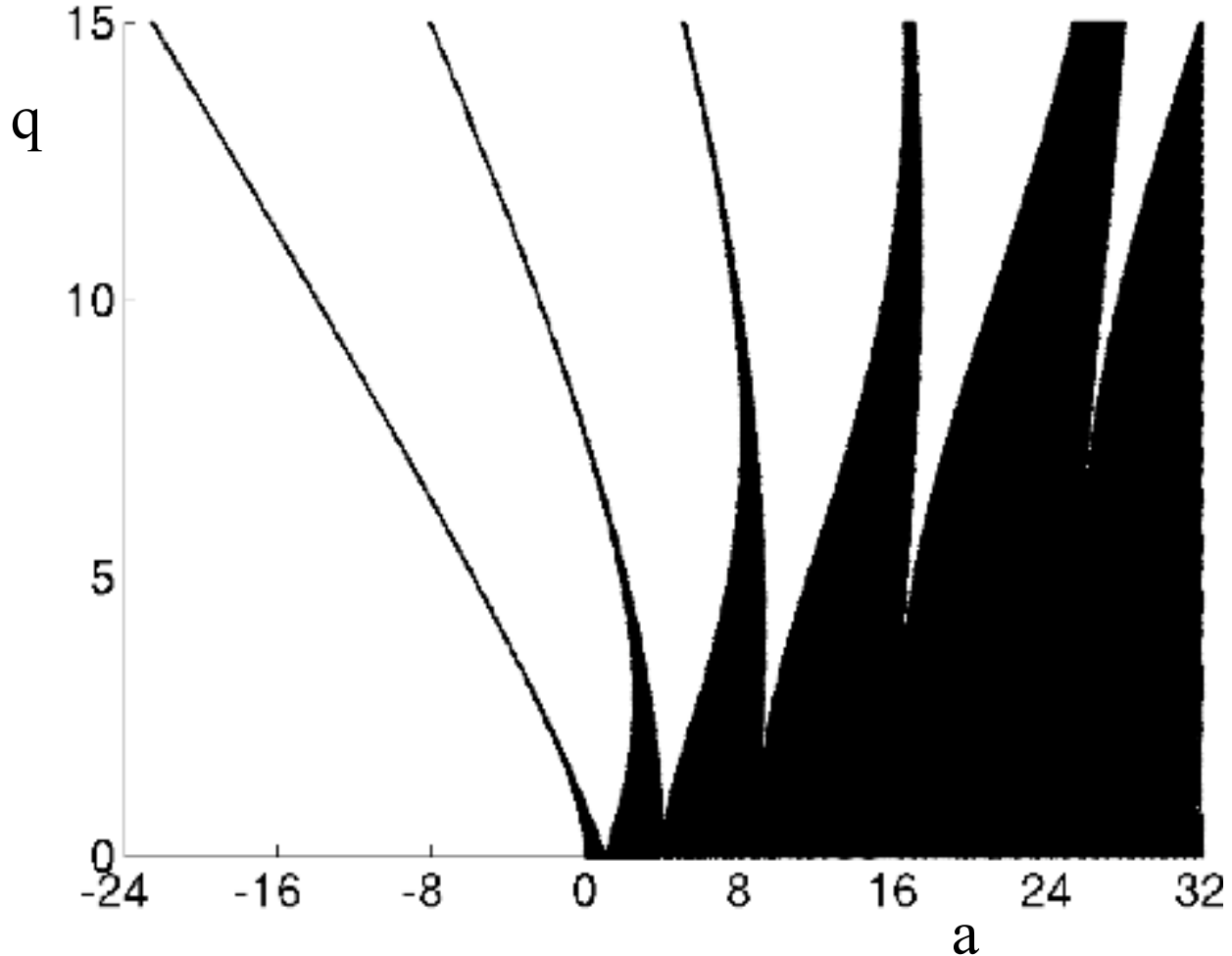
$$y'' + (a - 2q \cos(2x))y = 0 \iff -y'' + 2q \cos(2x)y = ay$$

Operator $-\partial_x^2 + 2q \cos(2x)$ is self-adjoint (real spectrum)

$$-\frac{1}{\Delta x^2} \begin{bmatrix} -2 & 1 & 0 & \dots & 0 & 1 \\ 1 & -2 & 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \ddots & & \\ \vdots & & & & \vdots & \\ & & & & 0 & \\ \vdots & \dots & 0 & 1 & -2 & 1 \\ 1 & 0 & \dots & 0 & 1 & -2 \end{bmatrix} + 2q \begin{bmatrix} \cos(2x_0) & & 0 & 0 & \dots & & 0 & 0 \\ & 0 & \cos(2x_1) & 0 & 0 & & \dots & 0 \\ & & & \ddots & \ddots & \ddots & & \\ & & & 0 & & & & \\ & & & \vdots & & & & \vdots \\ & & & & & & & 0 \\ & & & \vdots & \dots & 0 & 0 & \cos(2x_{n-1}) & 0 \\ & & & 0 & 0 & \dots & 0 & 0 & \cos(2x_n) \end{bmatrix}$$



Spectrum for Mathieu Equation



a is eigenvalue

Computing the Ground State

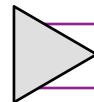
Convergence study and CPU time ($q=2$)

	Accuracy: 10^{-3}		Accuracy: 10^{-6}		Accuracy: 10^{-9}	
	Matrix size	CPU time	Matrix size	CPU time	Matrix size	CPU time
FDM2	239	0.43 sec	8000	1 hour	N/A	-
FDM4	52	0.01 sec	293	0.77 sec		

beyond Matlab7's ability

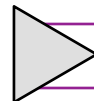
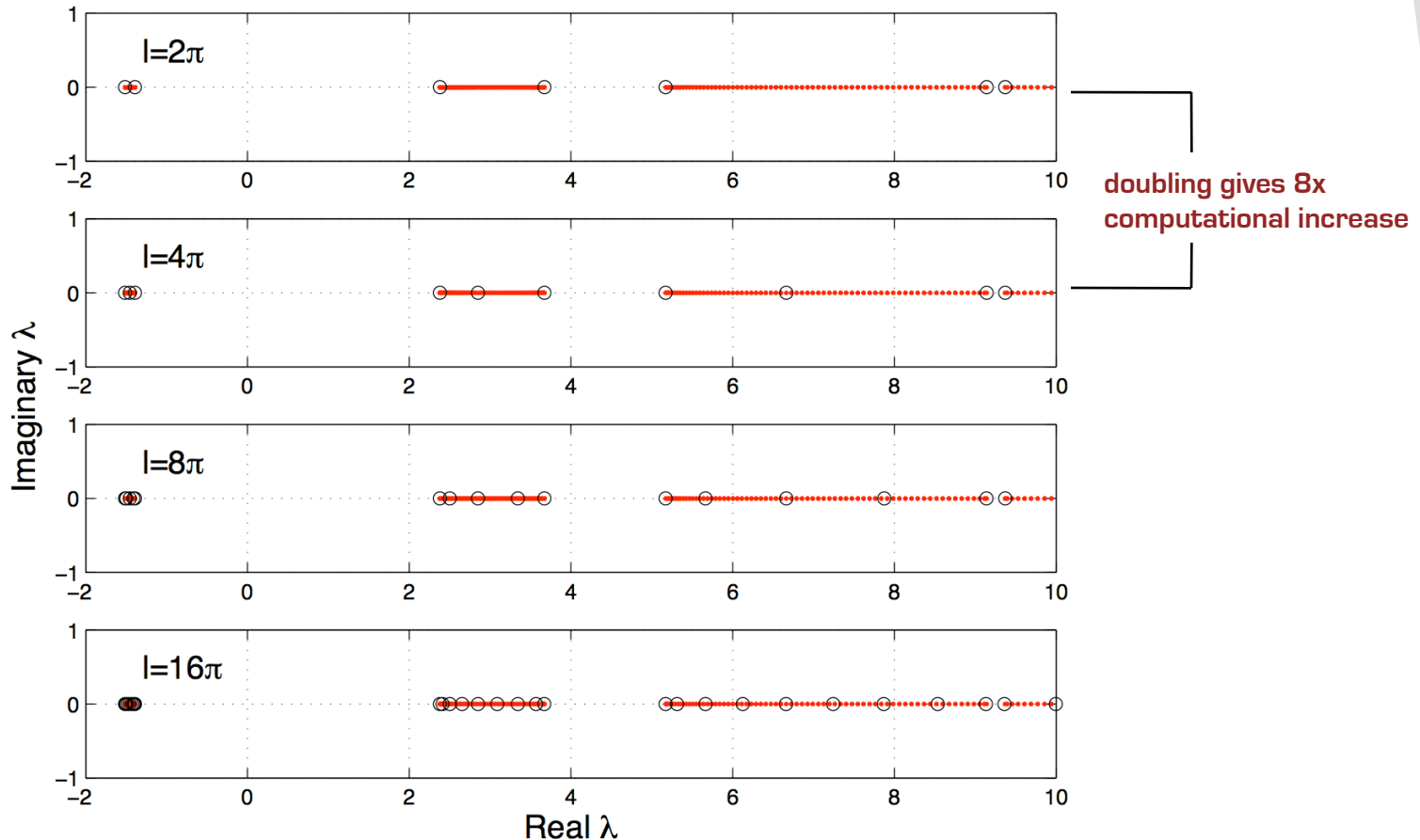
What about band-gap structure

- increase domain length
- Floquet theory



Calculating the Bands: Domain Length

Increase the domain length ($q=2$)



traditional way: very costly for recovering bands

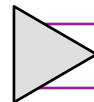
Calculating the Bands: Floquet Theory

Make use of Floquet (Bloch) theory

$$y(x + L) = e^{i\mu L} y(x) \quad \text{larger period solutions}$$

with Floquet (characteristic) exponents $\mu \in [0, 2\pi/L)$

- **keep fixed domain**
- **discretize** $\mu_k = 2(k - 1)/P, k = 1, \dots, D$
- **solve D $O(N^3)$ equations**



Implementing Floquet Theory

Floquet theory modifies matrix corners

$$D_2^{(4,h)} = \frac{1}{12h^2} \begin{pmatrix} -30 & 16 & -1 & 0 & \dots & \dots & 0 & -e^{-i\theta} & 16e^{-i\theta} \\ 16 & -30 & 16 & -1 & 0 & \dots & \dots & 0 & -e^{-i\theta} \\ -1 & 16 & -30 & 16 & -1 & 0 & \dots & \dots & 0 \\ 0 & -1 & 16 & -30 & 16 & -1 & 0 & \dots & \dots \\ & & & \ddots & \ddots & \ddots & & & \\ \dots & \dots & 0 & -1 & 16 & -30 & 16 & -1 & 0 \\ 0 & \dots & \dots & 0 & -1 & 16 & -30 & 16 & -1 \\ -e^{i\theta} & 0 & \dots & \dots & 0 & -1 & 16 & -30 & 16 \\ 16e^{i\theta} & -e^{i\theta} & 0 & \dots & \dots & 0 & -1 & 16 & 30 \end{pmatrix}$$

with Floquet slices $\theta \in [0, 2\pi)$

Floquet Theory vs. Domain Length

Compare methods for computing band ($q=2$)

band density

$$\delta_B = \frac{\max_{a_k, a_{k+1} \in \sigma_B} (a_{k+1} - a_k)}{|\sigma_B|}$$

	$\delta_2 = 0.25$		$\delta_2 = 0.025$		$\delta_2 = 0.0025$	
	D	CPU time	D	CPU time	D	CPU time
FDM4 matrix size=1172	1	9 min	N/A	-	N/A	-
FDM4, $D > 1$	4	8 sec	32	1 min	310	10 min

beyond Matlab7's ability

Use Floquet Theory!



Example: Periodic NLS

Consider the system

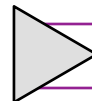
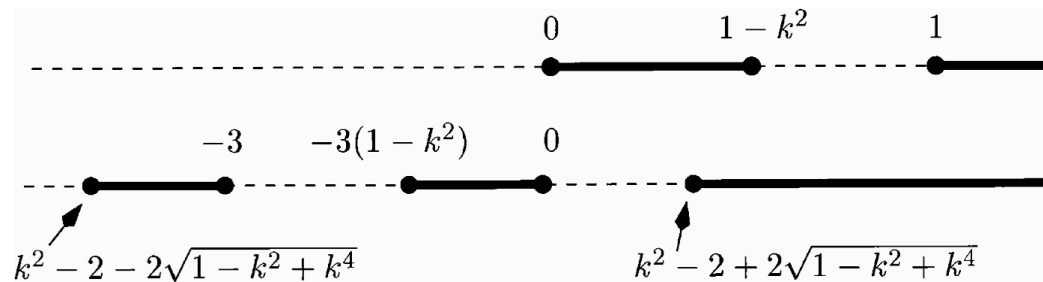
$$\begin{pmatrix} 0 & L_-(k) \\ -L_+(k) & 0 \end{pmatrix} \begin{pmatrix} U \\ V \end{pmatrix} = \lambda \begin{pmatrix} U \\ V \end{pmatrix}$$

with

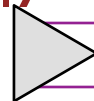
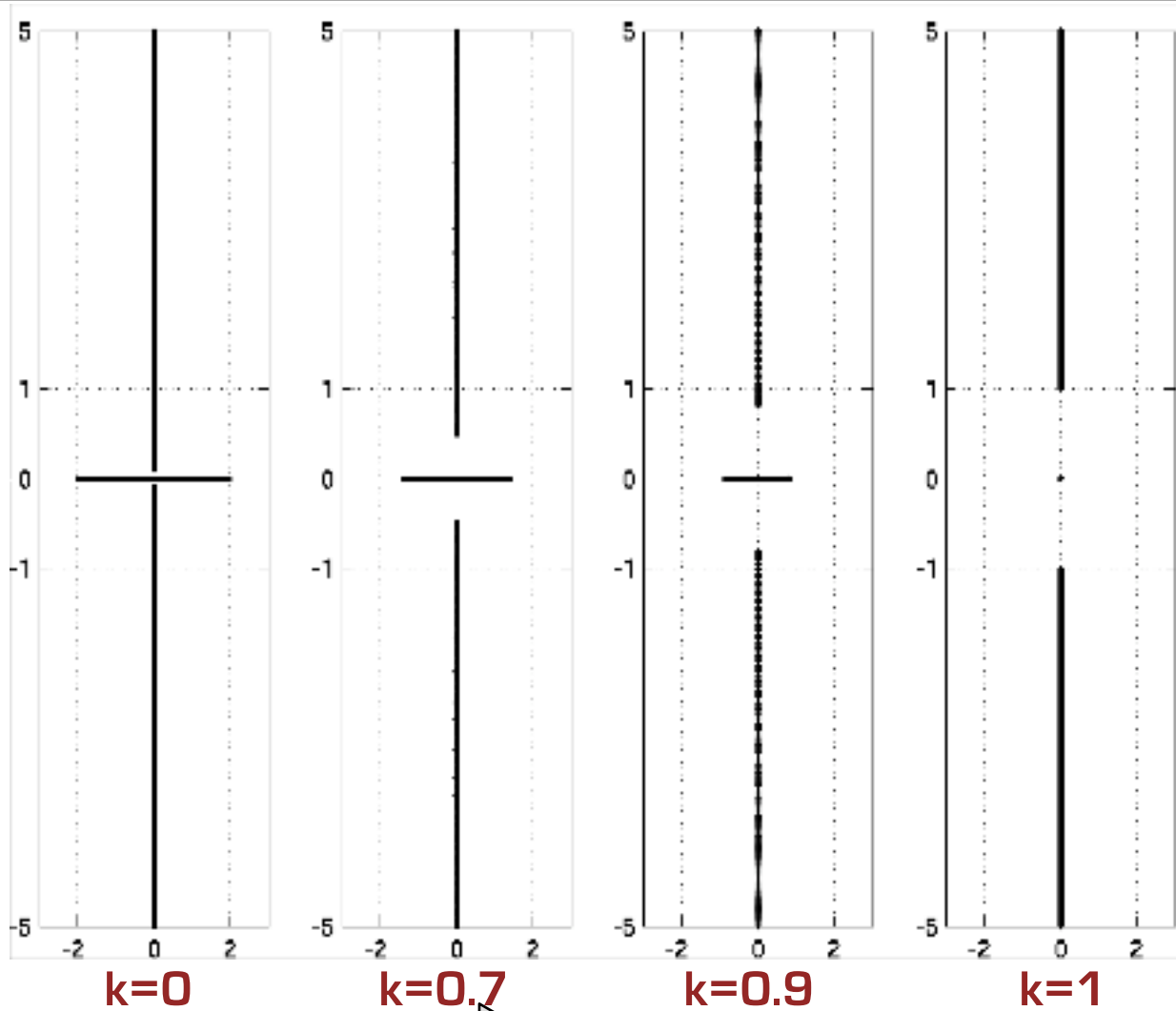
$$L_-(k)u = -u'' + (2k^2 \operatorname{sn}^2(x, k) - k^2)u$$

$$L_+(k)v = -v'' + (6k^2 \operatorname{sn}^2(x, k) - 4 - k^2)v$$

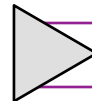
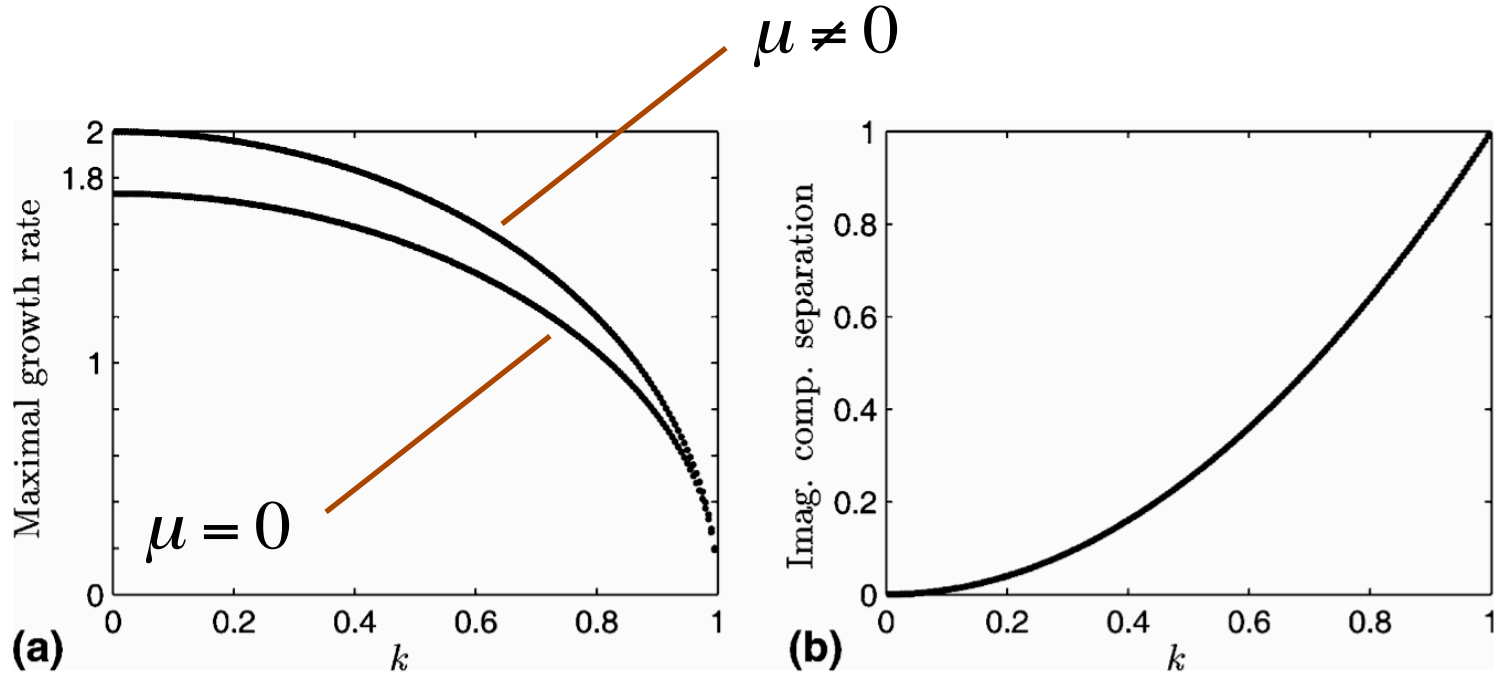
and Jacobi sine function $\operatorname{sn}(x, k)$



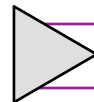
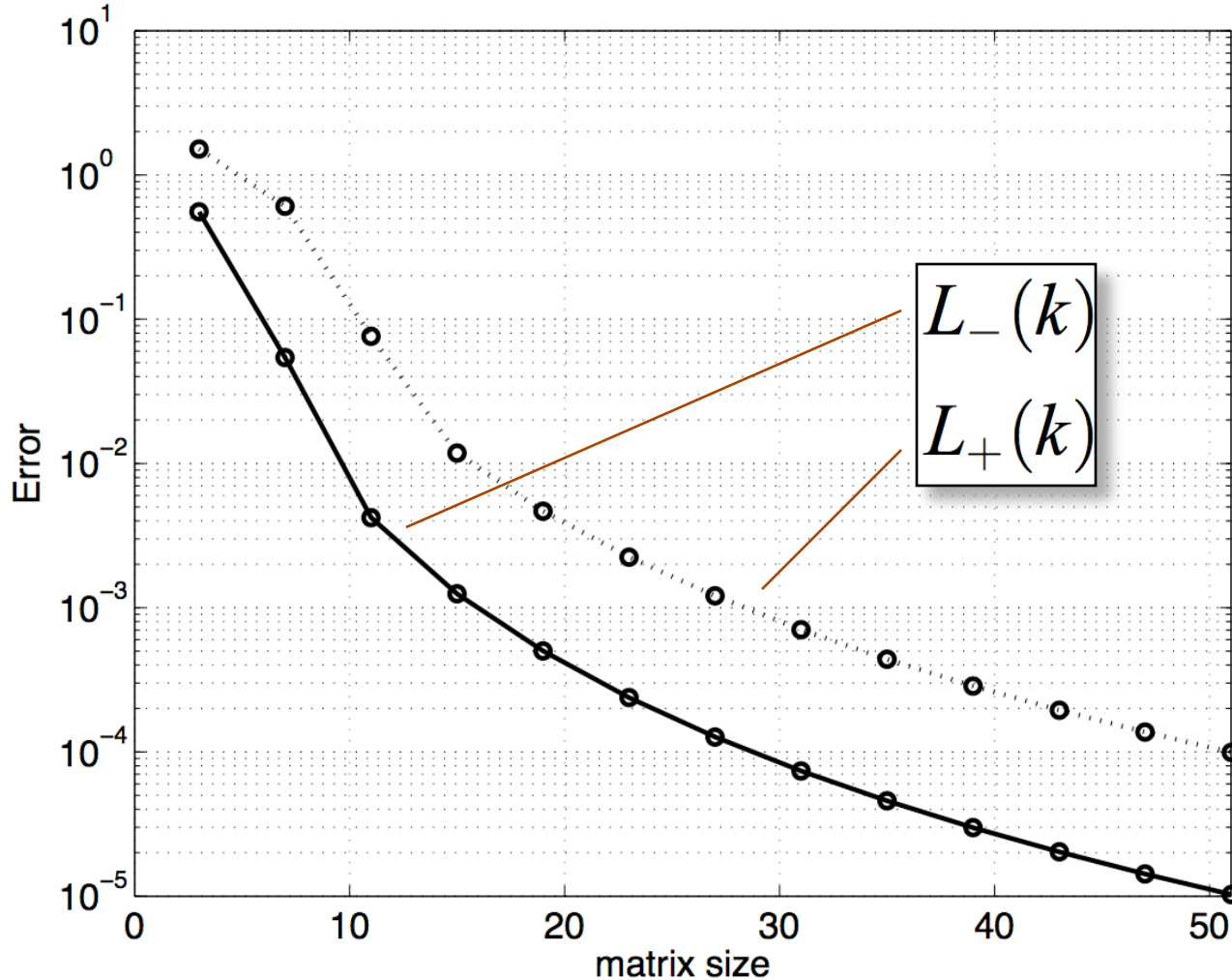
Spectrum of Periodic NLS



Importance of Floquet Slicing



Accuracy and Convergence



Example: 2D Mathieu Equation

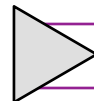
Consider

$$-\frac{1}{2}(\psi_{xx} + \psi_{yy}) + f(x, y)\psi = \lambda\psi$$

with

$$f(x, y) = A \sin^2 x \sin^2 y$$

Operation Count: $O((N^2)^3) = O(N^6)$



Laplacian in 2D

Consider $\nabla^2 \psi = \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2}$

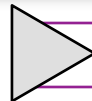
Discretize:

$$\frac{\psi(x + \Delta x, y, t) - 2\psi(x, y, t) + \psi(x - \Delta x, y, t)}{\Delta x^2} + \frac{\psi(x, y + \Delta y, t) - 2\psi(x, y, t) + \psi(x, y - \Delta y, t)}{\Delta y^2}$$

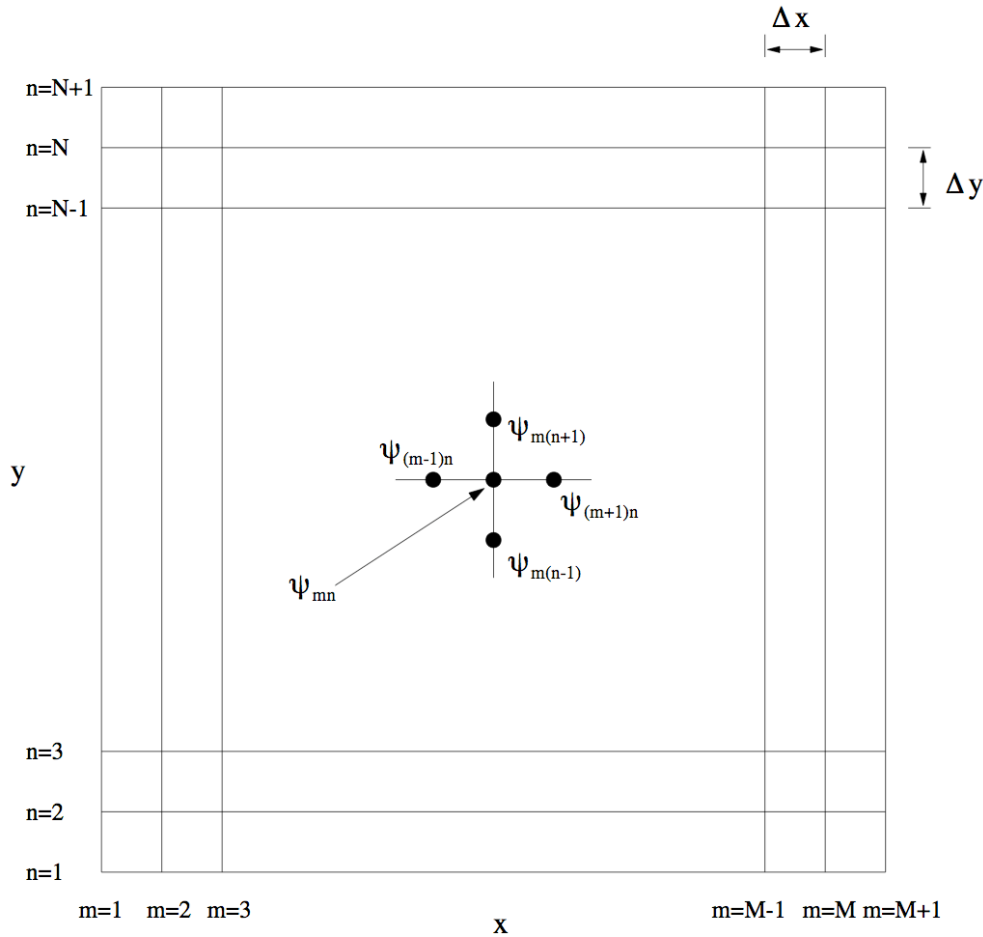
Let $\psi_{mn} = \psi(x_m, y_n)$

$$-4\psi_{mn} + \psi_{(m-1)n} + \psi_{(m+1)n} + \psi_{m(n-1)} + \psi_{m(n+1)}$$

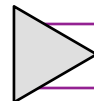
must stack 2D data: periodic boundaries add structure



Laplacian in 2D



$$\psi = \begin{pmatrix} \psi_{11} \\ \psi_{12} \\ \vdots \\ \psi_{1(M+1)} \\ \psi_{21} \\ \psi_{22} \\ \vdots \\ \psi_{(N+1)M} \\ \psi_{(N+1)(M+1)} \end{pmatrix}$$



Laplacian in 2D

$$\begin{bmatrix}
 -4 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\
 0 & 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\
 1 & 0 & 1 & -4 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
 1 & 0 & 0 & 0 & -4 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 1 & 0 & 1 & -4 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & -4 & 1 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 & 0 & 1 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & -4 & 0 & 0 & 0 & 0 & 1 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & -4 & 1 & 0 & 0 & 1 \\
 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 & 0 \\
 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & -4 & 1 & 0 \\
 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 1 & 0 & -4
 \end{bmatrix}$$

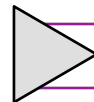
$$nx=ny=4$$

```

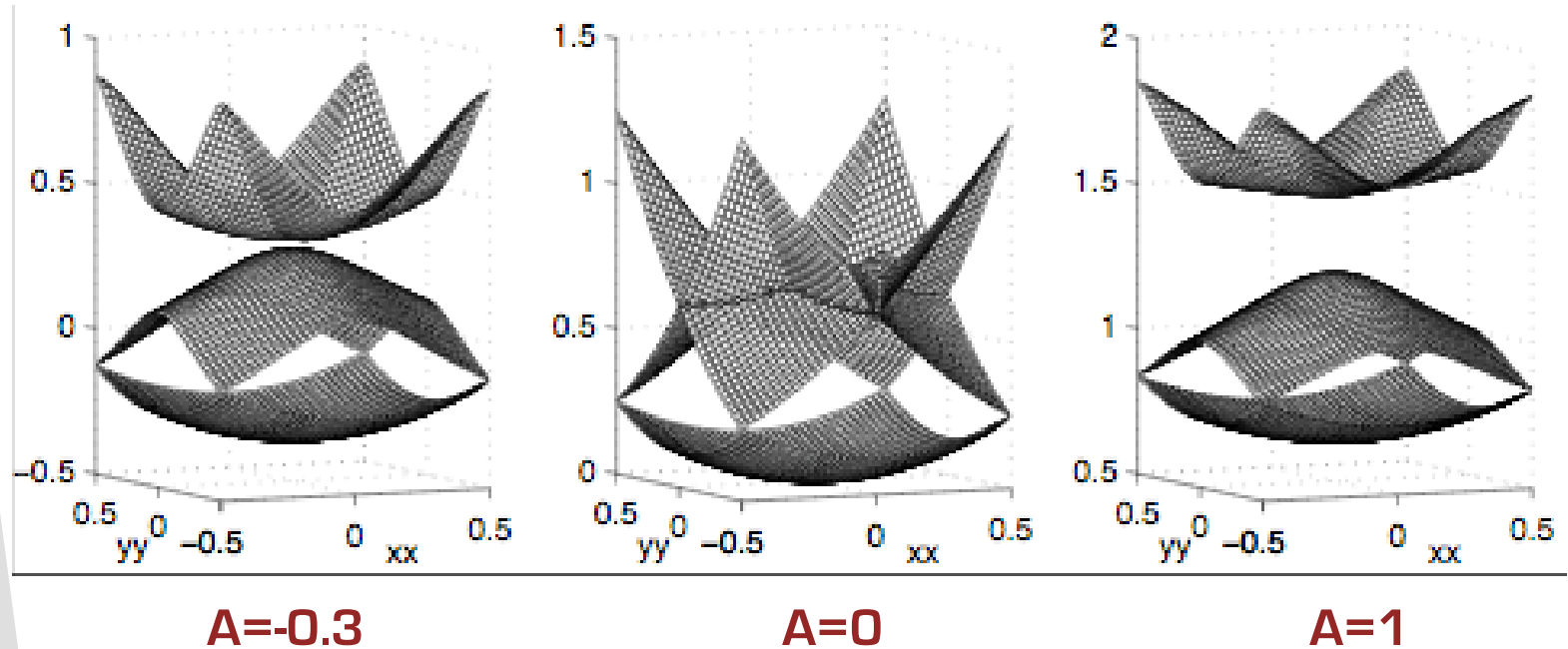
I=eye(n); % idendity matrix of size nXn
B=kron(I,A)+kron(A,I); % 2-D differentiation matrix

```

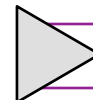
Matlab easily builds 2D Laplacian



Band Gap Structure

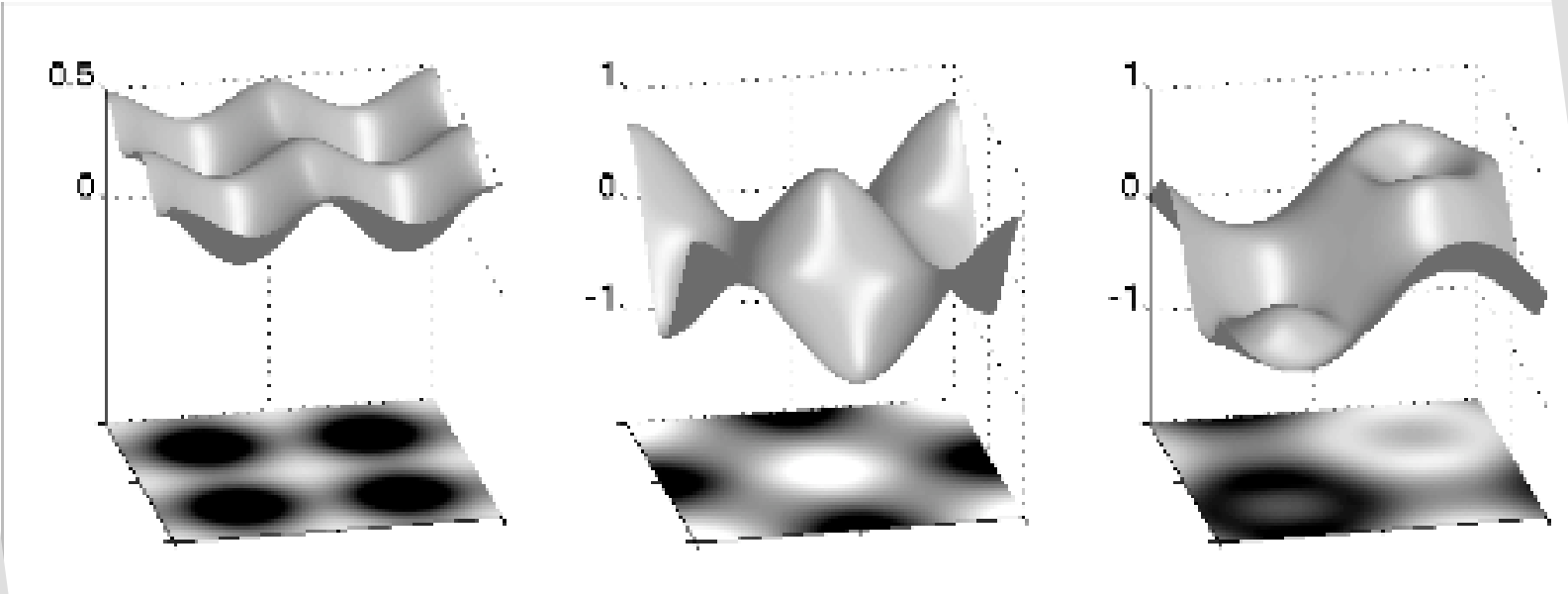


First three band-gap structures

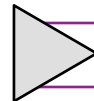


Quasi-momentum representation

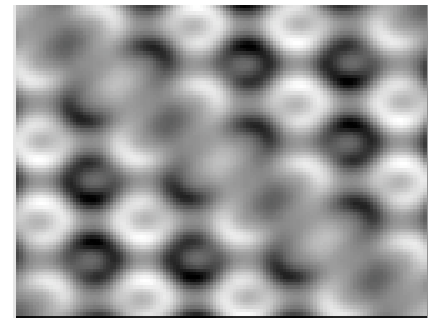
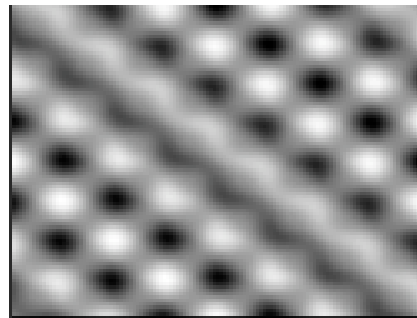
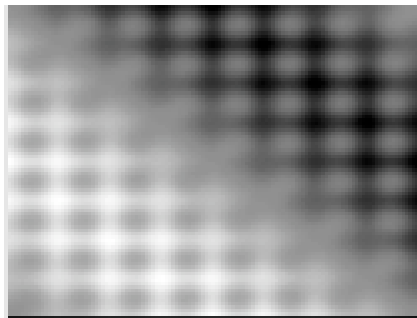
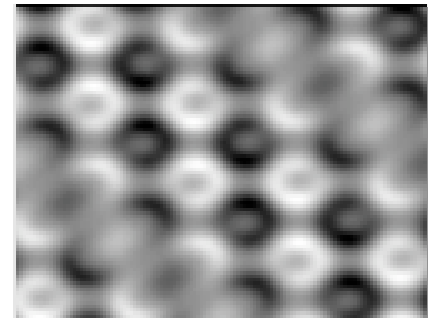
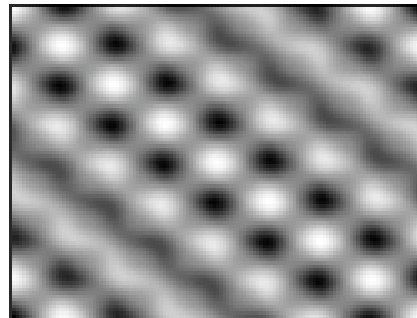
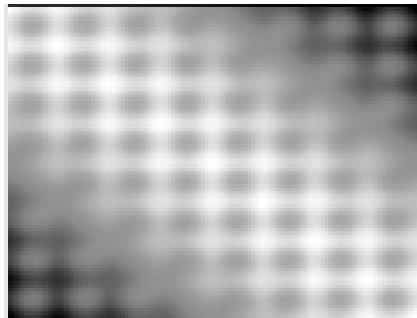
2D Dominant Eigenfunctions



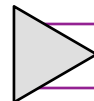
First three eigenfunctions for $\mu_x = \mu_y = 0$



2D Eigenfunctions



First three eigenfunctions for $\mu_x = \mu_y = 1/4$



Summary and Conclusions

- **simple, simple, simple**
- **boundary conditions at edge of matrices**
- **eigenvalue solvers make use of sparse structure**
- **Floquet theory for resolution of bands**
- **costly/impractical for 2D-3D problems**